

# Evaluating LLMs on Scientific Tasks

*multimodal, long-context, coding, agentic*

Subhashini Venugopalan  
Jun 2025

# Subhashini Venugopalan

## Univ. Texas at Austin

Image Captioning,  
Video Description  
2012-2017



## Healthcare

Disease Biomarkers:  
Diabetic Retinopathy,  
Pathology



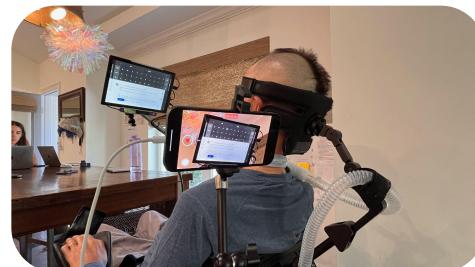
## Bio, Science

Microscopy Imaging,  
Model Explanation for  
validation & discovery



## Now

LLM science evals,  
reasoning, coding



## Physics Nobel scooped by machine-learning pioneers

John Hopfield and Geoffrey Hinton pioneered computational methods that enabled the development of neural networks.

By Elizabeth Gibney & Denise Castelhano

[Twitter](#) [Facebook](#)



## Chemistry Nobel goes to developers of AlphaFold AI that predicts protein structures

This year's prize celebrates computational tools that have transformed biology and have the potential to revolutionize drug discovery.

By Ewen Callanay

[Twitter](#) [Facebook](#) [Email](#)



David Baker, Demis Hassabis, and John Jumper (left to right) won the chemistry Nobel for developing computational tools that predict and design protein structures. Credit: BBA Foundation

For the first time – and probably not the last – a scientific breakthrough enabled by artificial intelligence (AI) has been recognized with a Nobel prize. The 2024 chemistry Nobel was awarded to John Jumper and Demis Hassabis at Google DeepMind in London, for developing a game-changing AI tool for predicting protein structures called AlphaFold, and David Baker, at the University of Washington in Seattle, for his work on computational protein design, which has been bolstered by AI in the past few years.

“For the first time – and probably not the last – a scientific breakthrough enabled by artificial intelligence (AI) has been recognized with a Nobel prize.”

# Evolution of Science + AI

nature



Can AI review the scientific literature – and figure out what it all means?

NEWS FEATURE | 13



Think agentic.

Agents can enable much more right now – in the multimodal space especially with the right safeguards.

Google

## How AI-powered science search engines can speed up your research

Artificial intelligence tools offer a variety of approaches to help scientists to sift through the literature – how can researchers use them responsibly?

By Helena Kudrjaber

[Twitter](#) [Facebook](#) [Email](#)



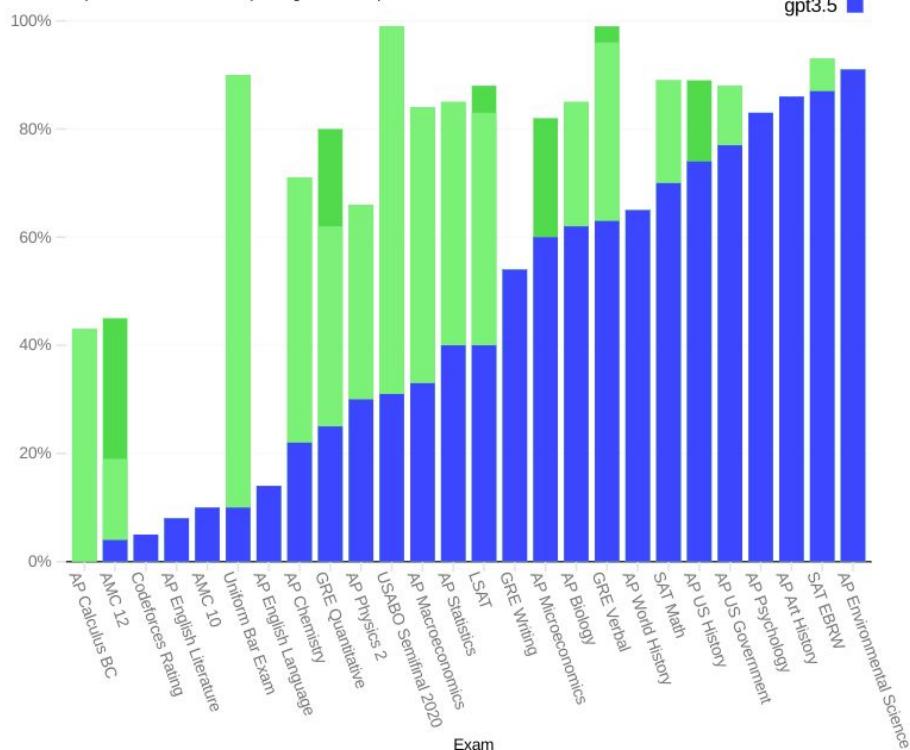
# Agenda

- 01 Overview
- 02 LLM Evals: multimodal
- 03 Long-context retrieval and reasoning evals
- 04 Tool-use simulation software code
- 05 Multimodal Accessibility Applications

# LLM evals testing knowledge

### Exam results (ordered by GPT-3.5 performance)

#### Estimated percentile lower bound (among test takers)



Benchmark	Description
Higher is better	
<b>MMLU</b>	Representation of questions in 57 subjects (incl. STEM, humanities, and others)
<b>Big-Bench Hard</b>	Diverse set of challenging tasks requiring multi-step reasoning
<b>DROP</b>	Reading comprehension (F1 Score)
<b>HellaSwag</b>	Commonsense reasoning for everyday tasks
<b>GSM8K</b>	Basic arithmetic manipulations (incl. Grade School math problems)
<b>MATH</b>	Challenging math problems (incl. algebra, geometry, pre-calculus, and others)
<b>HumanEval</b>	Python code generation

# LLMs transition to reasoning and now problem solving

Science

**GPQA diamond**

single attempt  
(pass@1)

Mathematics

**AIME 2025**

single attempt  
(pass@1)

Mathematics

**AIME 2024**

single attempt  
(pass@1)

Code generation

**LiveCodeBench**  
v5

single attempt  
(pass@1)

Code editing

**Aider Polyglot**

Agentic coding

**SWE-bench**  
Verified

Factuality

**SimpleQA**

Visual reasoning

**MMMU**

single attempt  
(pass@1)

Image understanding

**Vibe-Eval (Reka)**

Long context

**MRCR**

128k (average)

Multilingual performance

**Global MMLU**

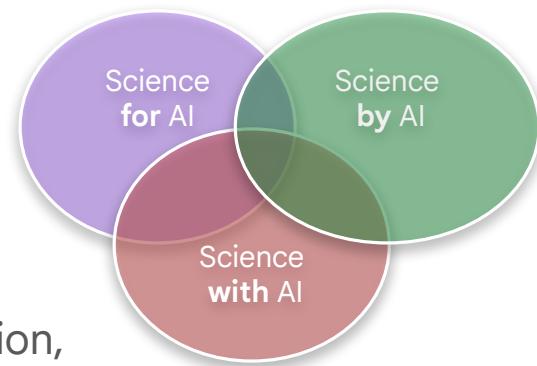


Science

- Multimodal
- Long-context
- Agentic

# We need rigorous evals

## Towards building trustworthy AI for science



- Capabilities to extract, aggregate, and summarize information, and handle algebraic manipulation all within a given large context e.g. a paper - evals for long context reasoning.
- Assess visual comprehension and multimodal understanding
- Automate and **accelerate scientific workflows** such as performing detailed reasoning for derivations, or code generation.
- (Future) **Automate scientific experimentation loop** e.g. starting from hypothesis to reproducing experiments for a full paper, and providing evidence and conclusions.

# SPIQA



[arxiv.org/abs/2407.09413](https://arxiv.org/abs/2407.09413)

## Question answering and grounding responses in figures / tables of papers



Shraman  
Pramanick



Rama  
Chellappa



Subhashini  
Venugopalan

# Humans are visual learners

## Learning to Learn Image Classifiers with Visual Analogy

Linjun Zhou<sup>1</sup> Peng Cui<sup>1</sup> Shiqiang Yang<sup>1</sup> Wenwu Zhu<sup>1</sup> Qi Tian<sup>2</sup>

<sup>1</sup>Tsinghua University <sup>2</sup>Huawei Noah's Ark Lab

zhou116@mails.tsinghua.edu.cn  
 {cuip, yangshd, wwzhu}@mails.tsinghua.edu.cn, tian.qi1@huawei.com

### Abstract

Humans are far better learners who can learn a new concept very fast with only a few samples compared with machine learning models. In this paper, we propose two fundamental learning mechanisms: learning to learn and learning by analogy. In this paper, we attempt to investigate a new human-like learning method by organically combining these two mechanisms. In particular, we study how to generalize the classification parameters from previously learned concepts to a new concept. We first propose a novel Visual Analogy Graph Embedded Regression (VAGER) model to jointly learn a low-dimensional embedding space and a linear mapping function from the embedding space to classification parameters for the novel class. We then propose an out-of-sample embedding method to learn the embedding of the novel class by analogy from samples through its visual analogy with base classes and derive the classification parameters for the new class. We conduct extensive experiments on ImageNet dataset and the results show that our method could consistently and significantly outperform state-of-the-art baselines.

### 1. Introduction

The emergence of deep learning has advanced the image classification performance into an unprecedented level. The error rate on ImageNet has been halved and halved again [11, 31, 2], even approaching human-level performance. Despite the success, the state-of-the-art models are notoriously data hungry, requiring tons of samples for parameter learning. In real cases, however, the visual phenomena follows a long-tail distribution [1] where there are a few sub-categories data-rich and the rest are with limited training samples. How to learn a classifier from as few samples as possible is critical for real applications and fundamental to exploring new learning mechanisms.

Compared with machines, people are far better learners as they are capable of learning models from very limited samples of a new category and make accurate prediction

and judgment accordingly. An intuitive example is that a baby learner can learn to recognize a wolf with only a few sample images provided that he/she has been able to successfully recognize a dog. The key is to verify using the different samples whether the prior knowledge to generalize across different categories [1]. It means that models do not need to learn a new classifier (e.g. wolf) from scratch as most machine learning methods, but generalize and adapt the previously learned classifiers (e.g. dog) towards the new category. A major way to acquire the prior knowledge is through learning to learn from previous experience. In the image classification scenario, learning to learn refers to the mechanism that learning to recognize a new concept can be accelerated by previously learned other related concepts.

A typical image classifier is constituted by representation and classification steps, leading to two fundamental problems in learning to learn image classifiers: (1) how to generalize the representation parameters from a few samples to a new concept; (2) how to generalize the classification parameters of previous concepts to a new concept. In literature, transfer learning and domain adaptation methods [12] are proposed with a similar notion, mainly focusing on the problem of representation generalization across different domains and tasks. With the development of CNN-based image classification models, the high-level representations learned from very large scale labeled dataset are demonstrated to have good transferability across different concepts or even different datasets [20], which significantly alleviate the representation generalization problem. However, how to generalize the classification parameters in deep models (e.g. the 67 layers in AlexNet) in well-trained concepts to a new concept (with only a few samples) is largely ignored by previous studies.

Learning by analogy has been proved to be a fundamental building block in human learning process [14], a plausible explanation on the fast learning of novel class is that a human learner selects some similar classes from the base classes by visual analogy, transfers and combines their classification parameters for the novel class. In this sense, visual analogy provides an effective and informative clue for

What is the purpose of a visual analogy graph?

# Retrieve information from meticulous figures/tables

## Learning to Learn Image Classifiers with Visual Analogy

Linjun Zhou<sup>1</sup> Peng Cui<sup>1</sup> Shiqiang Yang<sup>1</sup> Wenwu Zhu<sup>1</sup> Qi Tian<sup>2</sup>

<sup>1</sup>Tsinghua University <sup>2</sup>Huawei Noah's Ark Lab

{cuip, yangshd, wwzhu}@mails.tsinghua.edu.cn, tian.qi@huawei.com

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Humans are far better learners who can learn a new concept very fast with only a few samples compared with machine learning models. In this paper, we propose two fundamental learning mechanisms: learning to learn and learning by analogy. In this paper, we attempt to investigate a new human-like learning method by organically combining these two mechanisms. In particular, we study how to generalize the classification parameters from previously learned concepts to a new concept. We first propose a novel Visual Analogy Graph Embedded Regression (VAGER) model to jointly learn low-dimensional embedding space and a linear mapping function from the embedding space to classification parameters for a novel class. We then propose an out-of-sample embedding method to learn the embedding of a new class by inferring its embedding through its visual analogy with base classes and derive the classification parameters for the new class. We conduct extensive experiments on ImageNet dataset and the results show that our method could consistently and significantly outperform state-of-the-art baselines.

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Compared with machines, people are far better learners as they are capable of learning models from very limited samples of a new category and make accurate prediction

and judgment accordingly. An intuitive example is that a baby learner can learn to recognize a wolf with only a few sample images provided that he/she has been able to successfully recognize a dog. The key is to verify making the difference between the two images and then applying knowledge to generalize across different categories [15]. It means that models do not need to learn a new classifier (e.g. wolf) from scratch as most machine learning methods, but generalize and adapt the previously learned classifiers (e.g. dog) towards the new category. A major way to acquire the prior knowledge is through learning to learn from previous experience. In the image classification scenario, learning to learn refers to the mechanism that learning to recognize a new concept can be accelerated by previously learned other related concepts.

A typical image classifier is constituted by representation and classification steps, leading to two fundamental problems in learning to learn image classifiers: (1) how to generalize the representation of previous concepts to a new concept; (2) how to generalize the classification parameters of previous concepts to a new concept. In literature, transfer learning and domain adaptation methods [16] are proposed with a similar notion, mainly focusing on the problem of representation generalization across different domains and tasks. With the development of CNN-based image classification models, the high-level representations learned from very large scale labeled dataset are demonstrated to have good transferability across different concepts or even different datasets [20], which significantly alleviate the representation generalization problem. However, how to generalize the classification parameters in deep models (e.g. the fc7 layer in AlexNet) from well-trained concepts to a new concept (with only a few samples) is largely ignored by previous studies.

Learning by analogy has been proved to be a fundamental building block in human learning process [17]. A plausible explanation on the fast learning of novel class is that a human learner selects some similar classes from the base classes by visual analogy, transfers and combines their classification parameters for the novel class. In this sense, visual analogy provides an effective and informative clue for

What is the purpose of a visual analogy graph?

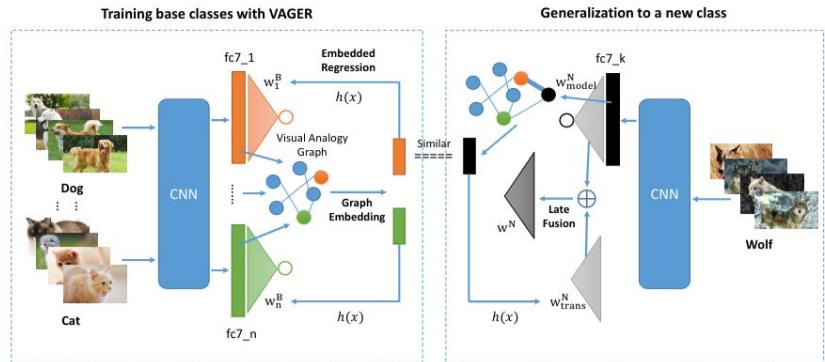


Figure 1. The framework of learning to learn image classifiers. *Training Base Classes with VAGER*: By training base classes with VAGER, we derive the embeddings of each base class and the common mapping function from embeddings to classification parameters. *Generalization to a New Class*: Given a new class with only a few samples, we can infer its embedding through out-of-sample inference, and then transform the embedding into transferred classification parameters by the mapping function learned by VAGER. After training the classifier with new class samples and getting the model classification parameters, we fuse the two kinds of parameters to form the final classifier.

# Scientific Paper Image Question Answering

## Scientific Research Paper

## Question: Which method performs best on nuScenes?

### nuScenes: A multimodal dataset for autonomous driving

Holger Caesar, Varun Bankiti, Alex H. Lang, Soroush Vera, Venic Liang, Qiang Xu, Anish Krishnan, Yu Pan, Giacomo Baldan, Oscar Brilhans  
nuTonomy an APTIV company  
[www.nutonomy.com](https://www.nutonomy.com)

#### Abstract

Robust detection and tracking of objects is crucial for the deployment of autonomous vehicle technology. Image based benchmarks have been developed to evaluate the performance of agents in the environment. Most autonomous driving systems rely on a combination of sensors, including range sensors such as lidar and radar. As machine learning provides, there is a need to train and evaluate such methods on datasets containing complex sensor data along with an annotation of the environment. In this paper, we introduce the first dataset to carry the full autonomous vehicle sensor stack. The nuScenes dataset contains 3600 scenes in a 360° field of view, achieves complete 1000 scenes each 200ms, and provides a detailed annotation of the environment with 23 classes and 8 attributes. It is the most annotated and the deepest dataset as many images in the previous KITTI dataset, the de facto standard for autonomous driving, only provide coarse object analysis as well as bounding box for lidar data. The nuScenes dataset is the first to provide full lidar and more information are available online.

**1. Introduction**  
Autonomous driving has the potential to radically change the way we live and move many human lives [1]. A crucial part of safe navigation is the ability to track objects in the environment and to predict the movement of the vehicle. To achieve this, a modern self driving vehicle deploys multiple sensors to detect and track objects using machine learning algorithms. Such algorithms rely increasingly on machine learning to make decisions in complex environments. While there is a wealth of image datasets for this purpose (Table 1), there is a lack of multimodal datasets that combine lidar, radar, and camera data to evaluate an autonomous driving perception system. We released the nuScenes dataset to address this gap.

Since the three sensor types have different failure modes and provide different types of information, a multimodal dataset is essential for agent detection and tracking. Lidar and radar are the most accurate sensors, but their sensing ranges are not complementary, but provide redundancy in the face of obfuscation, failure, adverse conditions

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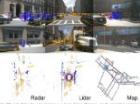


Figure 1: An example from the nuScenes dataset. We see a different camera view, lidar and radar data as well as the human annotated 3D scene representation. The camera view is shown with some descriptive text.



Figure 2: Caption



Figure 3: Caption



Figure 4: Caption

Details		Lidar sweeps/Pretraining					
Ge Caesar		NDS (%) mAP (%) mAVE (m)					
1	Lidar	KITTI	31.8	21.9	1.21		
5	Lidar	KITTI	42.9	27.7	0.34		
10	Lidar	KITTI	44.9	28.9	0.34		
10	Imagenet	KITTI	44.9	28.9	0.31		
10	None	KITTI	44.2	27.6	0.33		

Table 2: Caption

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Table 3: Caption

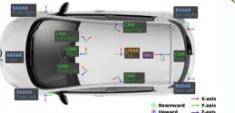


Figure 4: Caption

Method		NDS (%) mAP (%) mATE (%) mAOE (%) mAVE (%)					
Ours [2]		74.3 1.3 1.32 1.0 0.98					
SSD+2D [1]		26.8	16.4	0.90	0.35	1.31	0.29
MIFN [2]		38.4	30.4	0.74	0.26	1.55	0.13
PP [1]		45.3	30.5	0.52	0.29	0.90	0.37
Yggdrasil [3]		63.3	52.8	0.30	0.28	0.38	0.14

Table 4: Caption

## Figures and Tables with Captions

## Full Paper Text

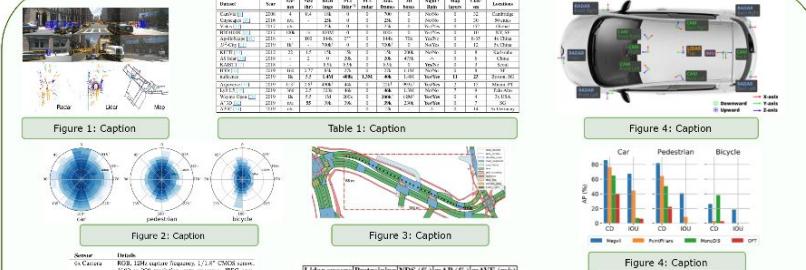


# Scientific Paper Image Question Answering

# Ground responses in figures/tables

## Scientific Research Paper

Q: Are walkways present in the semantic map?



## Figures and Tables with Captions

## Full Paper Tex



nuScenes: A multimodal dataset for autonomous driving

Holger Caesar, Yurun Bankiti, Alex H. Lang, Sourabh Vera, Venice Erin Liang, Qiang Xu,  
Anush Krishnan, Yu Pan, Giancarlo Baldan, Oscar Beijbom  
nuTonomy: an APTIV company

### Abstract

of detection and tracking of objects is crucial for development of autonomous vehicle technology. Image sequences from a camera-driven vehicle provide a consistent set of such data for training and testing of systems that detect and track objects in the environment. Most autonomous vehicles, however, carry a combination of cameras and lidars, and these sensors are used in tandem. As motion features are often used to detect and track objects in the scene, there is a need to develop and evaluate such methods (containing range sensor data along with images) that work well for camera sensor (recording images) and lidar sensor (recording range data). In this paper, we present the full dataset, including images, lidars, cameras, 5 radars and 1 lidar, all with full 280 deg. of view, collected over 1000 scenes, each with a different camera and lidar combination (e.g. 10 cameras and 8 lidars). We also present motion features, as many images as the pioneering KITTI dataset, the novel 3D dense and matching features. We also present a novel dataset for 3D lidar feature extraction. We believe that this dataset is a valuable resource for its research and development potential. Details and more information are available online.<sup>1</sup>

Autonomous driving has the potential to radically transform the cityscape and save many human lives [1]. A central part of navigation is the detection and tracking of the scene surrounding the vehicle. In this paper, we introduce a self-driving vehicle that deploys sensors along with analytical detection and tracking modules. Such architectures only increasingly come online, which drives the need for benchmark datasets. There is a plethora of image datasets for this purpose [2], but there is a lack of multimodal datasets that can be used to evaluate the performance of the full set of challenges associated with building a modern driving perception system. We released the *driv3r* dataset to address this gap<sup>1</sup>.

2025 RELEASE UNDER E.O. 14176

# SPIQA tasks

## Scientific Research Paper

### nuScenes: A multimodal dataset for autonomous driving

Holger Caesar, Varun Bankiti, Alex H. Lang, Soroush Vera, Venic Liang, Qiang Xu, Anish Krishnan, Yu Pan, Giacomo Baldan, Oscar Brilhans  
nuTonomy is an APTIV company  
[arXiv:1903.11027v5 \[cs.LG\]](https://arxiv.org/abs/1903.11027v5) 5 May 2020

#### Abstract

Robotic detection and tracking of objects is crucial for the deployment of autonomous vehicle technology. Image-based benchmarks have been developed to evaluate the performance of agents in the environment. Most autonomous vehicle perception systems are multimodal, using a variety of range sensors such as lidar and radar. As a result, to provide robust perception, there is a need to train and evaluate such methods on datasets containing raw sensor data along with an annotation of the environment. In this paper, we introduce the first dataset to carry the full autonomous vehicle sensor stack, including lidar, radar, camera, GPS, IMU, and a 360-degree field of view, inferences computed from 1000 scenes each with a different weather condition and time of day. The dataset contains 23 classes and 8 attributes. It is 7x or more annotated and has as many images as the previous KITTI dataset. The dataset is designed to be a general benchmark to facilitate provide careful dataset analysis as well as baseline for literature comparison. The nuScenes dataset is the first dataset that provides full and more information are available online.

**1. Introduction**  
Autonomous driving has the potential to radically change the way we live and see many human lives [1]. A crucial part of safe navigation is the ability to track objects in the environment and to predict the movement of the vehicle. To achieve this, a modern self-driving vehicle deploys multiple sensors to detect and track objects using machine learning algorithms. Such algorithms rely increasingly on machine learning models to make decisions in the environment. While there is a wealth of image datasets for the purpose (Table 1), there is a lack of multimodal datasets that combine raw sensor data with annotations for training an autonomous driving perception system. We released the nuScenes dataset [2].

Since the three sensor types have different failure modes and are not redundant, it is important to have a multimodal dataset to be able to detect and track objects in the environment. Lidar and radar are more robust to weather conditions, while camera vision is not just complementary, but provide redundancy in the face of suboptimal, failure, adverse conditions

Since the three sensor types have different failure modes and are not redundant, it is important to have a multimodal dataset to be able to detect and track objects in the environment. Lidar and radar are more robust to weather conditions, while camera vision is not just complementary, but provide redundancy in the face of suboptimal, failure, adverse conditions

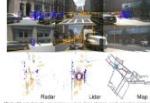


Figure 1: An example from the nuScenes dataset. We see 6 different camera views, lidar and radar data, as well as the human annotated 3D scene. The scene is a street in Boston, and the camera views are some descriptives.

## Question: Which method performs best on nuScenes?



Figure 1: Caption



Figure 2: Caption

Figure 2: Caption

Table 1: Caption

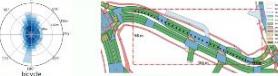


Figure 3: Caption

Figure 3: Caption

Table 2: Caption

Table 2: Caption

Table 3: Caption

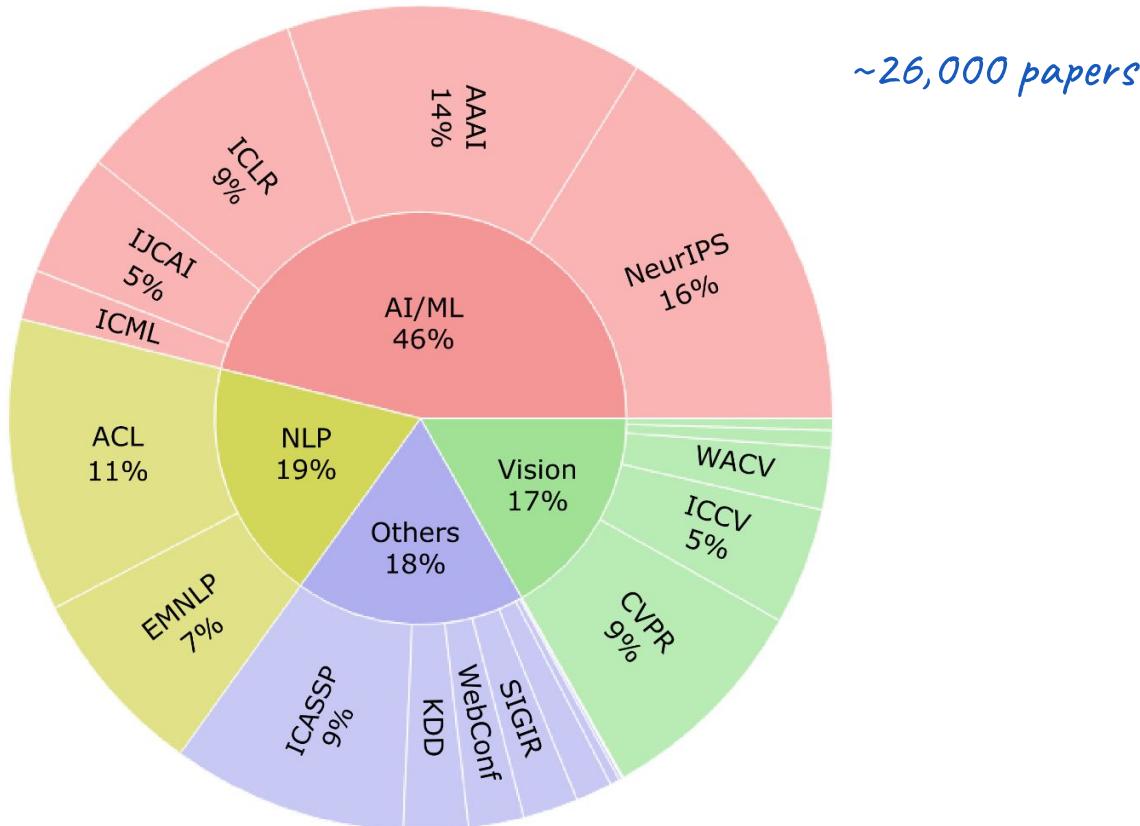
Table 3: Caption

Table 4: Caption

02

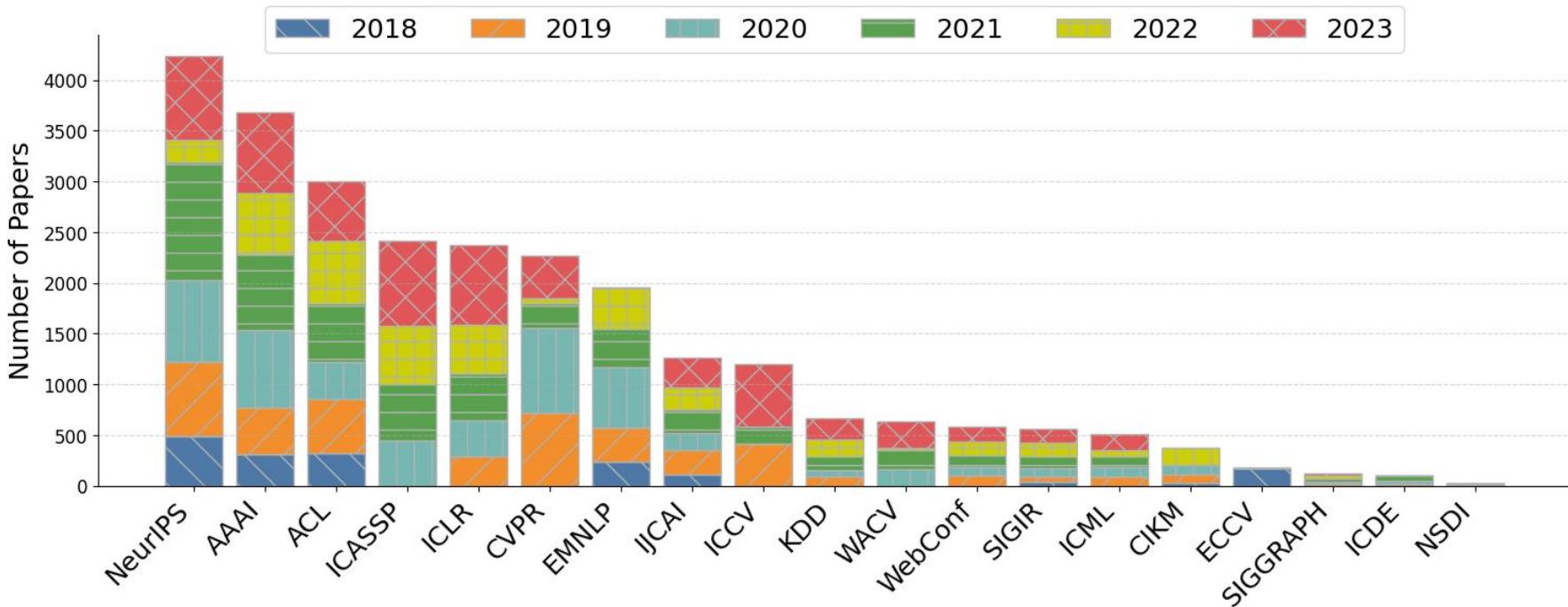
# SPIQA Dataset

# Papers published in CS conferences also on ArXiv

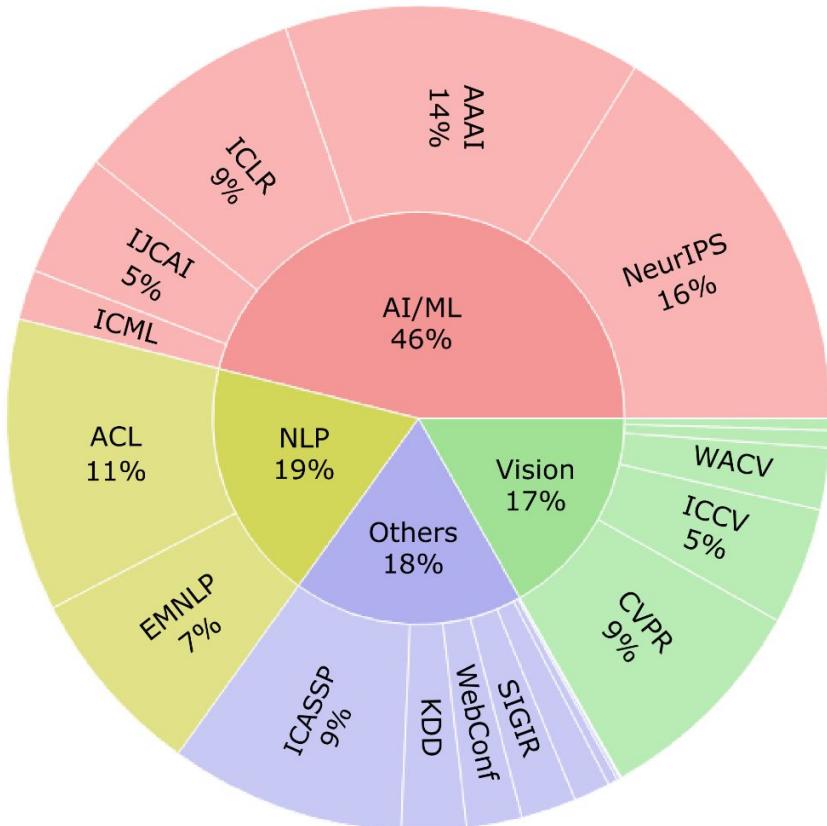


# Downloaded papers statistics

*~26,000 papers*



# Extracted Figures and Tables



*~26,000 papers*

*~270,000 images (figures + tables)*

Statistics	Numbers
Total papers	25,859
Published between	2018 - 2023
Total tables	117,707
Total figures	152,487
Figure subcategories	
- Schematics	45396
- Plots and charts	72327
- Visualizations	28103
- Others	6661

03

Automatically generate  
questions.

You are a professor. Generate one question based on the image and caption to test if a student can interpret and understand the image well.

Also classify the figure as "plot", "schematic", "photograph(s)", "table" or "others".

Image:

`{{ Image }}`

Caption: `{{ caption }}` \

The passage where the figure is referenced is provided below. \

PASSAGE: `{{ passage }}` \

Construct your questions and corresponding answers. Use this format. \

Question: <question that tests understanding of the image.> \

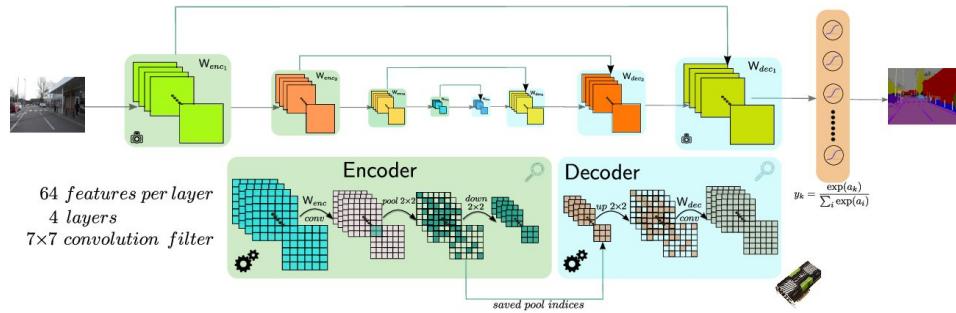
Answer: <Answer to the question based on the passage.> \

Explanation: <How the figure helps answer the question.> \

Figure\_type: <"type of figure" where type of figure is one of \ ["plot", "schematic", "photograph(s)", "table", "other"]>

# Paragraph:

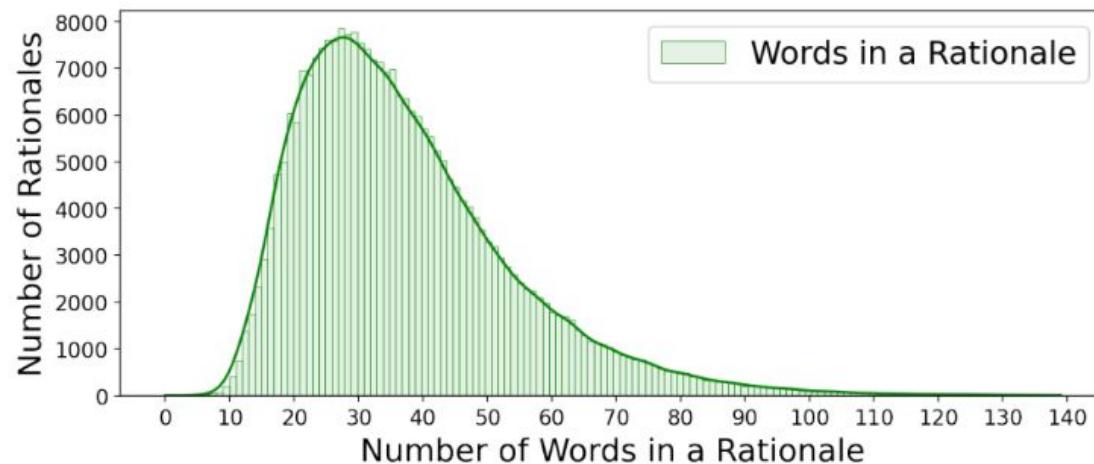
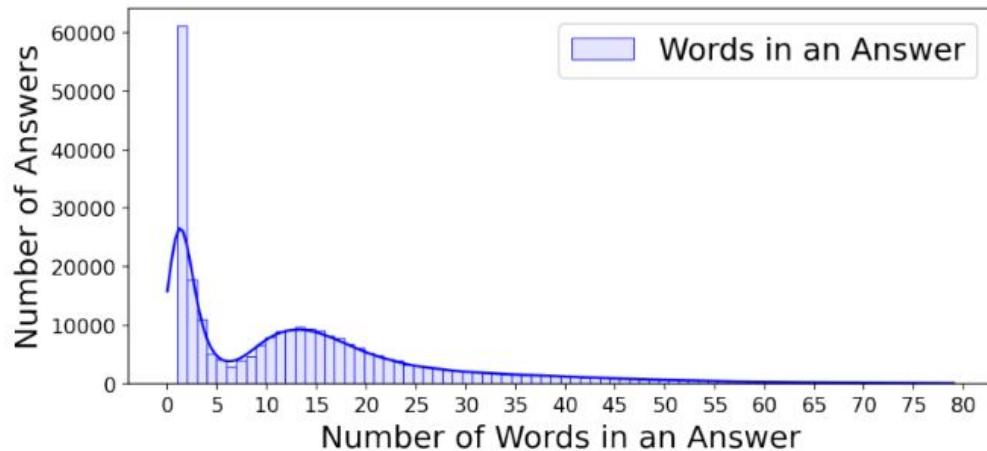
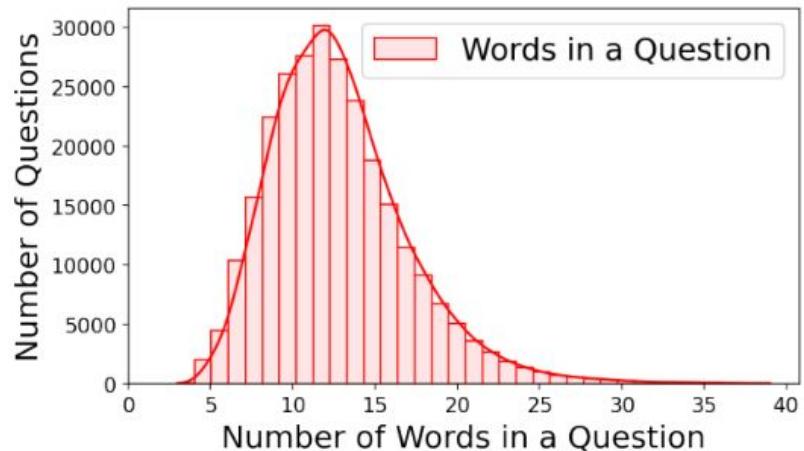
SegNet uses a “flat” architecture, i.e, the number of features in each layer remains the same (64 in our case) but with full connectivity. This choice is motivated by two reasons. First, it avoids parameter explosion, unlike an expanding deep encoder network with full feature connectivity (same for decoder). Second, the training time remains the same (in our experiments it slightly decreases) for each additional/deeper encoder-decoder pair as the feature map resolution is smaller which makes convolutions faster. Note that the decoder corresponding to the first encoder (closest to the input image) produces a multi-channel feature map although the encoder input is either 3 or 4 channels (RGB or RGBD) (see **Fig. 1**).



## Gemini Pro Vision

**Question:** How many feature maps are produced by the encoder?

**Answer:** 4



05

# Filter questions for quality (Test set)

# Pilot annotations

Can the question be answered from

- image-only or
- image+caption

In this task you will answer 2 distinct questions for the question and image presented below

- **Task 1: Image-only**
  - Does the image have information to help answer the question?
  - Can you try to guess the answer, otherwise explain why or why not?
- **Task 2: Image+caption**
  - Does the image along with the caption, now have information to help answer the question?
  - (optional) Do you want to guess the answer now or share any new explanation?

In this task, you will answer two distinct questions for the question and image presented below:

**Task-1: Image-only**

- Does the image have information to help answer the question?
- Can you try to guess the answer, otherwise explain why or why not

**Task-2: Image+caption**

- Does the image along with the caption, now have information to help answer the question?
- (optional) Do you want to guess the answer now or share any new explanation?

**Paper ID**

2105.05233

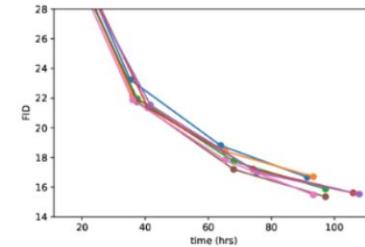
**Paper Title**

Diffusion Models Beat GANs on Image Synthesis

**Question**

Which are the metrics used by authors to compare the performance of the models?

**Image**



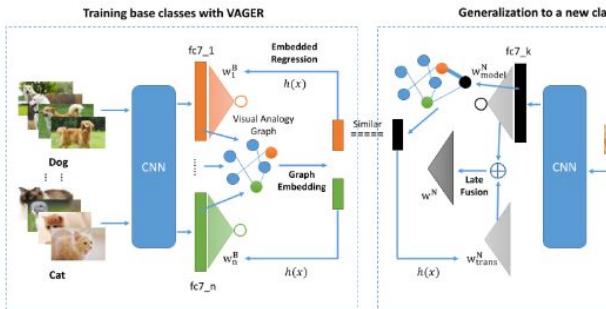
is a function of wall-clock time. FID evaluated over 10k samples instead of 50k for efficiency.

to help answer the question?

ation?

provide information on the metrics used for comparing the performance.

What is the purpose of the Visual Analogy Graph in the VAGER framework?



Caption

The framework of learning to learn image classifiers. Training Base Classes with VAGER: By training base classes to transform the embedding into transferred classification parameters by the mapping function learned by VAGER.

The Visual Analogy Graph is used to learn the relationships between different classes of images. It does this by

The Visual Analogy Graph is shown in the middle of the figure. It takes the output of the CNNs for each of the

UI

Consider If the question can be answered from the figure. Should we keep the questions or discard?

- Keep
- Discard

Should the question or answer be modified?

- YES
- NO

Modified question:

---



---

Modified answer:

---



---

05

Augment Existing QA datasets  
on papers with figures

# QASPER

## A Dataset of Information-Seeking Questions and Answers Anchored in Research Papers

Pradeep Dasigi\* Kyle Lo\* Iz Beltagy\* Arman Cohan\*  
Noah A. Smith◊\* Matt Gardner\*

\*Allen Institute for AI ◊Paul G. Allen School of CSE, University of Washington  
{pradeepd,kylel,beltagy,armanc,noah,mattg}@allenai.org

### Abstract

Readers of academic research papers often read with the goal of answering specific questions. Question Answering systems that can answer those questions can make consumption of the content much more efficient. However, building such tools requires data that reflect the difficulty of the task arising from complex reasoning about claims made in multiple parts of a paper. In contrast, existing information-seeking question answering datasets usually contain questions about generic factoid-type information. We therefore present QASPER, a dataset of 5,049 questions over 1,585 Natural Language Processing papers. Each question is written by an NLP practitioner who read only the title and abstract of the corresponding paper, and the question seeks information present in the full text. The questions are then answered by a separate set of NLP practitioners who also provide supporting evidence to answers. We find that existing models that do well on other QA tasks do not perform well on answering these questions, underperforming humans by at least 27  $F_1$  points when answering them from entire papers, moti-

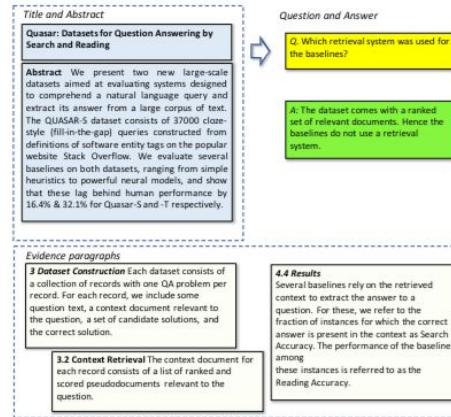


Figure 1: An example instance taken from QASPER. A **question** about the paper is written after reading only the title and the abstract. To arrive at the **answer**, one finds relevant **evidence**, which can be spread across multiple paragraphs. In this example, to answer the question about “baselines”, the reader must realize from evidence from Sections 3 and 4 that “context documents” come pre-ranked in the dataset and the paper’s “baselines” select from these “context documents.”

# QASA: Advanced Question Answering on Scientific Articles

Yoonjoo Lee <sup>\*1</sup> Kyungjae Lee <sup>\*2</sup> Sunghyun Park <sup>2</sup> Dasol Hwang <sup>2</sup> Jaehyeon Kim <sup>2</sup> Hong-in Lee <sup>3</sup>  
Moontae Lee <sup>2,4</sup>

## Abstract

Reasoning is the crux of intellectual thinking. While question answering (QA) tasks are prolific with various computational models and benchmark datasets, they mostly tackle factoid or shallow QA without asking deeper understanding. Dual process theory asserts that human reasoning consists of associative thinking to collect relevant pieces of knowledge and logical reasoning to consciously conclude grounding on evidential rationale. Based on our intensive think-aloud study that revealed the three types of questions: surface, testing, and deep questions, we first propose the QASA benchmark that consists of 1798 novel question answering pairs that require full-stack reasoning on scientific articles in AI and ML fields. Then we propose the QASA approach that tackles the full-stack reasoning with large language models via associative selection, evidential rationale-generation, and systematic composition. Our experimental results show that QASA's full-stack inference outperforms the state-of-the-art INSTRUCTGPT by a big margin. We also find that rationale-generation is critical for the performance gain, claiming how we should rethink advanced question answering. The dataset is available at <https://github.com/lgresearch/QASA>.

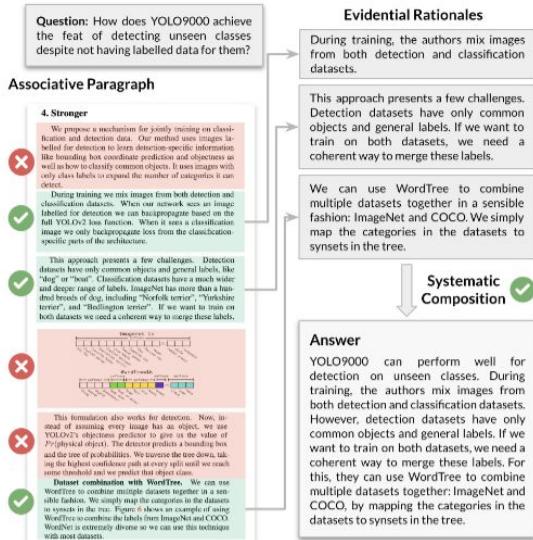


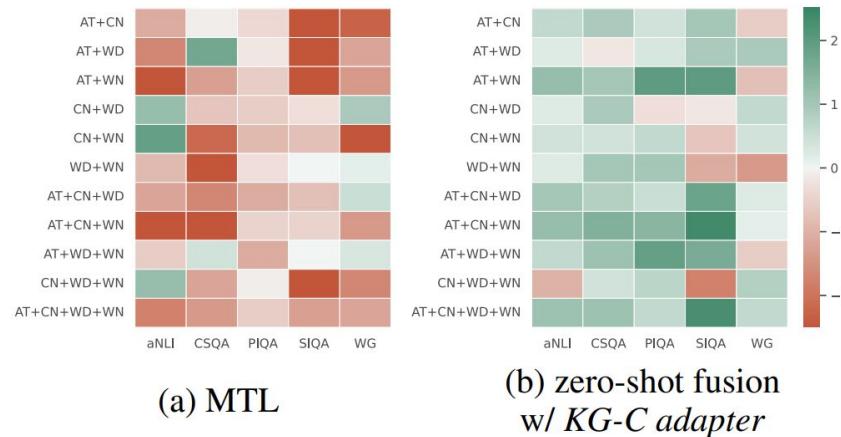
Figure 1. An example of QASA. A question that the reader/author asks about the paper while reading the paper. To formulate the answer, one classifies whether the paragraph contains evidence to answer the question. Evidential rationales are written for each evidential paragraph and are systematically composed into a comprehensive answer.

# Example from SPIQA-QASA dataset (qasa\_metadata['631']['question'])

Query: What is the correlation between the number of KGs and the performance when using zero-shot fusion?

Answer: In Figure 6, while the MTL tends to show the decrease of the performance when more KGs are utilized for training, our method obtains relative performance improvement across most of benchmarks.

Evidential Figure:



# Example from SPIQA-QASPER dataset (qasper\_metadata['56']['question'])

Query: By how much do they outperform other models in the sentiment intent classification tasks?

Answer: In the sentiment classification task by 6% to 8% and in the intent classification task by 0.94% on average.

Evidential Figures: Both figures answer the question.

Model	F1-score (micro, %)		
	Inc	Corr	Inc+Corr
<i>BLEU score</i>	0.63	0.00	0.63
Rasa (spacy)	44.00	54.00	54.00
Rasa (tensorflow)	53.06	60.00	59.18
Dialogflow	30.00	40.00	42.00
SAP Conversational AI	59.18	65.31	59.18
Semantic Hashing	72.00	70.00	72.00
BERT	72.00	76.00	74.00
Stacked DeBERT (ours)	<b>80.00</b>	<b>82.00</b>	<b>80.00</b>

Model	F1-score (micro, %)		
	Complete	gtts-witai	macsay-witai
<i>BLEU score</i>	0.00	0.44	0.50
<i>WER score</i>	0.00	2.39	3.11
Rasa (spacy)	92.45	91.51	86.79
Rasa (tensorflow)	<b>99.06</b>	92.89	91.51
Dialogflow	96.23	87.74	81.13
SAP Conversational AI	95.24	94.29	94.29
Semantic Hashing	<b>99.06</b>	95.28	91.51
BERT	98.11	96.23	94.34
Stacked DeBERT (ours)	<b>99.06</b>	<b>97.17</b>	<b>96.23</b>

# QASA and QASPER dataset statistics

	QASA	QASPER Dev	QASPER Train
# of papers	112	281	888
# of original questions	1554	1005	2593
# of papers after filtering	65	132	299
# of questions where answers mention figs/tables (% of original questions)	228 (14.6%)	372 (37.0%)	530 (20.4%)
Avg. # of questions per paper (after filtering)	3.507	2.818	1.772
Avg. # figs + tables per filtered paper	12.2153	6.6439	7.3177
Avg. # referenced figs + tables per filtered question	1.6096	1.2849	1.2905

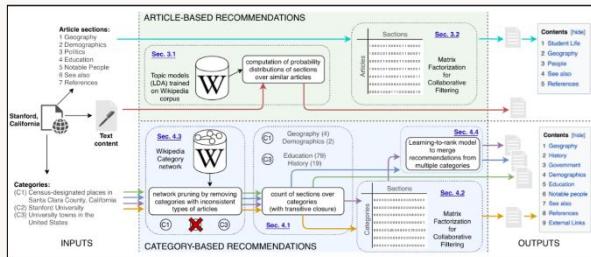
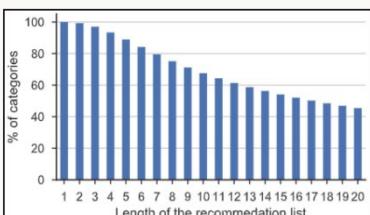
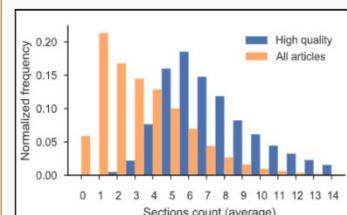
# Overall train, val, test splits for SPIQA

Split	# Papers	# Ques.	# Figures				# Tables
			Sche.	Plots & Charts	Vis.	Others.	
Train	25,459	262,524	44,008	70,041	27,297	6,450	114,728
Val	200	2,085	360	582	173	55	915
test-A	118	666	154	301	131	95	434
test-B	65	228	147	156	133	17	341
test-C	314	493	415	404	26	66	1332

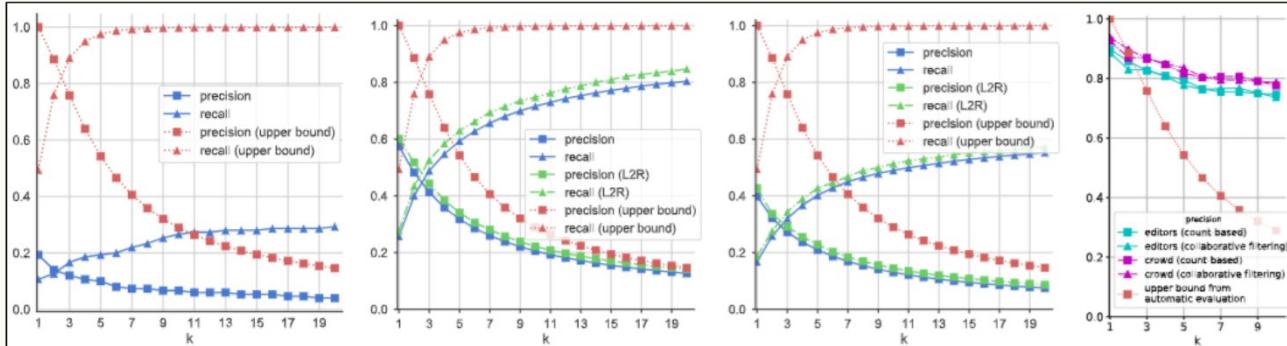
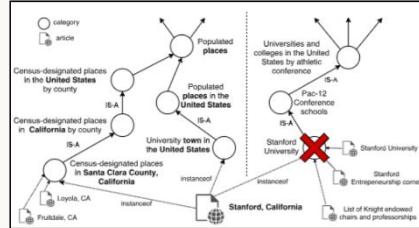
A - QASPER  
B - QASA  
C - new

1.3k+ Qs for test  
2k+ for val.  
260k+ for train

### All Images from the Paper



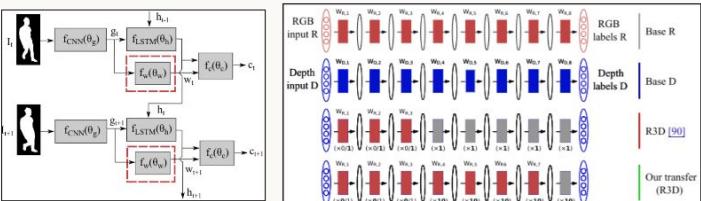
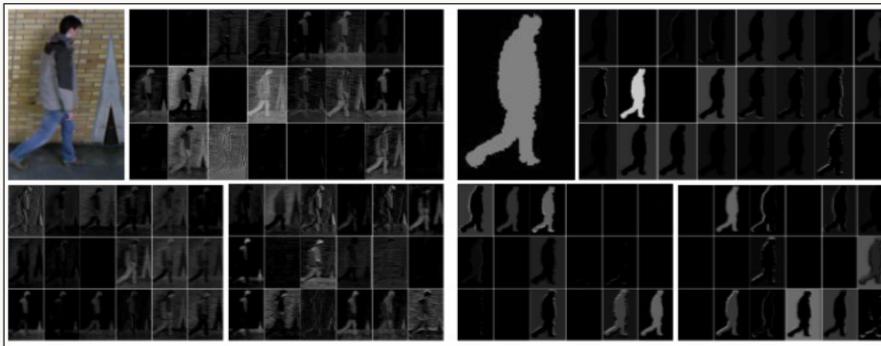
Topic modeling (Sec. 3.1)	Article-based collab. filtering (Sec. 3.2)	Category-section counts (Sec. 4.1)	Generalizing counts via collab. filtering (Sec. 4.2)
HISTORY	HISTORY OF THE DOCUMENT	HISTORY	HISTORY
SPORTS	FAIRY TALE	DEMOGRAPHICS	CAREER
AWARDS	COMMUNES WITHOUT ARMS	ECONOMY	PERSONAL LIFE
MEDAL SUMMARY	CONTENT AND IMPORTANCE	EDUCATION	HONOURS
STATISTICS	PLAYER MOVEMENT	POLITICS	CAREER STATISTICS



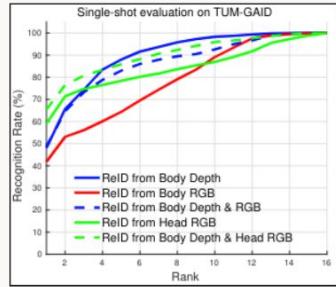
**Question:** What is the trend in precision, recall as number of recommended sections k increases?

**Input Prompt:** First find which of the input images are helpful to answer the given question, and then answer the question.

# All Images from the Paper



Mode	Method	Top-1 Accuracy (%)		
		DPL-T	BIWI	IIT PAVIS
Single-shot	Random	8.3	2.0	1.3
	Skeleton (NN) [58]	—	21.1	28.6
	Skeleton (SVM) [59]	—	13.8	35.7
	3D RAM [26]	47.5	<b>30.1</b>	41.3
	Our method (CNN)	<b>66.8</b>	25.4	<b>43.0</b>
Multi-shot	Skeleton (NN) [58]	—	39.3	—
	Skeleton (SVM) [59]	—	17.9	—
	Energy Volume [70]	14.2	25.7	18.9
	3D CNN+Avg Pooling [8]	28.4	27.8	27.5
	4D RAM [26]	55.6	45.3	43.0
	Our method (CNN-LSTM+Avg Pooling)	75.5	45.7	50.1
	Our method with attention from [88]	75.9	46.4	50.6
	Our method with RTA attention	<b>76.3</b>	<b>50.0</b>	<b>52.4</b>



**Question:** Which method achieves the highest Top-1 Accuracy for multi-shot person re-identification on the BIWI dataset, and how does it compare to the best single-shot method?

**Input Prompt:** First find which of the input images are helpful to answer the given question, and then answer the question.

07

# Eval Setup & Metrics

# Eval Setup – Tasks

Goal: Answer the question and ground the response in the correct figure.

## Direct QA

- All images (figures and tables) only
- Question
- Prompt the model to only answer the question.

# Eval Setup – Tasks

Goal: Answer the question and ground the response in the correct figure.

## Direct QA

- All images (figures and tables) only
- Question
- Prompt the model to only answer the question.

## CoT QA

- All images (figures and tables) only
- Question
- Prompt to first retrieve helpful image and then answer the question

# Sample prompt for CoT QA

You are given a question, a few input images, and a caption corresponding to each input image.

First, please determine which image and corresponding caption is most helpful to answer the question, and briefly explain why.

Next, please generate a direct answer to the question. Question:  
<question>.

First output which image is helpful in the following format: {'Image': A, 'Rationale': 'Very Brief Explanation on Why Image A is helpful'} where A is the image number.

Next, answer the question as The answer is : <Your Answer>.

# Eval Setup – Tasks

Goal: Answer the question and ground the response in the correct figure.

## Direct QA

- All images (figures and tables) only
- Question
- Prompt the model to only answer the question.

## CoT QA

- All images (figures and tables) only
- Question
- Prompt to first retrieve helpful image and then answer the question

## Direct QA w. Full Text

- All images (figures and tables)
- Full text of the paper
- Question
- Prompt the model to only answer the question.

# Models

- Gemini 1.0 pro vision
- Gemini-1.5 pro
- Gemini 1.5 flash
- Claude-3 (Opus)
- GPT-4o
- GPT-4 Vision
- SPHINX-v2
- InstructBLIP 7B
- LLaVA 1.5 7B
- XGen MM
- InternLM-XC
- Cog-VLM

Support only 1 image for inference.

# Models

- Gemini 1.0 pro vision
- Gemini-1.5 pro
- Gemini 1.5 flash
- Claude-3 (Opus)
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- GPT-4 Vision
- SPHINX-v2
- InstructBLIP 7B
- LLaVA 1.5 7B
- XGen MM
- InternLM-XC
- Cog-VLM

Support only 1 image for inference.

## Tuning (single image VQA)

- InstructBLIP 7B
- LLaVA 1.5 7B
- Gemini 1.0 pro (single and multi-image)

# Metrics



BLEU



METEOR



ROUGE-L



CIDEr



BERTScore

# Metrics



BLEU



METEOR



ROUGE-L



CIDEr



BERTScore

But, existing metrics are insufficient to correctly evaluate free-form QA especially where there is just a single ground truth reference.

# LLM-Log-likelihood Score (L3Score)

Is the semantic meaning of the predicted response similar (equivalent) to the ground truth answer?

$L3Score = P(\text{yes})$

# LLM-Log-likelihood Score (L3Score)

You are given a question, ground-truth answer, and a candidate answer.

Question: <question>

Ground-truth answer: <GT>

Candidate answer: <answer>

Is the semantic meaning of the ground-truth and candidate answers similar? Answer in one word - Yes or No.

# L3Score: Normalized log-probs for binary classification

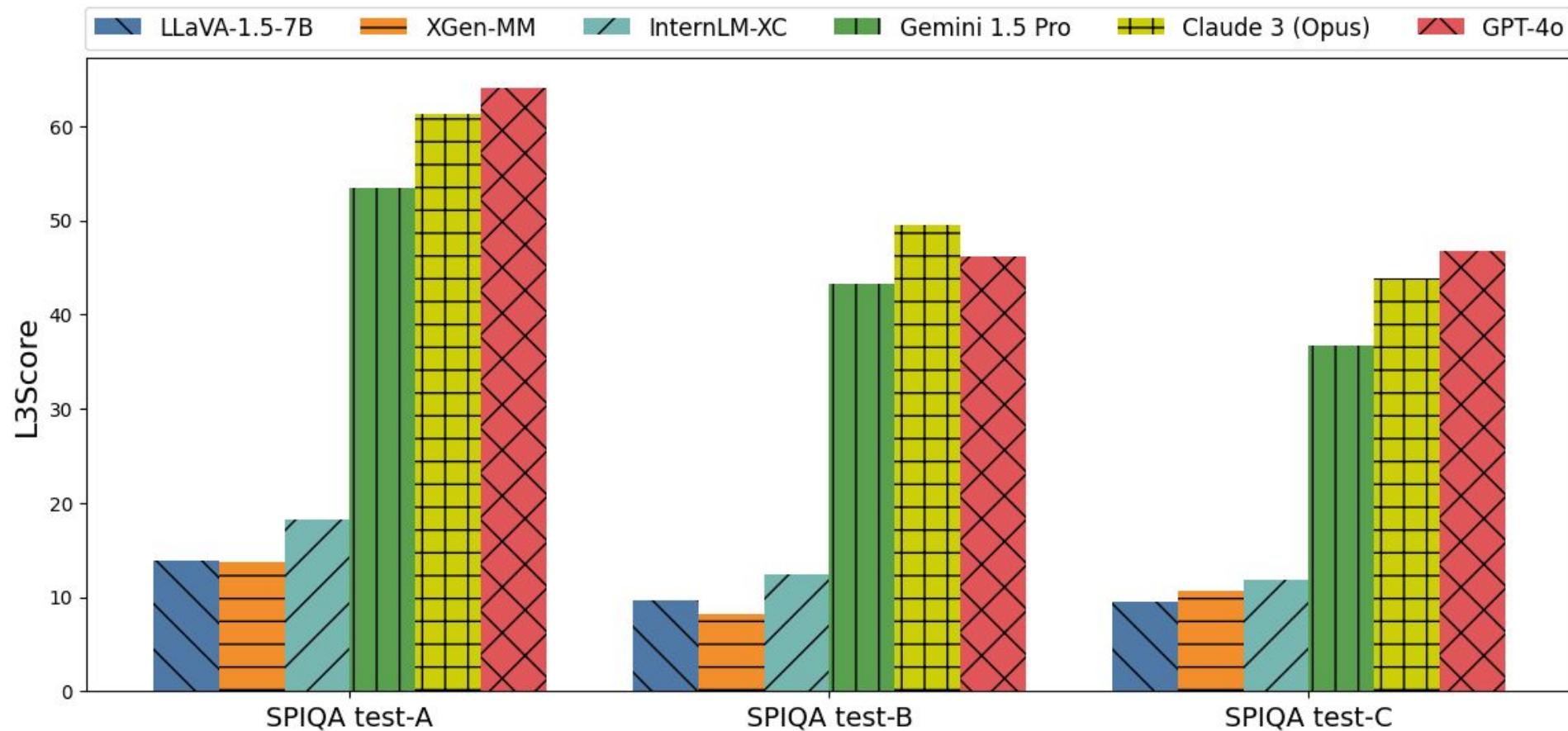
$$\text{L3Score} = \text{softmax}(x)_{yes} = \frac{\exp(l_{yes})}{\exp(l_{yes}) + \exp(l_{no})}$$

- $l_{yes}, l_{no}$ : log-probs of token 'yes' and 'no'
- scoring mode
- approx. for GPT-4o

08

# Results

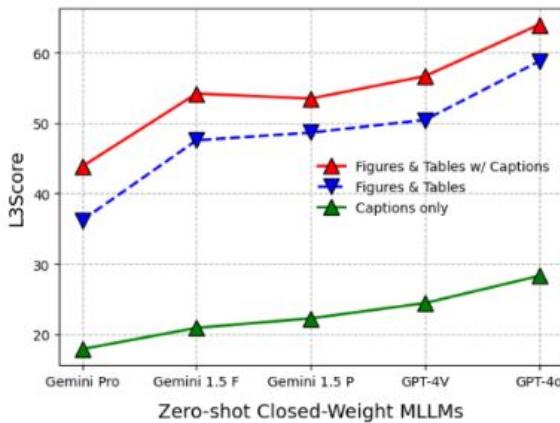
# GPT-4o best on test-A and test-C, Claude-3 tie on test-B



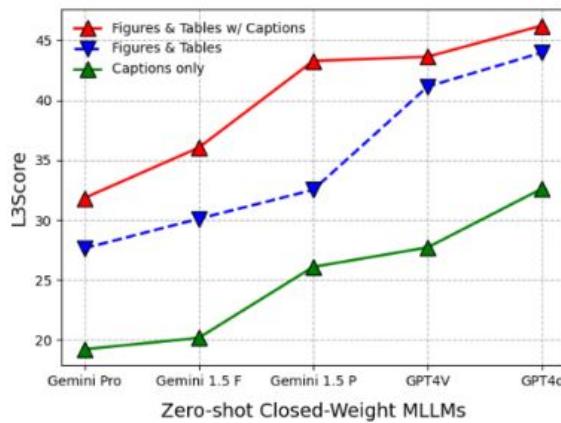
# GPT-4o best on test-A and test-C, Claude-3 tie on test-B

Method	SPIQA test-A					SPIQA test-B					SPIQA test-C				
	M	R-L	C	B-F1	L3S	M	R-L	C	B-F1	L3S	M	R-L	C	B-F1	L3S
<i>Zero-shot Closed-Weight MLLMs</i>															
Gemini Pro Vision [64]	22.9	38.3	124.6	64.87	43.85	9.9	19.0	29.1	54.83	31.84	11.6	19.4	47.8	48.95	31.98
Gemini 1.5 Flash [57]	25.4	38.8	110.9	65.84	54.20	11.5	19.4	24.4	56.32	36.04	14.4	18.1	45.5	48.79	36.67
Gemini 1.5 Pro [57]	23.4	35.5	87.1	64.36	53.49	10.8	19.3	26.8	56.62	43.27	12.6	16.8	40.2	47.51	36.72
Claude 3 (Opus) [2]	25.0	41.5	120.2	65.84	61.26	12.7	19.2	17.0	57.03	49.54	15.5	29.7	92.6	52.35	43.88
GPT-4 Vision [1]	23.1	37.7	113.8	64.01	56.67	12.2	18.8	23.7	55.09	43.62	15.2	22.9	75.5	51.02	40.85
GPT-4o [48]	25.5	42.2	133.7	66.14	64.00	10.7	18.9	31.8	53.73	46.22	15.6	31.3	98.4	53.57	46.68

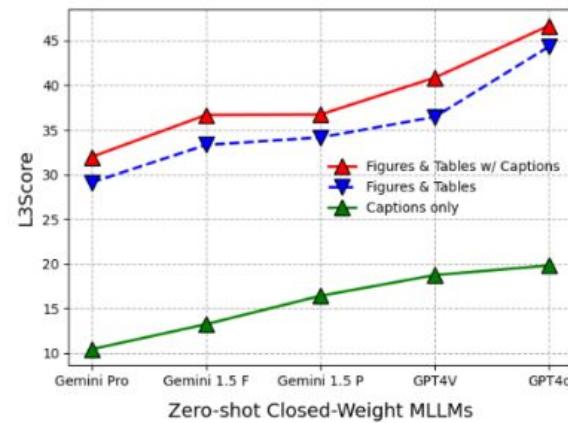
# Figures+Captions > Figures only >> Captions only



(a) Results on **test-A**.



(b) Results on **test-B**.

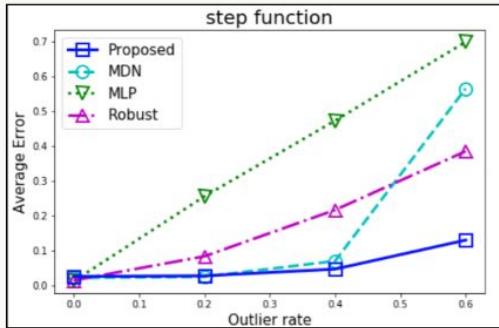


(c) Results on **test-C**.

Figure 3: **Ablation on the importance of captions in the QA task.** All Gemini and GPT variants suffer when captions are omitted. All numbers are for direct QA with figures and tables.

# L3Score correlates well with human intuition

Reference Image



**Question:** Which method has the best performance in terms of average error for the step function?

**Answer:** The proposed method in the paper shows lowest error rate.

**Figure Type:** Plot.

**InstructBLIP**  
Ours. **Correct**

R-L: 0

BERT: 35

L3S: 100

**Gemini 1.5 Flash**  
Proposed method.  
**Correct**

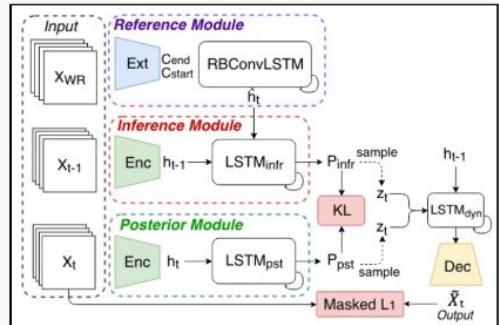
R-L: 100

BERT: 58

L3S: 100

# L3Score correlates well with human intuition

Reference Image



**Question:** What is the difference between the Inference and Posterior modules?

**Answer:** The Inference module is trying to predict the next frame based on the previous frame and the dynamic constraint, while the Posterior module is trying to reconstruct the current frame.

**Figure Type:** Schematic.

## GPT-4V

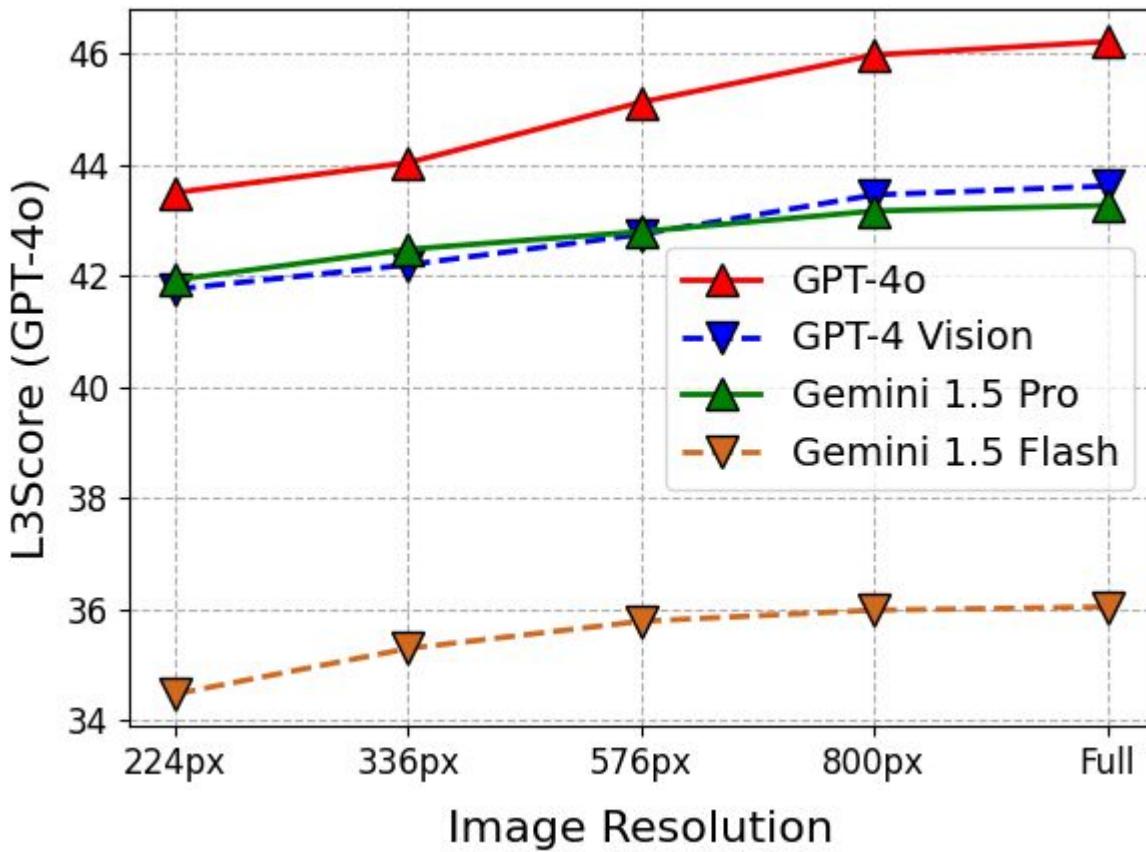
The Inference module takes the previous frame and dynamic constraint, while the Posterior module takes the current frame. This difference results in different output frames. **Almost Correct**

R-L: 37.0

BERT: 65

L3S: 96.9

# Higher resolution $\Rightarrow$ Better performance



# Performance of open source models were a bit mixed

InternLM and LLaVA works good among the open models.

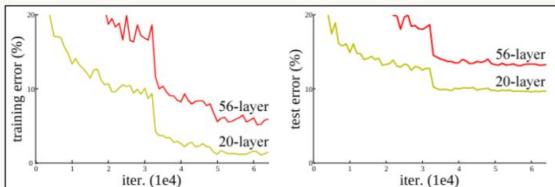
Method	SPIQA test-A					SPIQA test-B					SPIQA test-C				
	M	R-L	C	B-F1	L3S	M	R-L	C	B-F1	L3S	M	R-L	C	B-F1	L3S
<i>Zero-shot Open-Weight MLLMs</i>															
SPHINX-v2 [15]	4.3	17.2	60.5	46.70	7.38	3.8	11.1	12.6	42.19	8.24	1.0	3.3	11.0	8.03	3.32
InstructBLIP-7B [12]	9.5	18.9	62.6	47.70	7.50	3.5	9.5	16.3	39.62	7.07	2.8	15.5	36.6	48.45	8.79
LLaVA-1.5-7B [35]	2.6	34.7	117.8	61.61	13.86	7.7	15.5	16.8	47.21	9.63	7.0	15.1	26.7	45.55	9.53
XGen-MM [58]	17.3	30.6	127.0	58.41	13.74	4.4	8.0	11.1	35.49	8.18	4.2	17.4	46.6	45.25	10.66
InternLM-XC [14]	22.2	29.2	73.7	53.57	18.28	8.1	12.9	16.8	36.00	12.47	8.5	11.4	20.5	34.58	11.84
CogVLM [71]	20.4	27.9	59.2	51.24	16.89	7.9	16.0	26.2	43.93	9.60	9.7	13.9	24.4	42.90	12.52

# Finetuning on SPIQA improves open source model perf.

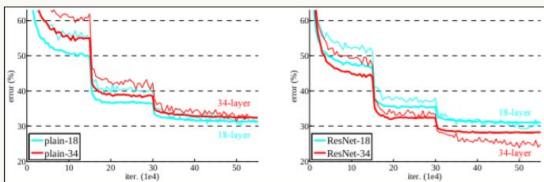
Method	SPIQA test-A					SPIQA test-B					SPIQA test-C				
	M	R-L	C	B-F1	L3S	M	R-L	C	B-F1	L3S	M	R-L	C	B-F1	L3S
<i>Fine-tuned MLLMs</i>															
InstructBLIP-7B [12]	17.8	32.5	110.0	62.10	43.90	8.8	17.2	28.6	52.79	31.82	10.1	22.8	69.8	50.22	33.48
$\Delta_{\text{InstructBLIP-7B FT - ZS}}$	8.3 $\uparrow$	13.6 $\uparrow$	47.4 $\uparrow$	14.40 $\uparrow$	36.40 $\uparrow$	5.3 $\uparrow$	7.7 $\uparrow$	12.3 $\uparrow$	13.17 $\uparrow$	24.75 $\uparrow$	7.3 $\uparrow$	7.3 $\uparrow$	33.2 $\uparrow$	1.77 $\uparrow$	24.69 $\uparrow$
LLaVA-1.5-7B [35]	23.8	36.0	121.2	63.74	45.45	11.0	18.4	29.5	53.13	33.50	10.5	24.1	69.6	50.15	32.40
$\Delta_{\text{LLaVA-1.5-7B FT - ZS}}$	1.2 $\uparrow$	1.3 $\uparrow$	3.4 $\uparrow$	2.13 $\uparrow$	31.59 $\uparrow$	3.3 $\uparrow$	3.1 $\uparrow$	12.7 $\uparrow$	5.92 $\uparrow$	23.87 $\uparrow$	3.5 $\uparrow$	9.0 $\uparrow$	42.9 $\uparrow$	4.60 $\uparrow$	22.87 $\uparrow$

Fine-tuned LLaVA is almost as good as Gemini Pro Vision.  
Train set is useful!

## All Images from the Paper

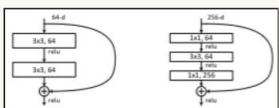


layer name	output size	18-layer	34-layer	50-layer	101-layer	152-layer
conv1	112×112					
conv2_x	56×56			7×7, 64, stride 2		
conv3_x	28×28			3×3 max pool, stride 2		
conv4_x	14×14					
conv5_x	7×7					
		$1.8 \times 10^9$	$3.6 \times 10^9$	$3.8 \times 10^9$	$7.6 \times 10^9$	$11.3 \times 10^9$
FLOPs						

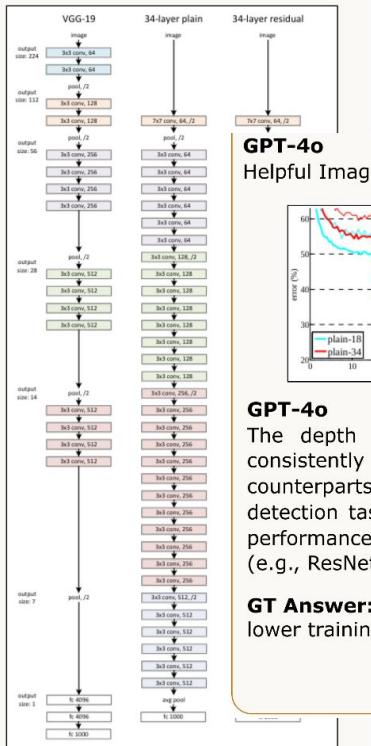


training data	07+12	07+12
test data	VOC 07 test	VOC 12 test
VGG-16	73.2	70.4
ResNet-101	<b>76.4</b>	<b>73.8</b>

metric	mAP@.5	mAP@[.5, .95]
VGG-16	41.5	21.2
ResNet-101	<b>48.4</b>	<b>27.2</b>

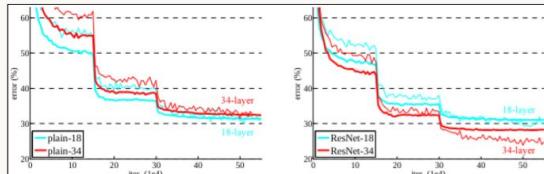


method	top-5 err. (test)
VGG [41] (ILSVRC'14)	7.32
GoogLeNet [44] (ILSVRC'14)	6.66
VGG [41] (v5)	6.8
PRelU-net [11]	4.94
BN-Inception [16]	4.82
ResNet (ILSVRC'15)	<b>3.57</b>



## GPT-4o

Helpful Images: Figure 4 and Table 2. **Correct**



	plain	ResNet
18 layers	27.94	27.88
34 layers	28.54	<b>25.03</b>

## GPT-4o

The depth of residual networks generally improves their performance. Deeper ResNets consistently achieve lower error rates and higher mAP scores compared to their shallower counterparts and non-residual networks. For instance, ResNet-101 outperforms VGG-16 in detection tasks (Image 0 and Image 7), and deeper ResNets (e.g., ResNet-152) show better performance in error rates on ImageNet validation (Image 1). Also, extremely deep ResNets (e.g., ResNet-110 and ResNet-1202) maintain lower errors on CIFAR-10. **Correct**

**GT Answer:** The increased depth of Residual network improves performance of this network, lower training error and make it generalizable to data. It also addresses degradation problem.

R-L: 23.5

BERT: 50.7

LAVE: 9

L3S: 100

**Question:** How does the depth of the residual networks affect their performance in the experiments?

**Input Prompt:** First find which of the input images are helpful to answer the given question, and then answer the question.

# SPIQA

arXiv



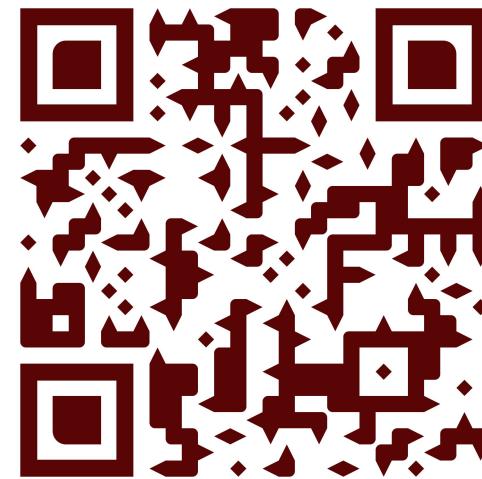
[arxiv.org/abs/2407.09413](https://arxiv.org/abs/2407.09413)

🤗 Hugging Face



[huggingface.co/datasets/google/spiqa](https://huggingface.co/datasets/google/spiqa)

Evaluation Code



[github.com/google/spiqa](https://github.com/google/spiqa)

# Understanding Scientific Literature via Expert-driven QA

[Expert Evaluation of LLM World Models: A High-T  \$c\$  Superconductivity Case Study](#)

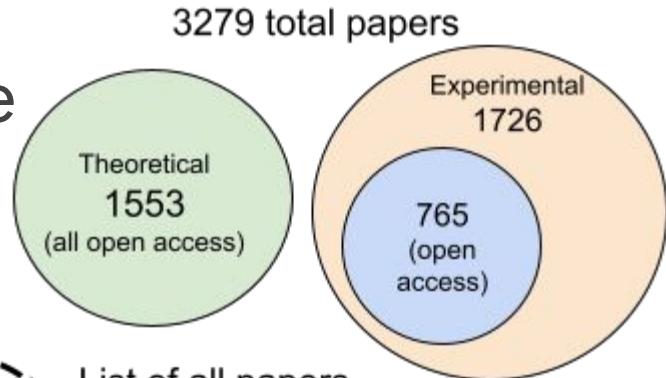
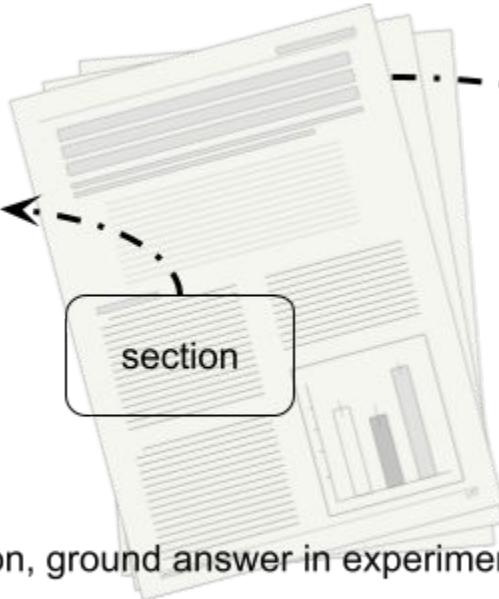
[arxiv.org/abs/2511.03782](https://arxiv.org/abs/2511.03782)

Haoyu Guo, Maria Tikhanovskaya, Paul Raccuglia, Alexey Vlaskin, Christopher Co, Daniel J. Liebling, Scott Ellsworth, Matthew Abraham, Elizabeth Dorfman, N.P. Armitage, John M. Tranquada, Senthil Todadri, Antoine Georges, Subir Sachdev, Steven Kivelson, B. J. Ramshaw, Chunhan Feng, Olivier Gingras, Vadim Oganesyan, Michael Brenner, **Subhashini Venugopalan**, Eun-Ah Kim

# Library of papers in high-temperature superconductivity

## Review articles

Questions based on experimental evidence



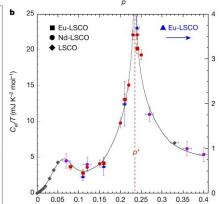
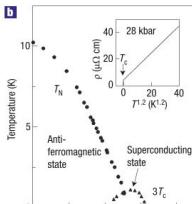
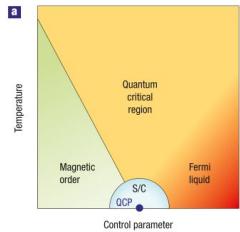
List of all papers referenced.



Task: Given question, ground answer in experimental evidence.

Being able to answer and ground responses in experimental evidence (across years) is a challenge.

# RAG system using image and text embeddings



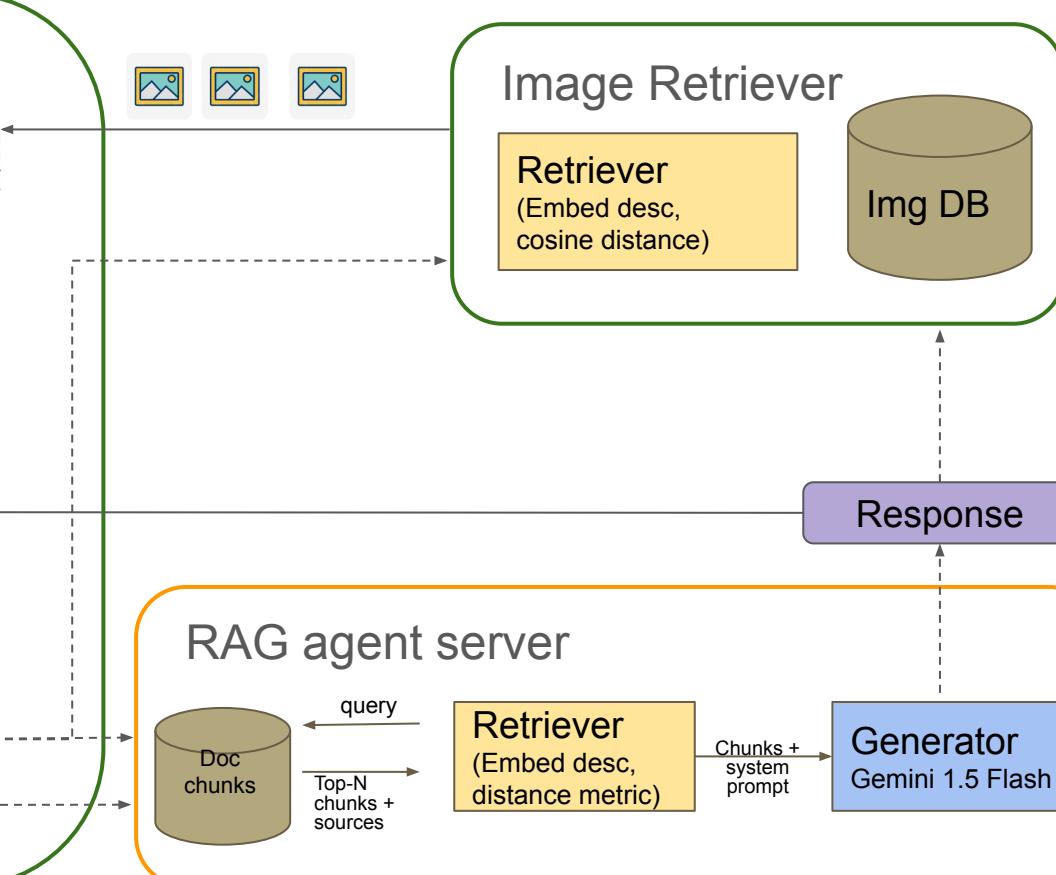
## Answer

Evidence for Quantum Critical Point Scenario in Cuprates. Several lines of evidence support the quantum critical point (QCP) scenario in cuprate superconductors: ...

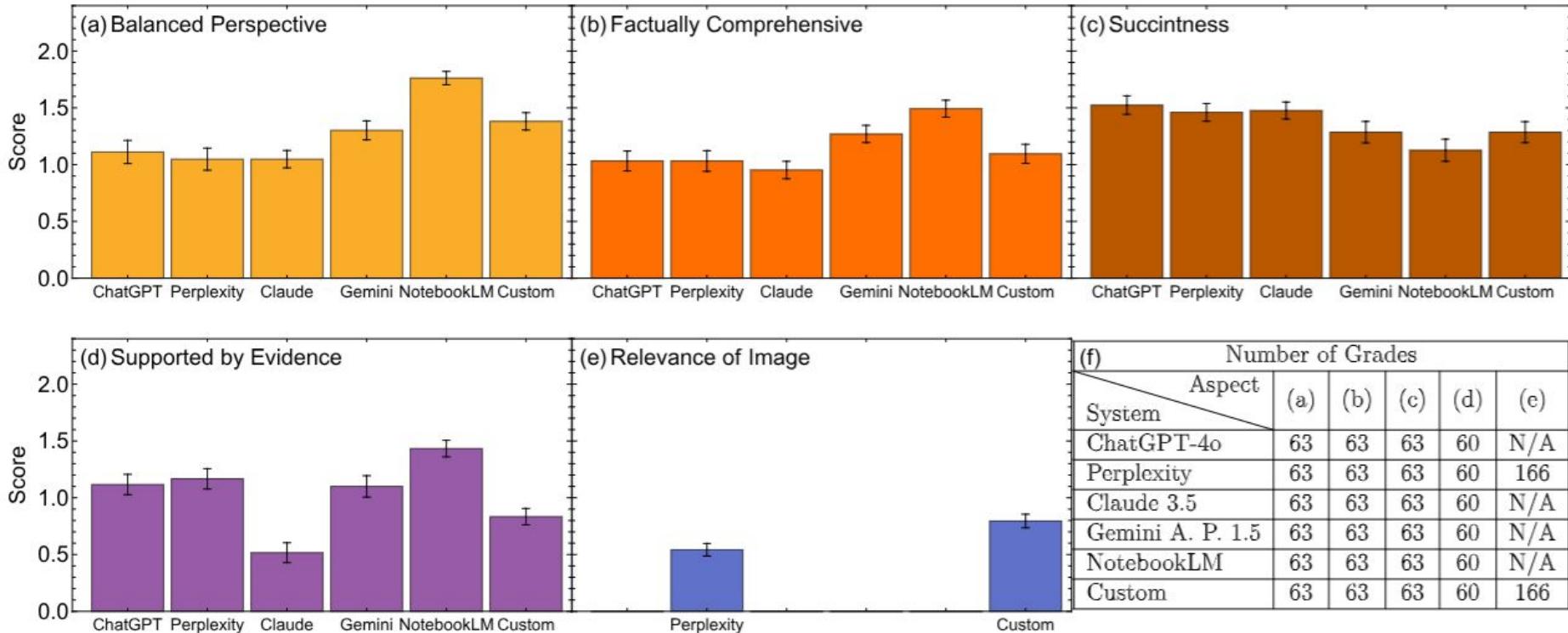
## Query

What is the evidence supporting the quantum critical point scenario of cuprates?

Authentication



# Expert evaluation of systems



# CURIE: Evaluating LLMs On Multitask Scientific Long Context Understanding and Reasoning

Hao Cui<sup>\*1</sup>, Zahra Shamsi<sup>\*1</sup>, Gowoon Cheon<sup>\*1</sup>, Xuejian Ma<sup>1</sup>, Shutong Li<sup>1</sup>, Maria Tikhonovskaya<sup>2</sup>, Peter Norgaard<sup>1</sup>, Nayantara Mudur<sup>2</sup>, Martyna Plomecka<sup>3</sup>,  
Paul Raccuglia<sup>1</sup>, Yasaman Bahri<sup>1</sup>, Victor V. Albert<sup>4,5</sup>, Pranesh Srinivasan<sup>1</sup>, Haining Pan<sup>6</sup>, Philippe Faist<sup>7</sup>, Brian Rohr<sup>8</sup>, Michael J. Statt<sup>8</sup>, Dan Morris<sup>1</sup>,  
Drew Purves<sup>1</sup>, Elise Kleeman<sup>1</sup>, Ruth Alcantara<sup>1</sup>, Matthew Abraham<sup>1</sup>, Muqthar Mohammad<sup>1</sup>, Ean Phing VanLee<sup>1</sup>, Chenfei Jiang<sup>1</sup>, Elizabeth Dorfman<sup>1</sup>,  
Eun-Ah Kim<sup>9</sup>, Michael Brenner<sup>1,2</sup>, Viren Jain<sup>1</sup>, Sameera Ponda<sup>1</sup>, Subhashini Venugopalan<sup>\*^1</sup>  
<sup>1</sup>Google, <sup>2</sup>Harvard, <sup>3</sup>University of Zurich, <sup>4</sup>NIST, <sup>5</sup>UMD College Park, <sup>6</sup>Rutgers, <sup>7</sup>FU Berlin, <sup>8</sup>Modelyst, <sup>9</sup>Cornell  
[{vsubhashini}@google.com](mailto:{vsubhashini}@google.com)

# Can LLMs assist scientists in some workflows?

MIGRATION STUDIES • VOLUME 3 • NUMBER 1 • 2015 • 89–110

89

## Modeling internal migration flows in sub-Saharan Africa using census microdata

Andres J. Garcia<sup>†,‡,§,¶</sup>, Deepa K. Pindolia<sup>†,‡,§,¶</sup>,  
Kenneth K. Lopiano<sup>¶,†,†</sup> and Andrew J. Tatem<sup>†,‡,§,¶,\*\*\*</sup>

<sup>†</sup>Department of Geography, University of Florida, Gainesville, FL, USA; <sup>‡</sup>Emerging Pathogens Institute, University of Florida, Gainesville, FL, USA; <sup>§</sup>Clinton Health Access Initiative, Boston MA, USA; <sup>¶</sup>Department of Statistics, University of Florida, Gainesville, FL, USA; <sup>¶</sup>Statistical and Applied Mathematical Sciences Institute, Research Triangle Park, NC, USA; <sup>¶</sup>Department of Geography and Environment, University of Southampton, Highfield, Southampton, UK; <sup>¶</sup>Fogarty International Center, National Institutes of Health, Bethesda, MD, USA; <sup>\*\*\*</sup>Flowminder Foundation, Karolinska Institute, SE-171 77 Stockholm, Sweden.

\*Corresponding author. Email: andygarcia@gmail.com

### Abstract

Globalization and the expansion of transport networks has transformed migration into a major policy issue because of its effects on a range of phenomena, including resource flows in economics, urbanization, as well as the epidemiology of infectious diseases. Quantifying and modeling human migration can contribute towards a better understanding of the nature of migration and help develop evidence-based interventions for disease control policy, economic development, and resource allocation. In this study we paired census microdata from 10 countries in sub-Saharan Africa with additional spatial datasets to develop models for the internal migration flows in each country, including key drivers that reflect the changing social, demographic, economic, and environmental landscapes. We assessed how well these gravity-type spatial interaction models can both explain and predict migration. Results show that the models can explain up to 87 percent of internal migration, can predict future within-country migration with correlations of up to 0.91, and can also predict migration in other countries with correlations of up to 0.72. Findings show that such models are useful tools for understanding migration as well as predicting flows in regions where data are sparse, and can contribute towards strategic economic development, planning, and disease control targeting.

Can we reproduce the analysis in this study?

Can I apply the same techniques for Europe?

### 1. Introduction

Human population movements are an important component in a wide range of diverse

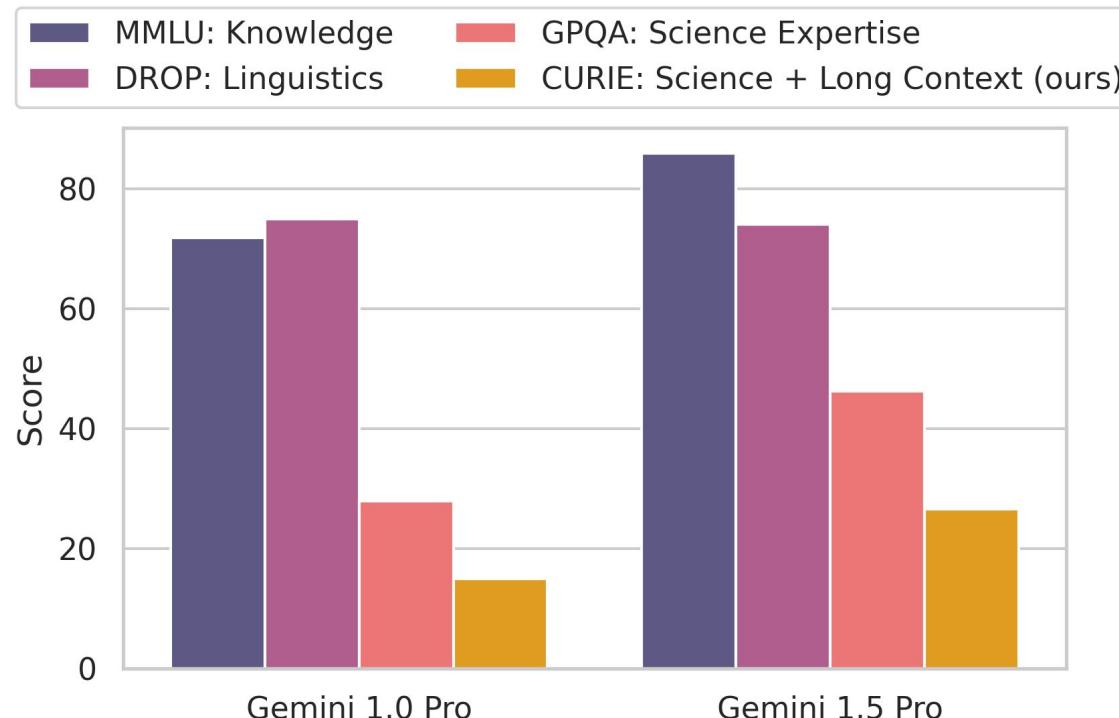
# Can we measure scientific problem-solving ability?

This requires

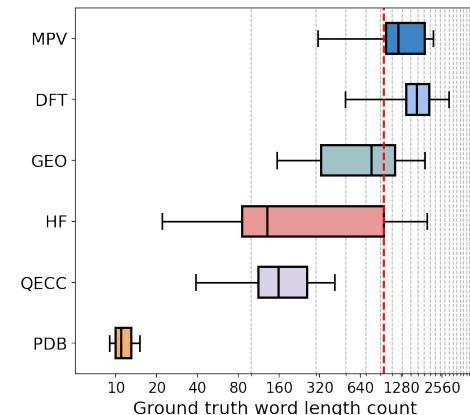
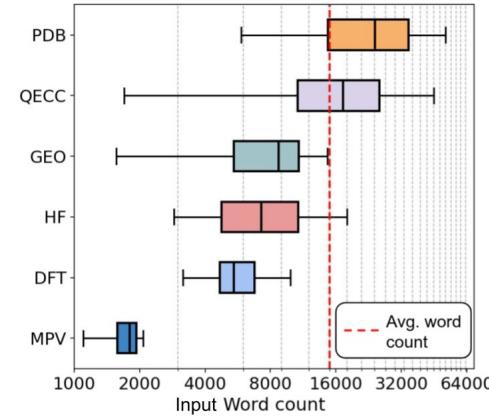
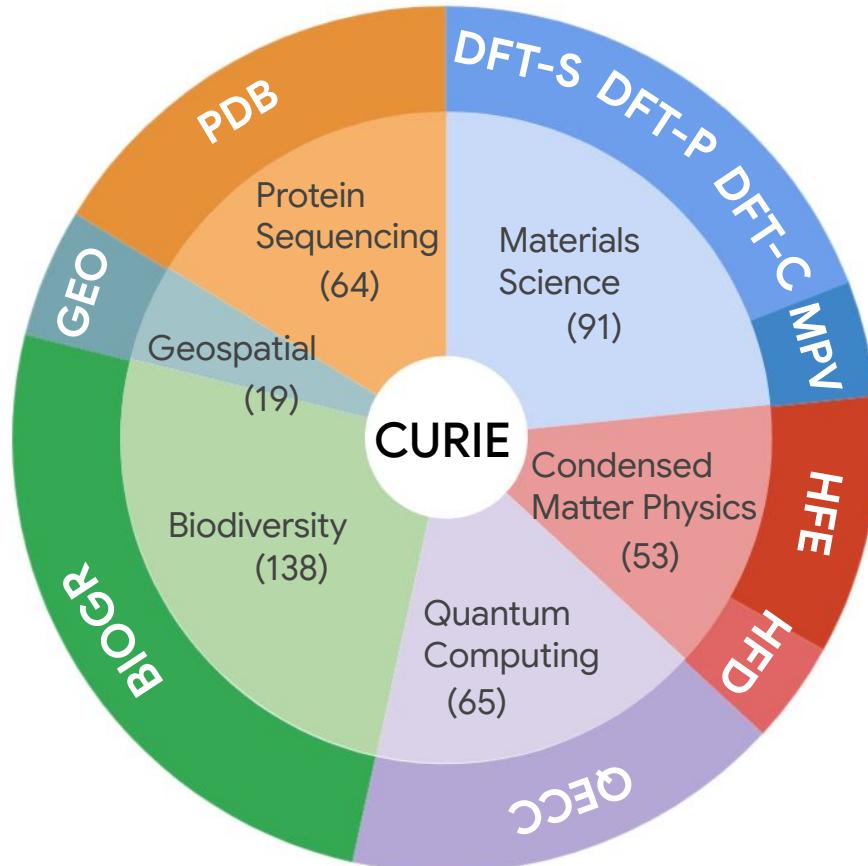
- Knowledge of the domain
- Long-context capabilities
  - to understand context of the problem
- Reasoning ability
  - to apply the knowledge in the context of a given problem

# CURIE: Test scientific problem solving

(scientific long-Context Understanding Reasoning and Information Extraction benchmark)



Avg. 15k words in the input, and 960 words in output



# Example: Materials Science

Given a paper we want to reproduce the DFT calculations done in this paper.

Task	Domain	# Qs	Brief Description
DFT-S	Material Science	74	Extracts input material structures for DFT calculations.
DFT-P	Material Science	74	Extract parameters for DFT calculations.
DFT-C	Material Science	74	Write functional code for DFT computations.
MPV	Material Science	17	Identify all instances of materials, their properties, and descriptors.

Coexistence of Co doping and strain on arsenene and antimonene: tunable magnetism and half-metallic behavior

Yungang Zhou, \* Geng Cheng and Jing Li

Effectively modulating the magnetism of two-dimensional (2D) systems is critical for the application of magnetic nanostructures in quantum information devices. In this work, by employing density functional theory calculations, we found the coexistence of Co doping and strain can effectively control the spin

## Density Functional Theory (DFT)

DFT-S: Identify input structures.

DFT-P: Identify DFT calculations and params.

DFT-C: Write python code for DFT calculations.

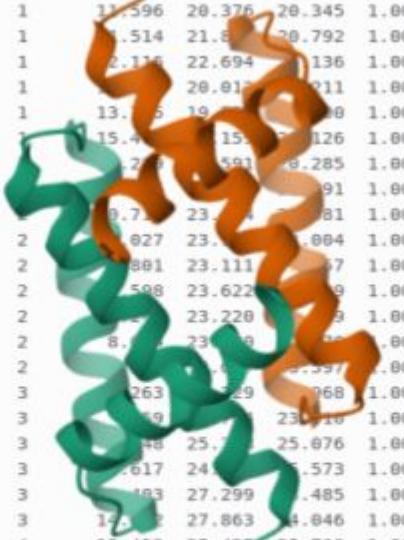
```
"common_name": "arsenene",
"scientific_name": "NaN",
"type": "surface",
"composition": "As2",
"crystal_or_isolated": "surface",
"vacuum": "[0,0,15]",
"supercell": "[4,4,1]",
"cell_size": "NaN",
```

```
"software": "vasp",
"functional": "PBE",
"k-points": "[8,8,1]",
"pseudopotentials": "NaN",
"basis_set": "NaN",
"energy_cutoff": 500.0,
"force_convergence": 0.01,
"energy_convergence": "NaN",
```

```
def get_strained_structures(atoms: Atoms) -> list[Atoms]
strains = np.linspace(0.96, 1.08, 7)
return_list = []
for strain in strains:
    strained_atoms = deepcopy(atoms)
    atoms.cell *= strain
    atoms.positions *= strain
    return_list.append(strained_atoms)
```

# Example: Protein Data Bank

3d protein structure



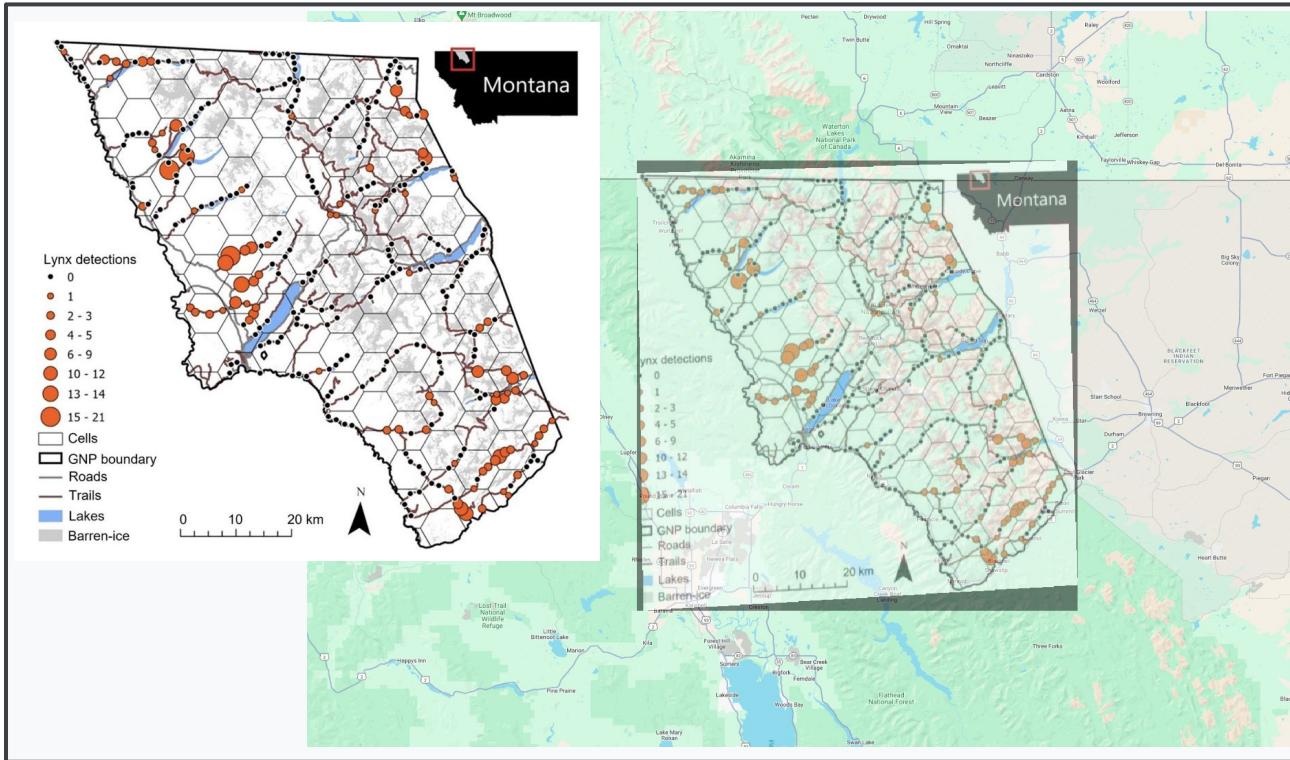
ATOM	1	N	MET	A	1	10.928	26.190	19.023	1.00	39.43	N	
ATOM	7	SD	MET	A	1	11.596	20.376	20.345	1.00	37.11	C	
ATOM	8	CE	MET	A	1	11.514	21.8	20.792	1.00	34.95	C	
ATOM	9	N	ASP	A	1	12.116	22.694	136	1.00	33.33	O	
ATOM	10	CA	ASP	A	1	13.017	20.017	211	1.00	39.22	C	
ATOM	11	C	ASP	A	2	13.155	19.508	108	1.00	40.41	C	
ATOM	12	O	ASP	A	2	15.429	15.57	126	1.00	43.32	O	
ATOM	13	CB	ASP	A	2	12.299	15.593	108	1.00	43.21	C	
ATOM	14	CG	ASP	A	2	12.71	23.174	181	1.00	29.06	C	
ATOM	15	OD1	ASP	A	2	12.027	23.174	108	1.00	25.84	O	
ATOM	16	OD2	ASP	A	2	12.881	23.111	157	1.00	21.31	O	
ATOM	17	N	SEB	A	3	12.598	23.622	149	1.00	33.29	N	
ATOM	18	CA	SEB	A	3	12.59	23.220	139	1.00	37.60	C	
ATOM	19	C	SEB	A	3	12.48	25.1	157	1.00	38.61	C	
ATOM	20	O	SEB	A	3	12.617	24.573	1573	1.00	20.77	O	
ATOM	21	CB	SEB	A	3	12.593	27.299	1485	1.00	20.44	C	
ATOM	22	OG	SEB	A	3	12.592	27.863	14846	1.00	17.38	O	
ATOM	23	N	ASN	A	4	12.423	25.427	15798	1.00	23.65	N	
ATOM	24	CA	ASN	A	4	12.423	25.427	15798	1.00	16.34	C	
ATOM	25	C	ASN	A	4	12.423	25.427	15798	1.00	15.92	C	
ATOM										0	14.27	C

Amino acid sequence



MDSNTVSSFQVDCF<sub>L</sub>WHVRKQVVDQELGDAPFLDRLRRDQKSLRGR  
GSTLGLNIEAATHVGKQIVEKILK

PDB task requires reconstructing a protein's amino acid sequence from the 3D structure.



BIOGR task requires identifying lat./lon. (georeferencing) of a map image.

# CURIE: 10 tasks requiring different capabilities

Task	Domain	# Qs	Brief Description	Capability	Output Format	Primary Eval. metric
DFT-S	Material Science	74	Extracts input material structures for DFT calculations.	entity recognition, concept tracking	JSON	LLMSim-F1
DFT-P	Material Science	74	Extract parameters for DFT calculations.	concept extraction, tracking, aggregation	JSON	LLMSim-F1
DFT-C	Material Science	74	Write functional code for DFT computations.	concept aggregation, coding	TEXT	ROUGE-L
MPV	Material Science	17	Identify all instances of materials, their properties, and descriptors.	entity recognition, concept extraction, tracking	JSON	LLMSim-F1
QECC	Quantum Computing	65	Create a YAML file with the Error Correction Code's properties.	concept aggregation, summarization	YAML	ROUGE-L

# Different kinds of outputs: dicts, equations, text etc.

Task	Domain	# Qs	Brief Description	Capability	Output Format	Primary Eval. metric
HFD	Condensed Matter Physics	64	Derive the Hartree-Fock mean-field Hamiltonian for a quantum many-body system.	concept extraction, algebraic manipulation, reasoning	TEXT	ROUGE-L
HFE	Condensed Matter Physics	19	Extract the most general mean-field Hamiltonian.	concept extraction	TEXT (latex equation)	ROUGE-L
GEO	Geospecial	15	Extract information for all geospatial datasets used along with the spatial and temporal extents.	concept extraction, aggregation	JSON	ROUGE-L
BIOGR	Biodiversity	38	Determine the latitude, longitude bounding box encompassing the region in the map image.	visual comprehension, reasoning	JSON (lat. lon. co-ordinates)	Intersection-over-Union (IoU)
PDB	Protein Sequencing	138	Reconstruct a protein's amino acid sequence form the 3D structure.	tracking, aggregation reasoning	Code or TEXT (seq.)	Identity ratio (IDr)

# Evaluation metrics



## Programmatic

*Doesn't require an LLM e.g. ROUGE-L, IoU*

## LLM-based

*Uses an LLM as a proxy to rate or measure semantic closeness*

# LMScore: Coarse evaluation of outputs

$$LMScore = \sum_{t=0}^2 p(x_t) \times w_t$$

$$x_t \in \{\text{bad, ok, good}\}$$

$$w_t \in \{0, 0.5, 1\}$$

# LLMSim: LLM eval for optimal match b/w list of dicts

$D_G$  A set of ground truth dictionaries

```
[  
  {"material": "Indium Nitride", "property": "band gap"},  
  {"material": "Silicon", "property": "power conversion efficiency"},  
  {"material": "Zinc Oxide", "property": "Direct band gap"},  
]
```

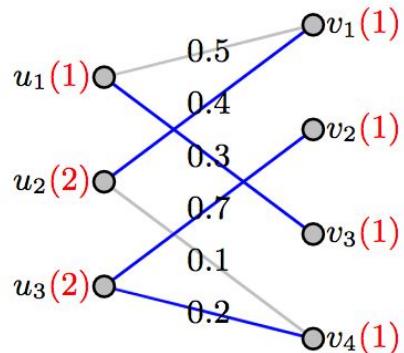
$D_P$  A set of predicted dictionaries

```
[  
  {"material": "ZnO", "property": "Exciton binding energy"},  
  {"material": "Indium nitride", "property": "band gap"},  
  {"material": "Si", "property": "power conversion efficiency\nPCE"},  
  {"material": "ZnO", "property": "band gap"},  
]
```

# LLMSim: LLM eval for optimal match b/w list of dicts

$$\text{LLMSim} = M(D_P, D_g) \quad \text{Match each ground truth record to a predicted record}$$

$$= \begin{cases} \text{None, if no match in values} \\ D_p \in D_P : \arg \max s(f_i, D_p, D_g) \quad \text{Select predicted record most similar to ground truth} \end{cases}$$



# LLMSim: LLM eval for optimal match b/w list of dicts

$$\text{LLMSim} = M(D_P, D_g) \quad \text{Match each ground truth record to a predicted record}$$

$$= \begin{cases} \text{None, if no match in values} \\ D_p \in D_P : \arg \max s(f_i, D_p, D_g) \end{cases} \quad \text{Select predicted record most similar to ground truth}$$

$$Pr = \frac{|(D_p, D_g) \in M|}{|D_P|}, Re = \frac{|(D_p, D_g) \in M|}{|D_G|} \quad \text{Compute Precision and Recall}$$

# LLMSim: LLM eval for optimal match b/w list of dicts

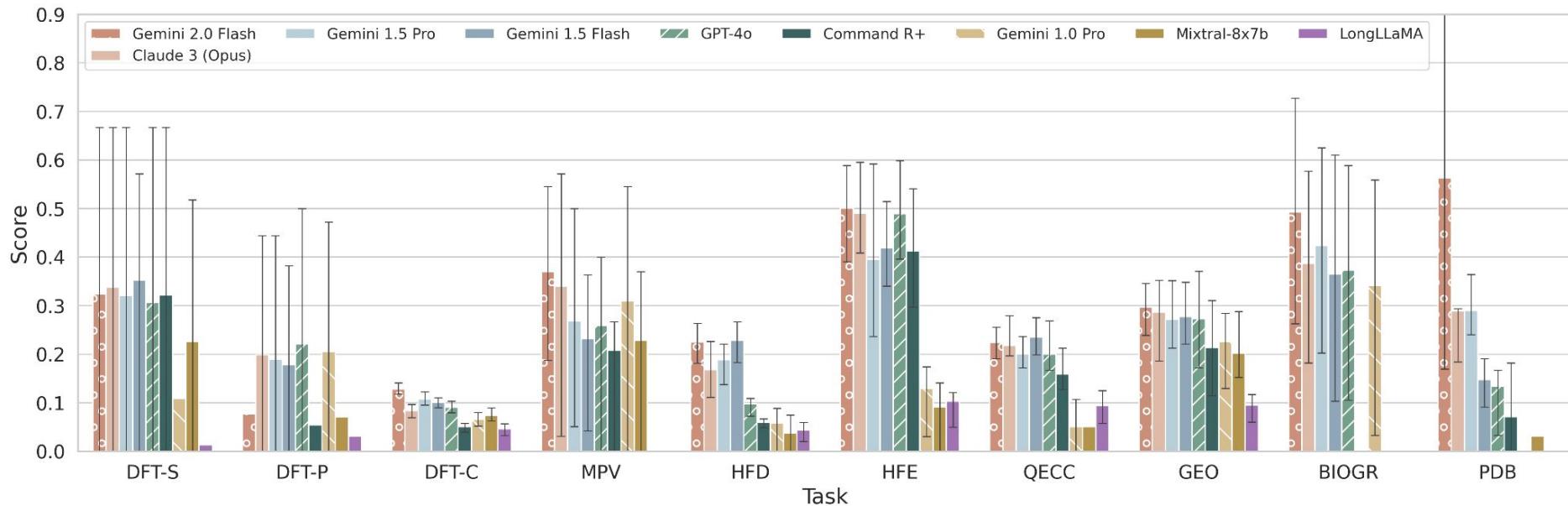
$$\text{LLMSim} = M(D_P, D_g) \quad \text{Match each ground truth record to a predicted record}$$

$$= \begin{cases} \text{None, if no match in values} \\ D_p \in D_P : \arg \max s(f_i, D_p, D_g) \end{cases} \quad \text{Select predicted record most similar to ground truth}$$

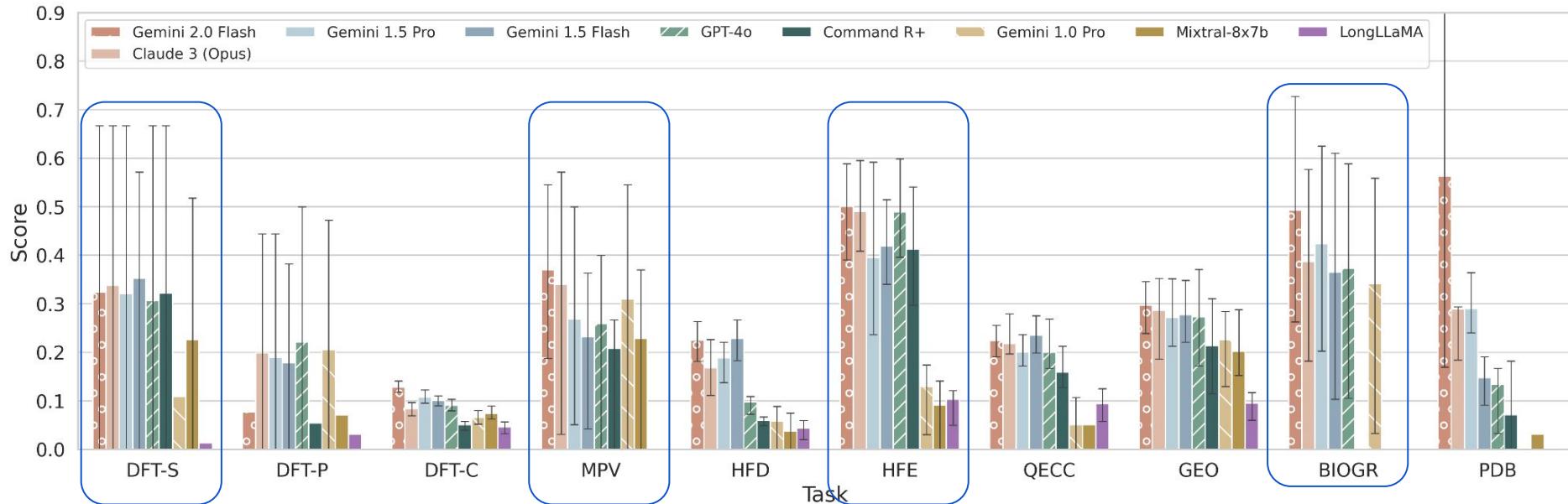
$$Pr = \frac{|(D_p, D_g) \in M|}{|D_P|}, Re = \frac{|(D_p, D_g) \in M|}{|D_G|} \quad \text{Compute Precision and Recall}$$

$$f_1 = \frac{2 \times Pr \times Re}{Pr + Re}, F1_{macro} = \frac{\sum_1^N f_1}{N} \quad \text{Compute f1 score and avg. F1}$$

# Analysis across tasks

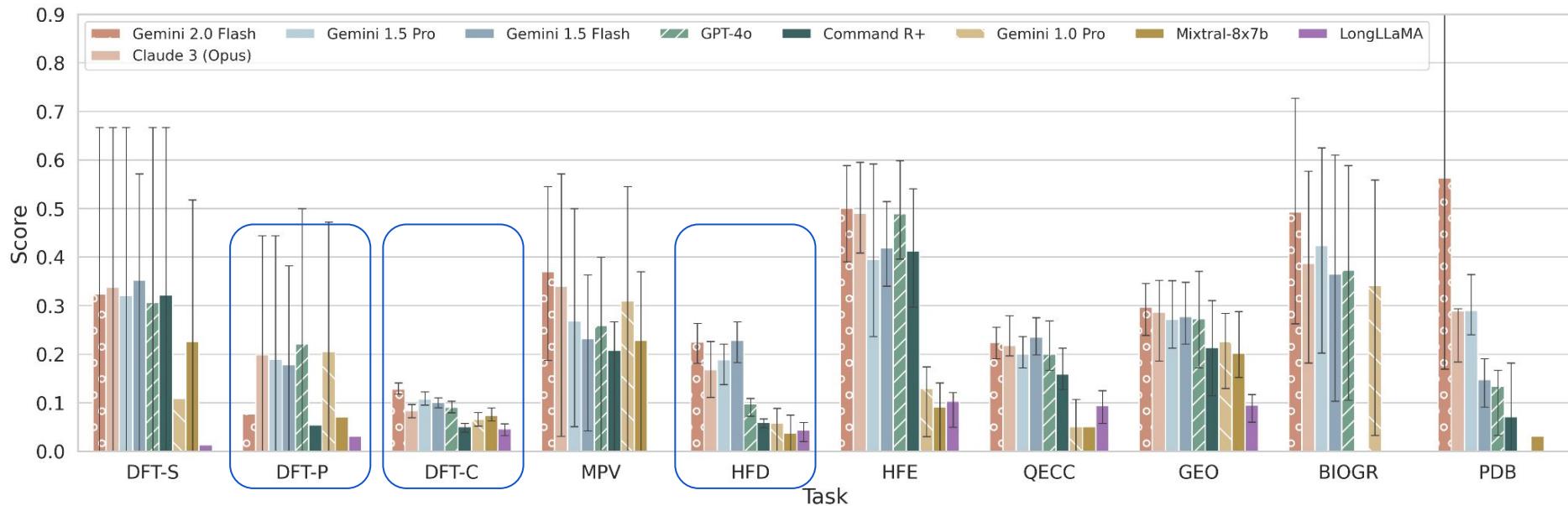


# Frontier models do better on extraction tasks



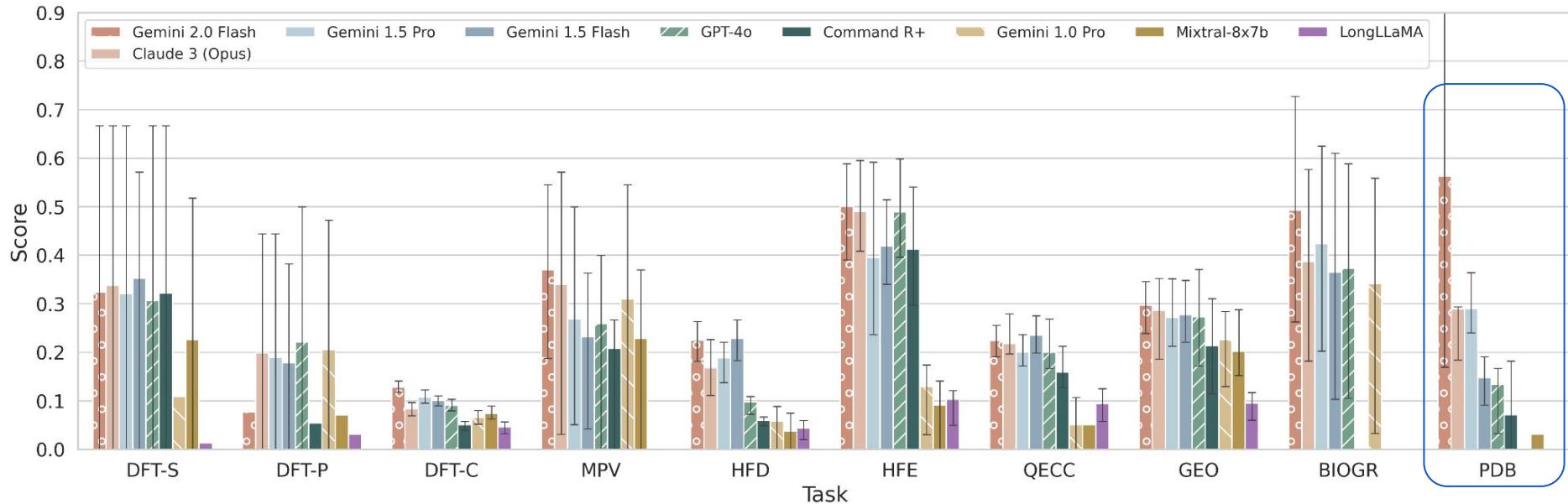
- Extraction tasks (DFT-S, MPV, HFE) and geo-referencing (BIOGR) are easier.

# Reasoning - derivation, aggregation see lower perf.



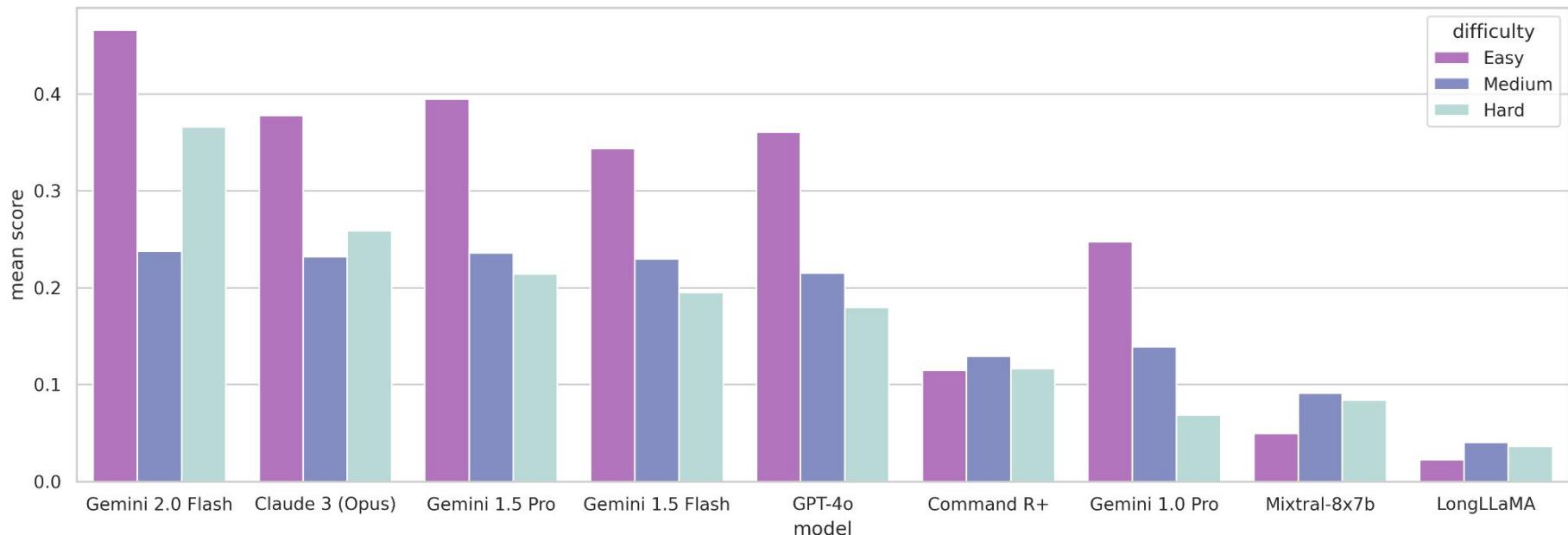
- Extraction tasks (DFT-S, MPV, HFE) and geo-referencing (BIOGR) better perf.
- Reasoning e.g. derivation (DFT-P), aggregation and coding (DFT-C) harder.

# Newer models use code to solve some problems!



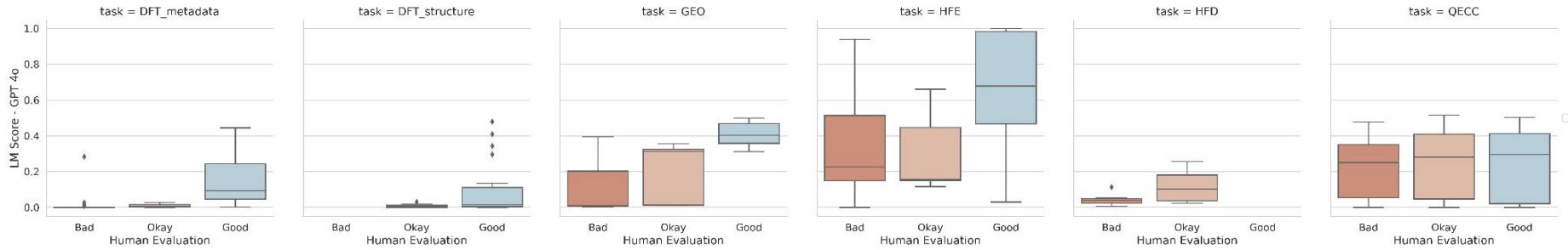
- Gemini Flash 2 decided to generate code for half of the examples for PDB and those were all correct! Other 50% it wrote out the sequence and made mistakes like the other models

# Sliced by difficulty, models do better on easy examples



Experts marked each example as easy, difficult or hard, often based on how spread-out the information required to answer the question is.

# LMScore: Model eval ~ to human eval (bad, okay, good)



$$LMScore = \sum_{t=0}^2 p(x_t) \times w_t \quad (1)$$

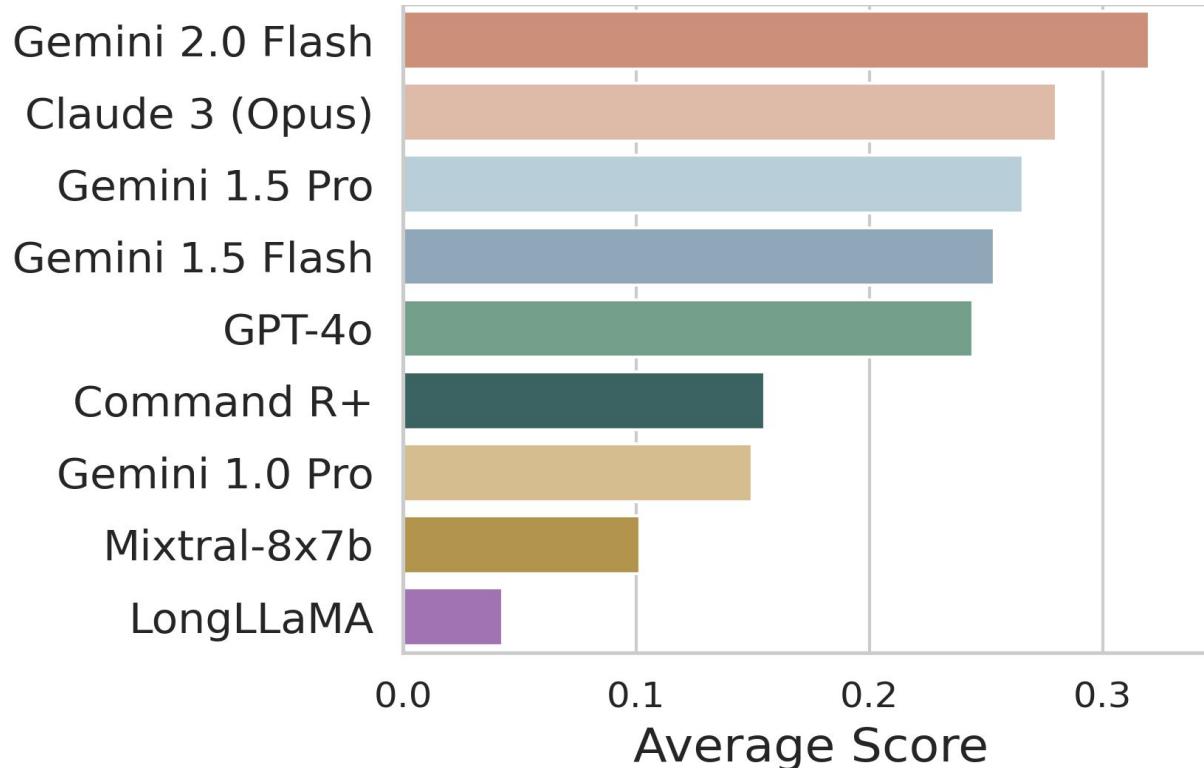
$p(x_t)$  is computed by renormalize the probabilities of the tokens by considering a *softmax()* operation on the log-probabilities of the tokens:  $([l_{bad}, l_{ok}, l_{good}])$ .

# LLMSim for exhaustive retrieval

Model	DFT-S			DFT-P			MPV			MPV-non-trivial			MPV-specific		
	Pr.	Rec.	F1	Pr.	Rec.	F1	Pr.	Rec.	F1	Pr.	Rec.	F1	Pr.	Rec.	F1
<i>Zero-shot Open Weight LLMs</i>															
Mixtral	24.96	23.30	22.67	9.12	6.13	7.09	31.86	23.29	22.82	29.70	21.14	22.31	22.20	35.05	22.64
Command-R+	41.67	27.95	32.19	6.92	4.63	5.41	22.64	27.25	20.80	3.87	6.31	4.52	18.18	17.84	15.97
LongLLaMa	1.26	1.47	1.36	2.99	3.95	3.13	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
<i>Zero-shot Closed Weight LLMs</i>															
Gemini 1.0 Pro	11.19	12.62	10.93	23.1	21.01	20.56	31.28	32.92	31.00	36.41	34.92	31.78	24.86	38.76	23.26
GPT-4o	36.96	29.50	30.63	27.93	19.66	22.13	39.22	24.14	25.90	45.10	24.08	30.05	32.35	21.77	22.97
Gemini 1.5 Pro	36.04	33.67	32.11	23.67	16.53	19.00	23.86	38.36	26.85	31.74	42.60	30.08	25.00	31.34	24.48
Gemini 1.5 Flash	33.07	48.74	35.28	22.35	16.42	17.91	16.41	50.90	23.16	15.82	50.97	21.69	14.77	32.90	17.76
Gemini 2.0 Flash	31.38	40.46	32.39	8.22	7.74	7.68	35.84	46.56	36.99	30.81	47.76	33.79	26.48	33.64	24.37
Claude 3 (Opus)	40.45	32.89	33.76	27.26	17.17	19.87	41.35	35.60	34.04	45.64	43.67	38.32	32.18	47.06	31.48

Table 2: **Retrieval performance using LLMSim** On tasks requiring exhaustive retrieval of information we use LLMSim and compute Precision, Recall, and F1 scores on each document and report the mean. We also include 2 ablations for the MPV task where we ask the LLM to retrieve non-trivial or specific property values (refractive index and optical bandgap) for materials.

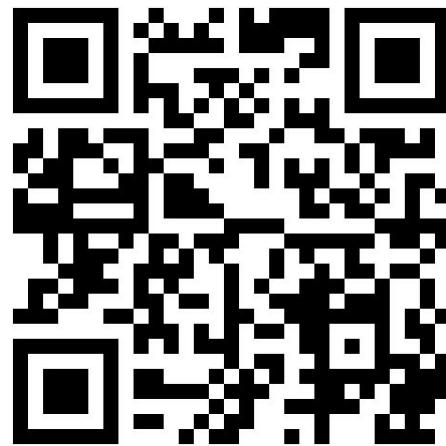
# Highest score 32% – much room for improvement



# CURIE: Data and code on GitHub



[github.com/google/curie](https://github.com/google/curie)



[arxiv.org/abs/2503.13517](https://arxiv.org/abs/2503.13517)

# Thanks!



Zahra  
Shamsi



Gwoon  
Cheon



Jackson  
Cui



Subhashini  
Venugopalan



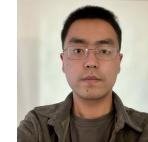
Sameera  
Ponda



Peter  
Norgaard



Shutong  
Li



Xuejian  
Ma



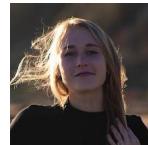
Matthew  
Abraham



Nayantara  
Mudur



Michael  
Brenner



Maria  
Tikhonovskaya



Martyna  
Plomecka



Paul  
Raccuglia



Lizzie  
Dorfman



Yasaman  
Bahri



Dan  
Morris



Drew  
Purves



Elise  
Kleeman



Ruth  
Alcantara



Eun-Ah  
Kim



Phing  
Lee



Chenfei  
Jiang



Viren  
Jain



Muqthar  
Mohammad



Haining  
Pan



Philippe  
Faist



Victor  
Albert



Brian  
Rohr



Michael  
Statt

# FEABench

## Evaluating LLMs on MultiPhysics Reasoning Ability



Nayantara  
Mudur



Jackson  
Cui



Subhashini  
Venugopalan



Paul  
Raccuglia



Michael  
Brenner



Peter  
Norgaard

# Finite Element Analysis



COMSOL Blog

## Modeling the Official Euro 2024 Match Ball



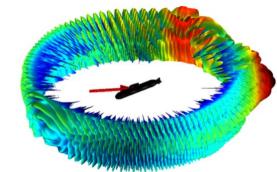
by [Ed Fontes](#)

June 14, 2024

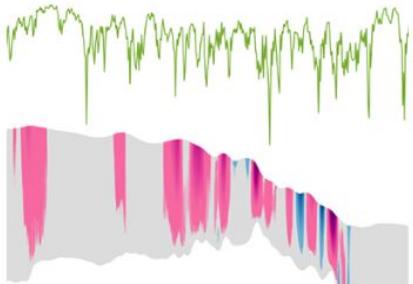
## Submarine Target Strength

Application ID: 90091

The primary defense of a submarine lies in its capacity to remain hidden during operation. As radio waves are strongly absorbed by seawater, sound navigation ranging, or sonar, is one of the main methods used for the detection of submarines. Sonar systems are also used for underwater exploration as well as in the fishing industry.



Designers analyze the way acoustic waves are reflected in order to minimize the equivalent reflecting area of the submarine. The target strength, or TS, is a measure of the area of a sonar target. This tutorial presents a simplified method to analyze the TS of the benchmark target echo strength simulation (BeTTS) benchmark submarine.



## Forecasting the Ice Loss of Greenland's Glaciers with Viscoelastic Modeling

Alfred Wegener Institute, Bremerhaven, Germany

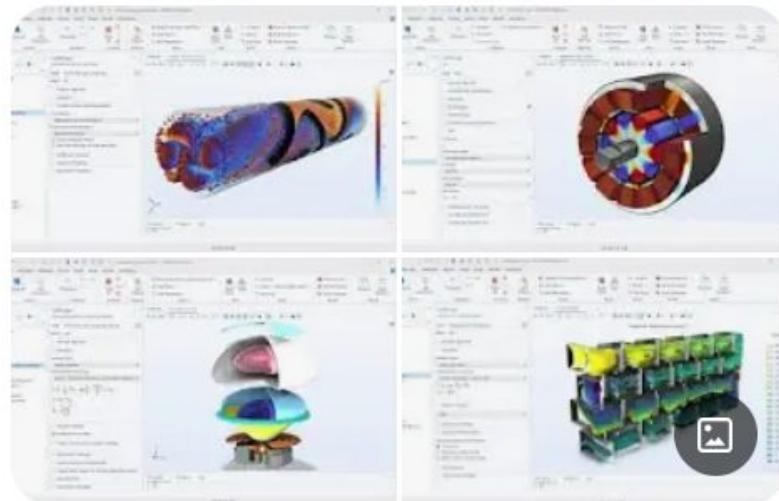
The Northeast Greenland Ice Stream's discharge of ice into the ocean has been accelerating. To help forecast future discharge, researchers at the Alfred Wegener Institute have developed an improved viscoelastic model to capture forces that contribute to glacial flow. [read more](#)

# Finite Element Software

- COMSOL is popular FEA software
- There are other python based software

## COMSOL Multiphysics

Software :



COMSOL Multiphysics is a finite element analyzer, solver, and simulation software package for various physics and engineering applications, especially coupled phenomena and multiphysics. The software facilitates conventional physics-based user interfaces and coupled systems of partial differential equations.

[Wikipedia >](#)

# Skills for solving a problem with COMSOL entail?

- Spatial and Physics reasoning skills
  - How to compose and represent geometries (eg: a cross-section of a cylinder can be represented as a 2D axisymmetric rectangle)
  - Setting boundary conditions
- Instruction Following
  - Correct units
  - Assigning selections to numeric identities correctly
- Code Generation
  - Generate executable code (API calls) in a domain specific language

# Example problem from a tutorial

## **Finite Element Analysis Description: 2D Axisymmetric Steady-State Heat Conduction in a Cylinder**

**ANALYSIS TYPE:** Steady-state heat conduction with axisymmetric geometry.

**GEOMETRY:** \* The domain is a cylindrical section defined by:  
\* Inner radius: 0.02 m \* Outer radius: 0.1 m  
\* Height: 0.14 m

\* The geometry represents a 2D cross-section of this cylinder, with the width corresponding to the difference between the inner and outer cylindrical surfaces.

**LOADING:** \* A constant heat flux of 5e5 W/m<sup>2</sup> is applied to the inner cylindrical surface, between z = 0.04 ...

### **BOUNDARY CONDITIONS:**

\* The outer cylindrical surface, top surface, and bottom surface have a uniform temperature of 273.15 [K].

**MATERIAL PROPERTIES:** \* Thermal conductivity (k): 52 W/(m·K) ...

**OUTPUT:** The analysis should determine the temperature in Kelvins [K] (Kelvins are the default units) at ...

Export the table with the value to OUTPUT\_PATH/output.txt

**SELECTION IDENTITIES:** DOMAINS: \* Thermal Conductivity applies to the entire geometry, all domains, or Domain 1. BOUNDARIES: \* The temperature setting T\0 = 273.15 [K] applies to Boundaries 2, 5 and 6. \* The constant heat flux applies to Boundary 3.

**TARGET DESCRIPTION:** Temperature at the location R = 0.04 m, Z = 0.04 m in K.

# Data: Took problems from tutorials

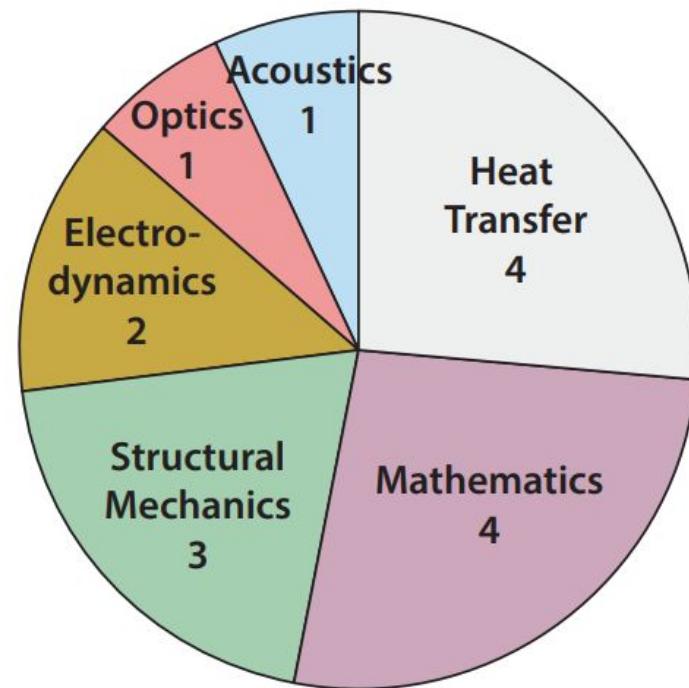
## Input data

- 15 Problem descriptions
- Model Definition
- Modeling Instructions

## Output

- .mph files which are  
COSMOL JAVA API  
[Ground truth code]
- **A single numerical solution** when solved

FEABench Gold



# Setup

Input: Problem Description



LLM / LLMAgent:

Agent Target Output:  
COMSOL JAVA API Code

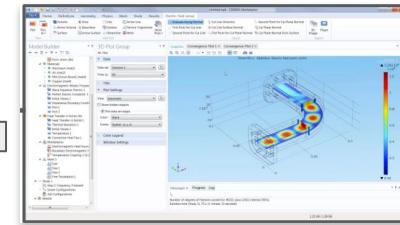
Derived Artifacts generated upon  
executing LLM Output



COMSOL Sandbox

Evaluation

Sandbox Replies / Error  
Messages



```
% Model: Untitled.mph
% Version: COMSOL 6.1.0.357
% Date: Jul 31 2024, 00:05
% Table: Table 2 - Global Evaluation 1
% Time (s) State variable u (1)
1 1.6618884492995585
```

\* Target Value saved in a File \*

# Agents

- One-shot prompt
- Agent with Physics documentation in context
- Multi-turn agent. Has access to
  - Sandbox for execution
  - Tools to query properties from the API
  - RAG to retrieve relevant code snippets
  - Option to do self-improvement and debug code
    - I.e. can retry with feedback

# Evaluation metrics



## Code structure

*Is it calling the right methods?*

*Is it using the right kinds of arguments?*

## Code execution

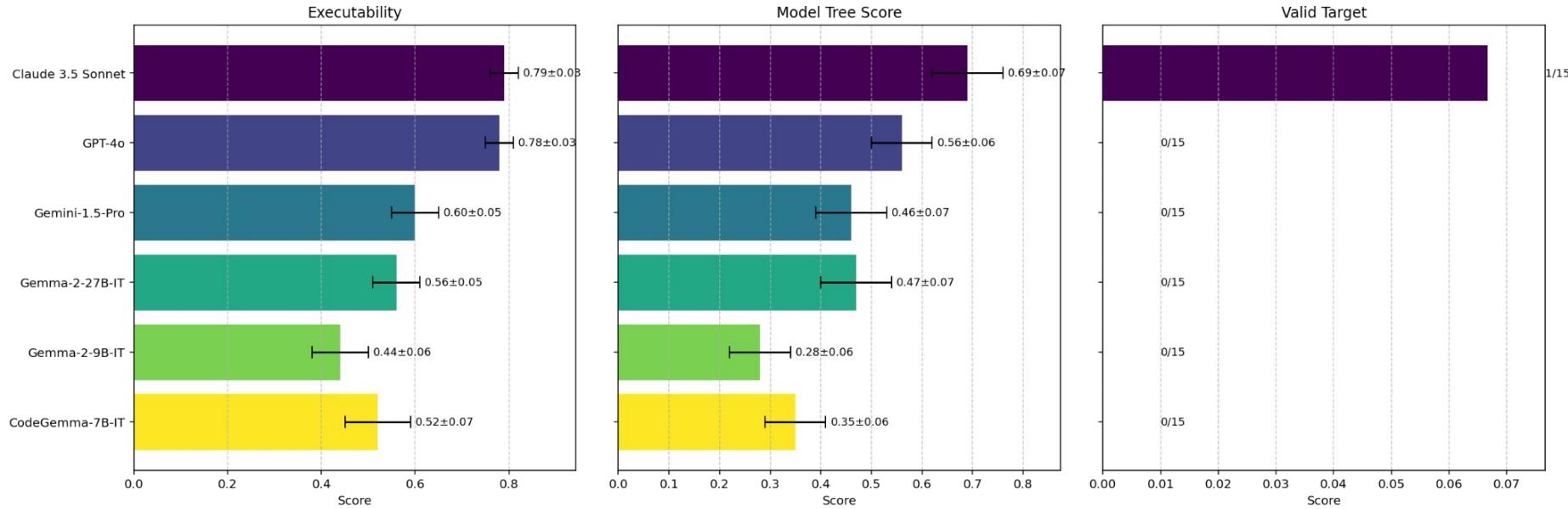
*Is the code bug-free?*

*Progress: At what stage does it break?*

Table 5: Code Metrics: Comparison across tasks, prompts and agents.

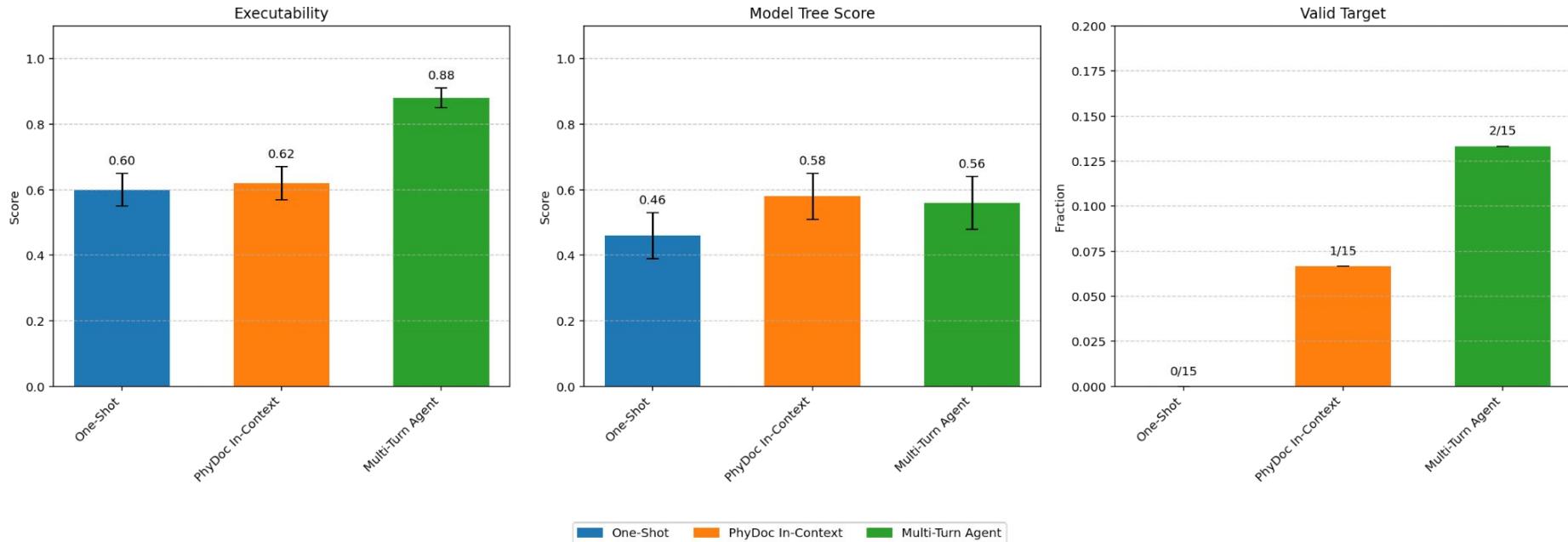
Experiment	Executability	Model Score	Tree	Code Similarity	Valid Target
<b>ModelSpecs</b> : One-Shot	$0.60 \pm 0.05$	$0.46 \pm 0.07$	$0.17 \pm 0.03$	0/15	
<b>ModelSpecs</b> : PhyDoc In-Context	$0.62 \pm 0.05$	$0.58 \pm 0.07$	$0.15 \pm 0.02$	1/15	
<b>ModelSpecs</b> : Multi-Turn Agent	<b><math>0.88 \pm 0.03</math></b>	$0.56 \pm 0.08$	$0.17 \pm 0.03$	<b>2/15</b>	

# Claude 3.5 Sonnet solves 1 / 15 problems



Claude 3.5 and GPT-4o are better than most

# Multi-turn agent solves 2 / 15 problems



# The Cloud-Based Geospatial Benchmark: Challenges and LLM Evaluation

Jeffrey A. Cardille<sup>\*1,2</sup>, Renee Johnston<sup>1</sup>, Simon Ilyushchenko<sup>1</sup>, Zahra Shamsi<sup>1</sup>, Johan Kartiwa<sup>1</sup>, Matthew Abraham<sup>1</sup>, Khashayar Azad<sup>4</sup>, Nuala Caughey<sup>2</sup>, Emma Bergeron Quick<sup>2</sup>, Karen Dyson<sup>5</sup>, Andrea Puzzi Nicolau<sup>5</sup>, Fernanda Lopez Ornelas<sup>6</sup>, David Saah<sup>6</sup>, Michael Brenner<sup>1,3</sup>,  
Sameera Ponda<sup>1</sup>, Subhashini Venugopalan<sup>1</sup>

<sup>1</sup>Google, <sup>2</sup>McGill University, <sup>3</sup>Harvard University, <sup>4</sup>Concordia University, <sup>5</sup>Spatial Informatics Group, <sup>6</sup>University of San Francisco

**Terrabytes @ ICML 2025**

# What is Google Earth Engine?

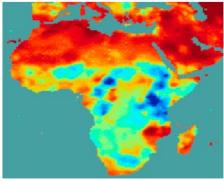
Standardized collection of geospatial data  
(more than 100PB!)

Landsat MODIS Sentinel API Docs

Datasets tagged temperature in Earth Engine ▾

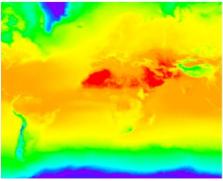
Filter list of datasets

SPEIbase: Standardised  
Precipitation-Evapotranspiration  
Index database, Version 2.8



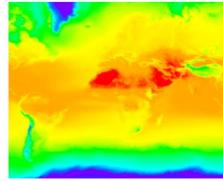
The Global SPEI database (SPEIbase) offers long-time robust information about drought conditions at the global scale, with a 0.5 degree pixel size and monthly cadence. It provides SPEI time scales from 1 to 48 months. The Standardized Precipitation-Evapotranspiration Index (SPEI) expresses, as a standardized variate for

ERA5 Daily Aggregates - Latest  
Climate Reanalysis Produced by  
ECMWF / Copernicus Climate



ERA5 is the fifth generation ECMWF atmospheric reanalysis of the global climate. Reanalysis combines model data with observations from across the world into a globally complete and consistent dataset. ERA5 replaces its predecessor, the ERA-Interim reanalysis. ERA5 DAILY provides aggregated values for each day for

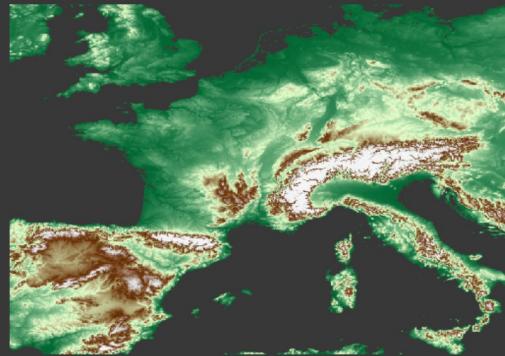
ERA5 Monthly Aggregates - Latest  
Climate Reanalysis Produced by  
ECMWF / Copernicus Climate



ERA5 is the fifth generation ECMWF atmospheric reanalysis of the global climate. Reanalysis combines model data with observations from across the world into a globally complete and consistent dataset. ERA5 replaces its predecessor, the ERA-Interim reanalysis. ERA5 MONTHLY provides aggregated values for each month for

Computational power + API  
to make sense of that data at scale.

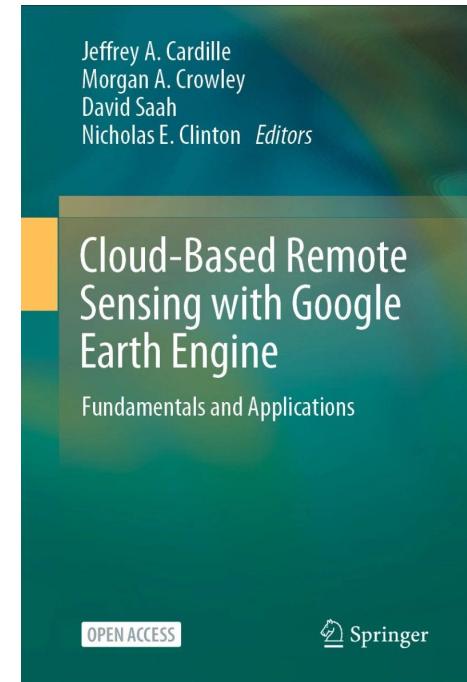
```
# Import the USGS ground elevation image.  
elv = ee.Image('USGS/SRTMGL1_003')  
  
# Make pixels with elevation below sea level transparent.  
elv_img = elv.updateMask(elv.gt(0))  
  
# Display the thumbnail of styled elevation in France.  
Image(url=elv_img.getThumbURL({  
    'min': 0, 'max': 2000, 'dimensions': 512, 'region': roi,  
    'palette': ['006633', 'E5FFCC', '662A00', 'D8D8D8', 'F5F5F5']}))
```



# Benchmark of cloud-based geo-spatial problems

Assignments from ***Cloud-Based Remote Sensing with Google Earth Engine*** [Book, [www.eefabook.org](http://www.eefabook.org)]

- The book is available online (LLMs are trained on it), but the answers are not.
- Partnered w/ Editors / Authors
- Experts and students wrote answers to textbook questions and developed additional questions



# Example benchmark question and answer

## Easy: Calculating Iron Oxide Ratio (IOR) for Hydrothermal Rock Detection

Objective : You are tasked with calculating the Iron Oxide Ratio (IOR), which is the ratio of the red band reflectance to the blue band reflectance. This ratio can help detect hydrothermally altered rocks that contain oxidized iron-bearing sulfides. Complete the following steps:

- Focus on this point in Seattle, WA, USA: (-122.2040, 47.6221).
- Access the COPERNICUS/S2\_HARMONIZED ImageCollection and select images that:
  - Cover the Seattle point,
  - Are from 2020-08-15 to 2020-10-01, and
  - Have less than 10% cloud coverage.
- Select the earliest image from that set.
- Identify the red band and blue band that surround the following wavelengths: Red band, 665 nm; Blue band, 490 nm.
- Compute the IOR. Extract the calculated IOR value at the given Seattle point. Print the IOR value to the console.

Notes: Ensure band values (e.g., radiance, temperature) are scaled to their proper units prior to use. Reflectance values should be scaled to between 0 and 1 prior to use. Retrieve values at the native scale of the imagery. Write the answer to 3 decimal points of precision (e.g, 12345.678)

```
# EBA_F2.0_A2
# Calculating Iron Oxide Ratio (IOR) for Hydrothermal Rock Detection
seattle_point = ee.Geometry.Point([-122.2040, 47.6221])

sentinel = ee.ImageCollection('COPERNICUS/S2_HARMONIZED') \
    .filterDate('2020-08-15', '2020-10-01') \
    .filterBounds(seattle_point) \
    .filter(ee.Filter.lt('CLOUDY_PIXEL_PERCENTAGE', 10)) \
    .first()

red = sentinel.select('B4')
blue = sentinel.select('B2')

ior = red.divide(blue).rename('IOR')

ior_value = ior.reduceRegion(
    reducer=ee.Reducer.first(),
    geometry=seattle_point,
    scale=10
).get('IOR')

print('IOR', ior_value.getInfo())

IOR 0.9936675461741424
```

# Example of domains and skills exercised in the book

Identify which US states have greatest amounts of **impervious surfaces in floodplain areas**

Calculate **Urban Heat Islands** in New Haven

Forecast **malaria** in Ethiopia using precipitation, temperature, and a vegetation water index data

## SECTION A1: HUMAN APPLICATIONS

### **A1.1 Agricultural Environments**

Sherrie Wang and George Azzari

### **A1.2 Urban Environments**

Michelle Stuhlmacher and Ran Goldblatt

### **A1.3 Built Environments**

Erin Trochim

### **A1.4 Air pollution and population exposure**

Zander Venter and Sourangsu Chowdhury

### **A1.5 Heat Islands**

TC Chakraborty

### **A1.6 Health Applications**

Dawn Nekorchuk

### **A1.7 Humanitarian Applications**

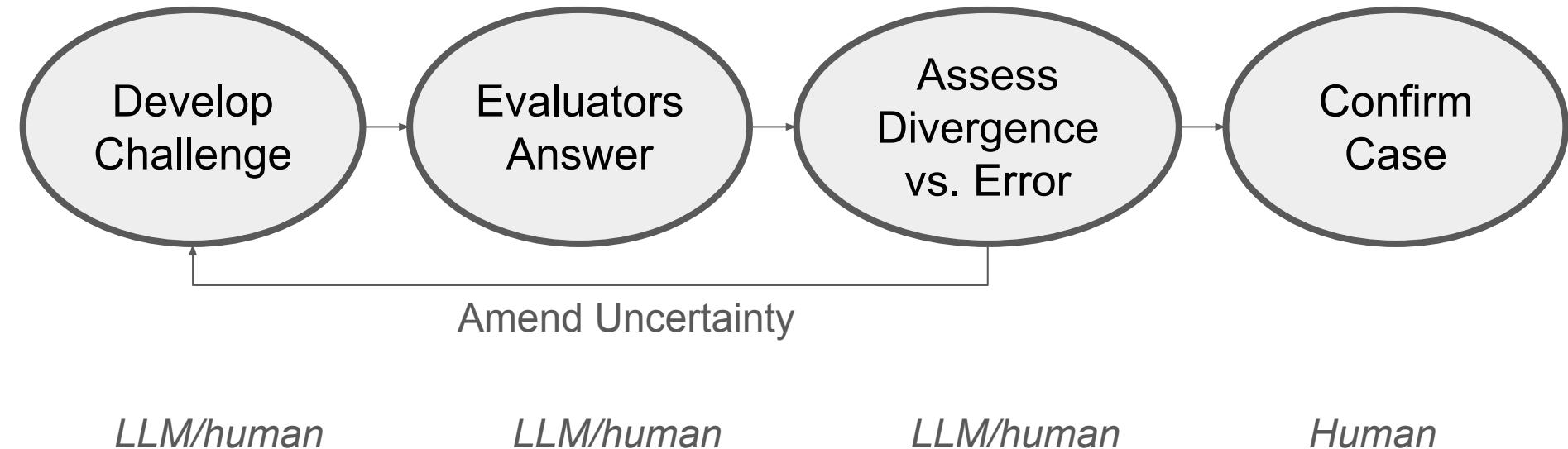
Jamon Van Den Hoek and Hannah Friedrich

## **Conceptual design of problems**

1. Testing a classroom of 'students'
2. Exam to create maps and measures
3. Requiring an automatic objective assessment

## **Problems must be tightly constrained but still interesting**

1. Constrained questions: only correct work  $\Rightarrow$  correct answer
2. Refined repeatedly to reduce verbal ambiguity while retaining realistic tone
3. Solutions may use Earth Engine or any other software



# Experiment Setup

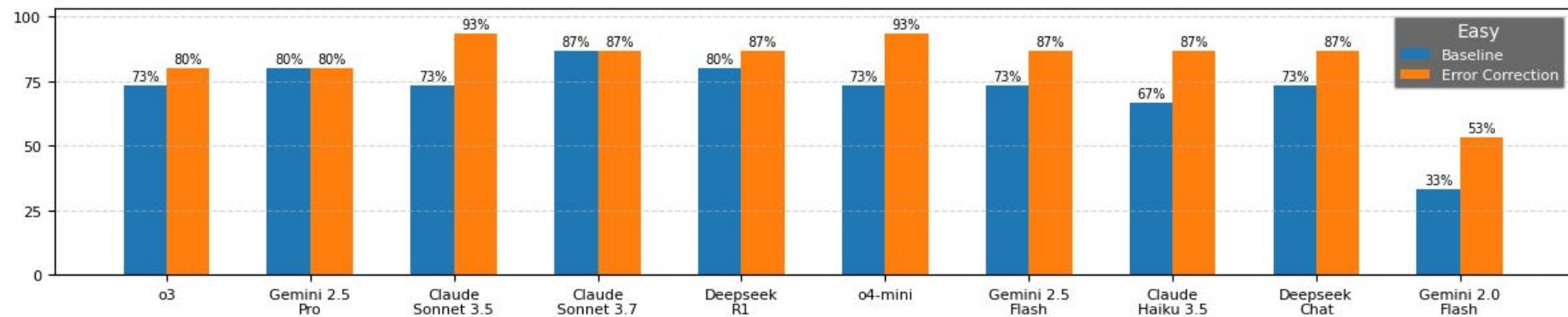
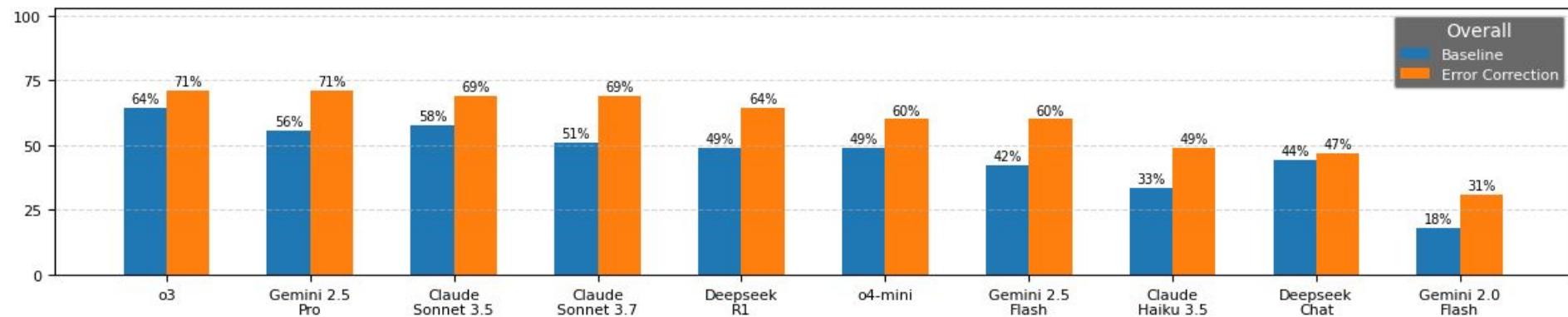
## Evaluation

- All problems have a numeric answer.
- Answers must match solution.

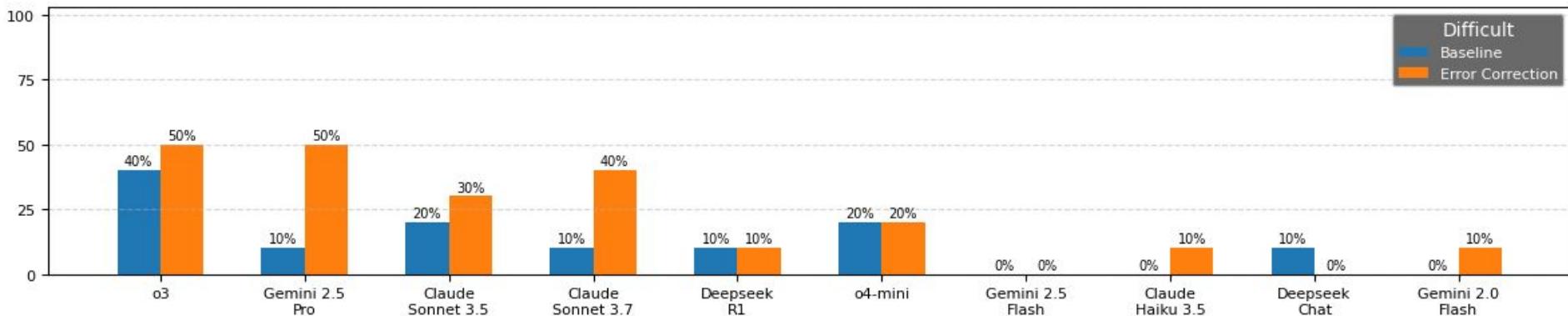
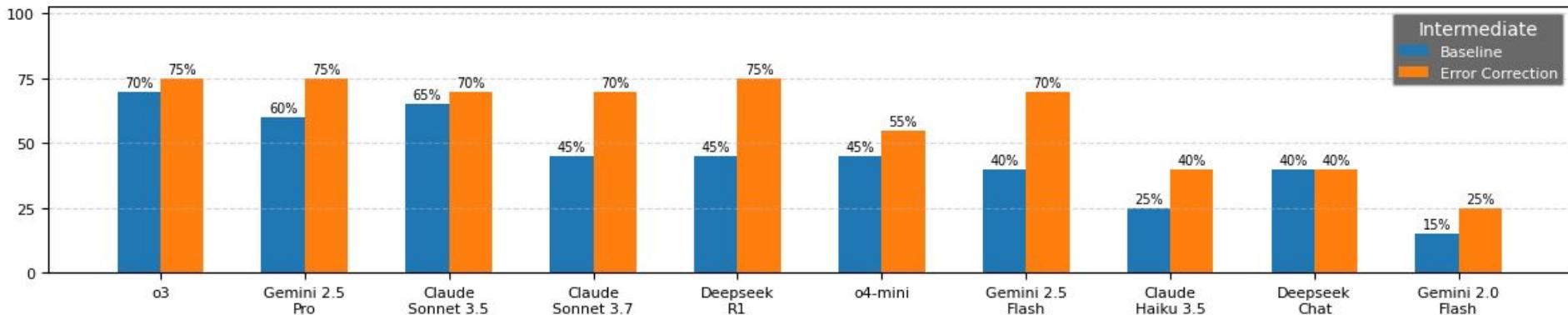
## Variants

- **Base model:** Gets one shot at generating the code.
- **Error-correction:** Models have access to code.
- execution and can correct errors up to 3 reruns.

# Results (overall, and sliced by difficulty)



# Results (overall, and sliced by difficulty)



# Difficult: Deforestation Rate Comparison in Colombian Amazon Protected Areas

**Objective :** This problem will compare the total deforestation assessed to have occurred within and around two protected areas in the Colombian Amazon: **La Paya** and **Tinigua**:

- Use the "WCMC/WDPA/current/polygons" data set to identify the boundaries of the La Paya and Tinigua protected areas. Add a 1000m buffer around each protected area's geometry for the analysis of each area .
- Calculate the forest loss within each protected area using the *lossyear* band of the GFC dataset, where each pixel indicates the year of deforestation. Use the Global Forest Change dataset ([UMD/hansen/global\\_forest\\_change\\_2023\\_v1\\_11](#)).
- Consider areas with tree cover greater than 30% in the year 2000.
- Determine the absolute value of the difference in total deforestation amounts between the area within and around La Paya and the area within and around Tinigua between 2001 and 2023.
- Provide the answer in hectares.

## Notes:

- Unless directed otherwise, retrieve or summarize value(s) at the native resolution of the image band(s). If multiple bands or sensors are used with different resolutions, retrieve or summarize values using the finest resolution among the inputs unless directed otherwise.
- Unless directed otherwise, write the answer to 3 decimal points of precision (e.g, 12345.678).

# Findings

- **Realistic Challenges are Constructible:** The benchmark demonstrates that a set of realistic, scaled challenges can be created, mimicking real-world user queries while minimizing ambiguity. And the benchmark is **not saturated**.
- **Error Correction is Effective:** Error correction consistently improved model performance across all models, often boosting "lightweight" models to the level of more powerful ones operating without correction.
- **Benchmark Informs Domain-Specific Improvements:** The iterative process of refining challenges to remove uncertainty-derived divergence revealed that errors stemmed from incorrect decision-making, poor data awareness, and syntax errors, suggesting areas for improvement.
- **Uncertainty has Different Flavors:** Two types of uncertainty were identified: general imprecision in high-level questions and missing but crucial details for repeatability (e.g., specific cloud masking parameters). These lessons **are transferable** when creating new datasets.

# Agenda

- Multimodal
- Long-context
- Agentic

- 01 Overview
- 02 Grounding responses in paper figures
- 03 Long-context retrieval and reasoning evals
- 04 Tool-use simulation software code
- 05 Multimodal Accessibility Applications

# Overall key takeaways

- SPIQA
  - multimodal long-context benchmark
  - Questions can be improved with newer models
- CURIE
  - Long-context (single paper) science benchmark
  - Much room for improvement
- FEA Bench
  - A challenging framing of the problem
- Overall
  - Create benchmarks with domain experts
  - finding ways to make good evaluation metrics is hard
  - Must be easy to eval and hard to solve



# Speech Recognition with LLMs Adapted to Disordered Speech Using Reinforcement Learning

<https://arxiv.org/abs/2501.00039>

Chirag Nagpal, Subhashini Venugopalan, Jimmy Tobin, Marilyn Ladewig, Katherine Heller, Katrin Tomanek

# Project Euphonia

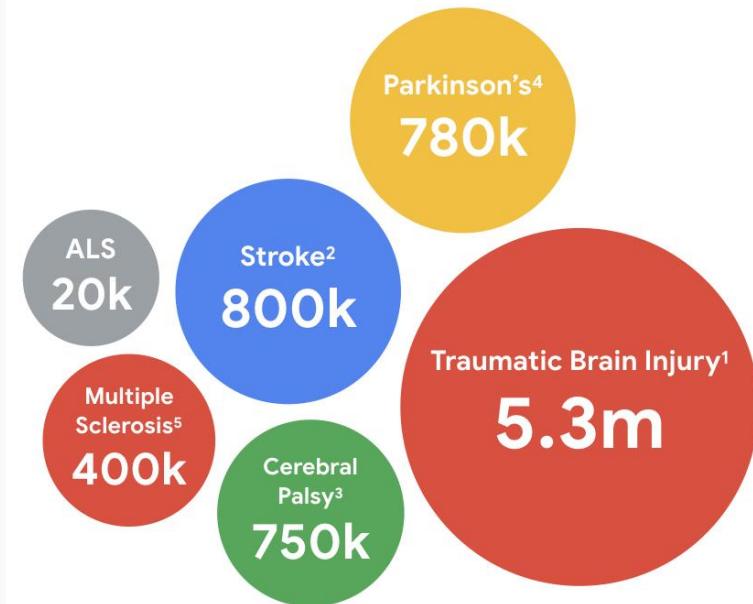
Improve ASR to help people with **speech disorders** who have difficulty being understood by other people and technology.

Our goal is to help these users **communicate and gain independence.**

<https://sites.research.google/euphonia/about/>

## Condition prevalence (US)

Millions of users have neurological conditions that cause speech impairments, in the US and around the world.



# Project Relate - Personalize their on-device ASR model

LISTEN - Keeping the network informed YVONNE

me better. Even when I went to Barbados, my cousin came online as a. Thank you for letting me understand, you better Don't always be a positive. Yes, is sad, always unfortunate, not that it is unfortunate that I have this condition but I'm going to keep it.

Stop

0:15 / 1:21

Watch later Share

Google

# Project Relate - Personalize their on-device ASR model



What project are you working on?  
from different backgrounds. It's not only embarrassing.  
It's nothing to be ashamed of.  
It's about talking and sharing.  
What do you think relate to  
the title? The stuff I was  
just going to help you with.  
Oh yes, amazing. So it's not  
embarrassing for the person  
for

Stop

# Can mLLMs help recognize impaired speech?



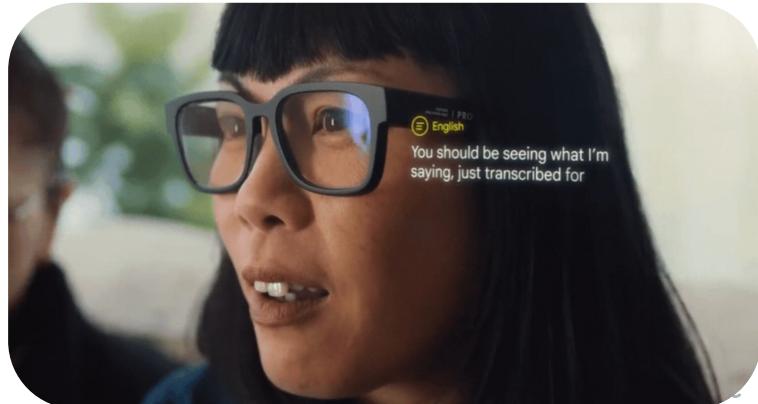
+



(image+speech)

Gemini

→ “I'd like a croissant”



# Can start with open source text-only LLMs?

- LLMs already have a lot of world knowledge.
- Can we add speech inputs?
- Small model / on-device



+

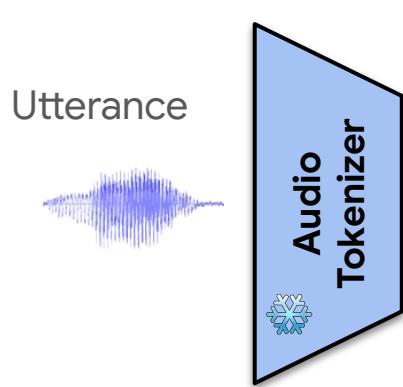


Gemma

→ “I'd like a croissant”

# How do you turn an LLM into an ASR model?

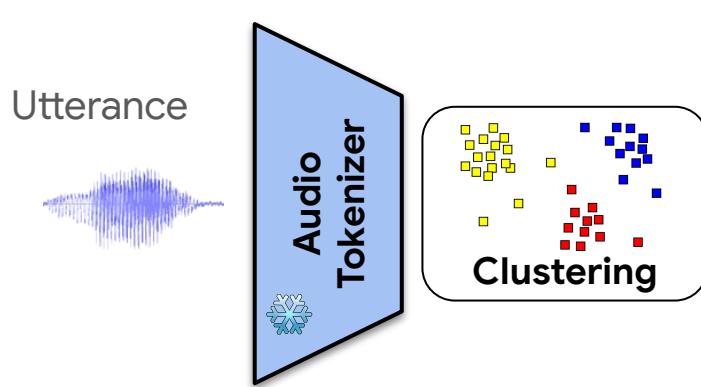
## Tokenization of the audio



# How do you turn an LLM into an ASR model?

## Tokenization of the audio

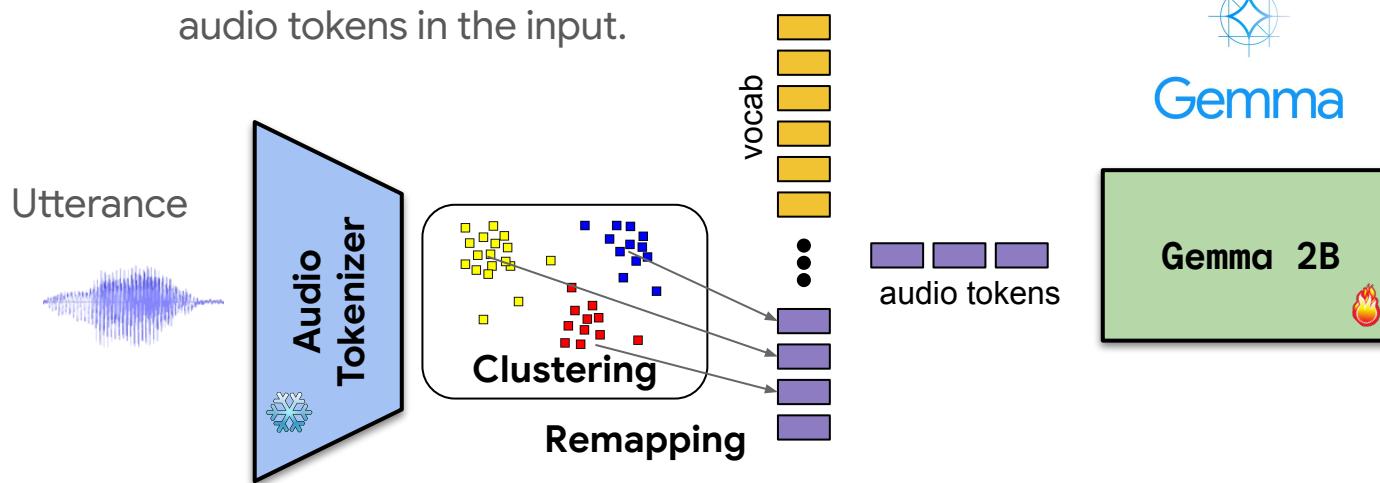
- We cluster embeddings to 1024 tokens from the Librispeech Corpus.



# How do you turn an LLM into an ASR model?

## Tokenization of the audio

- We cluster embeddings to 1024 tokens from the Librispeech Corpus.
- We remap the Gemma Vocab to use the audio tokens in the input.

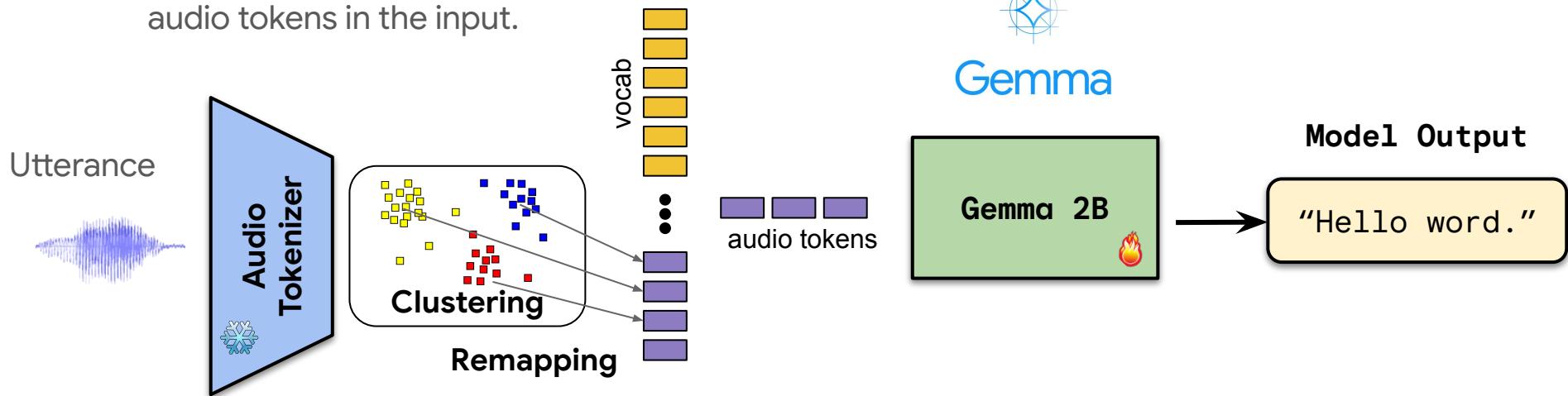


Specifically replace the low-frequency tokens

# How do you turn an LLM into an ASR model?

## Tokenization of the audio

- We cluster embeddings to 1024 tokens from the Librispeech Corpus.
- We remap the Gemma Vocab to use the audio tokens in the input.



*Now this is an ASR model!*

Specifically replace the low-frequency tokens

# Let's train it.

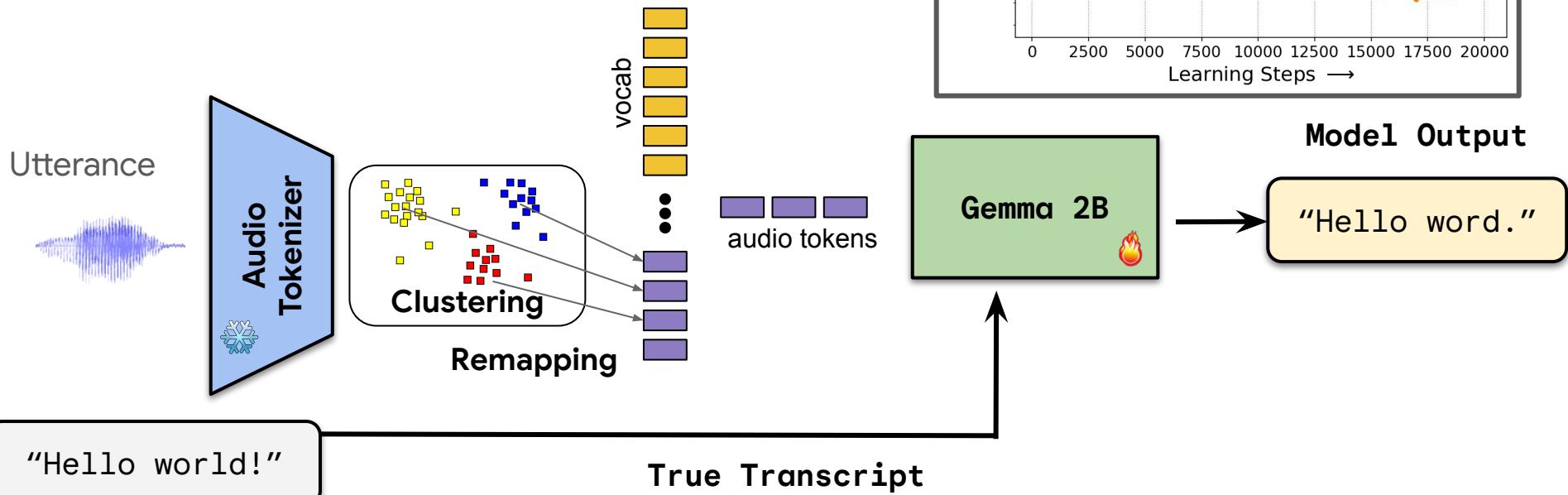
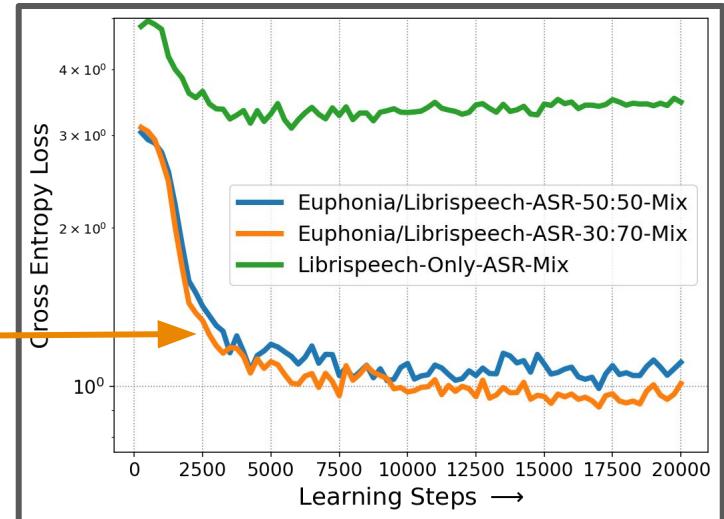
- First train on Librispeech
  - Librispeech: 1000 hrs of audio from books
- Then adapt to disordered speech
  - Euphonia also ~1000 hrs of prompted audio
  - **Training:** 900k utterances, 1246 speakers
  - **Test:** 5699 utterances, 200 speakers



# Supervised Fine Tuning

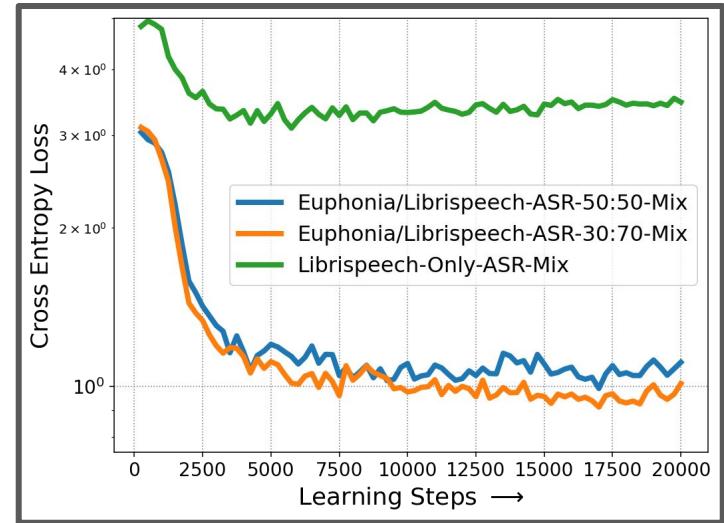
## Mixture of Librispeech and Euphonia Audio

- Augmenting the SFT mixture with ASR data gives generalizes better to disordered speech.



# How well does it work?

TABLE I: Training the LLM on ASR data with a 30:70 mix of Euphonia:Librispeech leads to significant (\*) improvements on Euphonia and little loss on Librispeech.  $\uparrow$  and  $\downarrow$  indicate higher or lower is better respectively. **bold** shows best score.

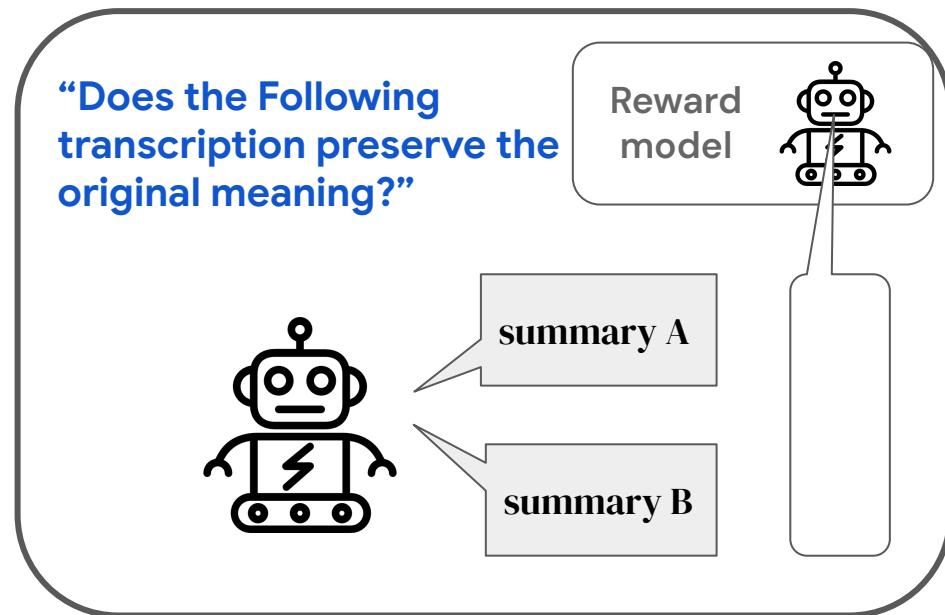


Dataset mixture	Euphonia Test		Euphonia Dev		Librispeech Dev	
	WER $\downarrow$	MP $\uparrow$	WER $\downarrow$	MP $\uparrow$	WER $\downarrow$	MP $\uparrow$
Librispeech Only	70.9	39.0	66.5	31.8	<b>17.1</b>	<b>86.6</b>
30:70 mixture	<b>50.4*</b>	<b>48.2*</b>	<b>47.3*</b>	<b>48.1*</b>	17.2	85.6

Can RL can help generalize further than SFT on  
Disordered Speech Data?

# We need a reward

- Can meaning preservation be a reward?



# Example: Meaning preservation as reward

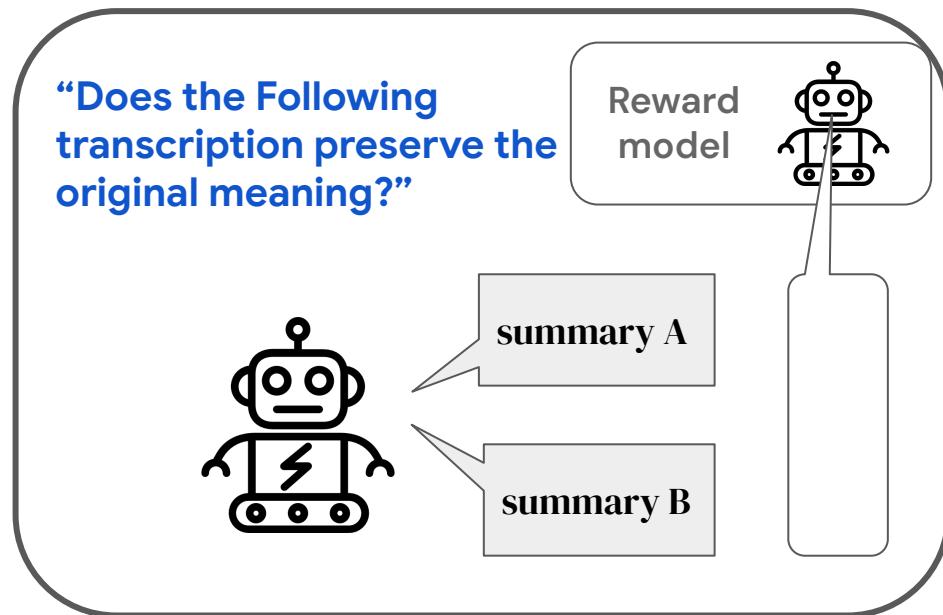
Insight: **High word errors can still preserve meaning !**

Ground Truth: **“Not so good today”**

Output A: **“not so good to the.”**

Output B: **“not so good to day.”**

Both have same same WER, but B Preserves Meaning.



# Meaning preservation as a reward

Conferences > ICASSP 2024 - 2024 IEEE Inter... [?](#)

## Large Language Models As A Proxy For Human Evaluation In Assessing The Comprehensibility Of Disordered Speech Transcription

Publisher: IEEE

[Cite This](#)



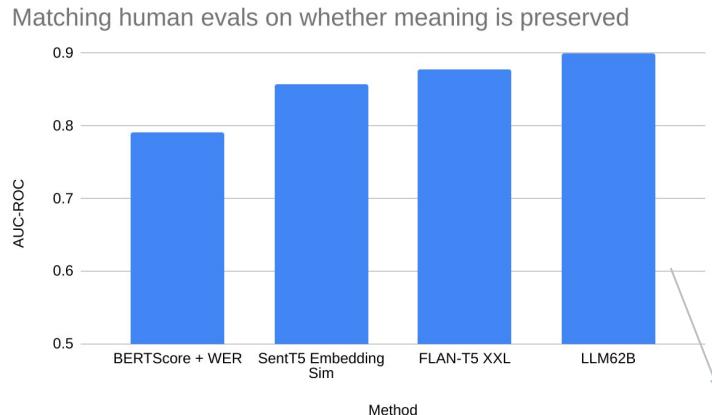
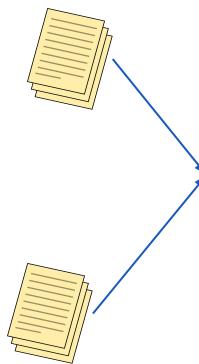
Katrin Tomanek ; Jimmy Tobin ; Subhashini Venugopalan ; Richard Cave ; Katie Seaver ; Jordan R. Green [All Authors](#)

in ICASSP 2024

# Meaning preservation as a reward

Train models to predict human labels of whether meaning was preserved

**GROUND  
TRUTH**



Is meaning  
preserved?

 ASR Transcript

Prompt-tuned LLM does best  
(+ case-study on model deployment of  
SI-ASR vs personalized)

This work: we retrain Gemma 2B as a reward model achieving AUC ~0.88

# Using Meaning Preservation as a Reward signal

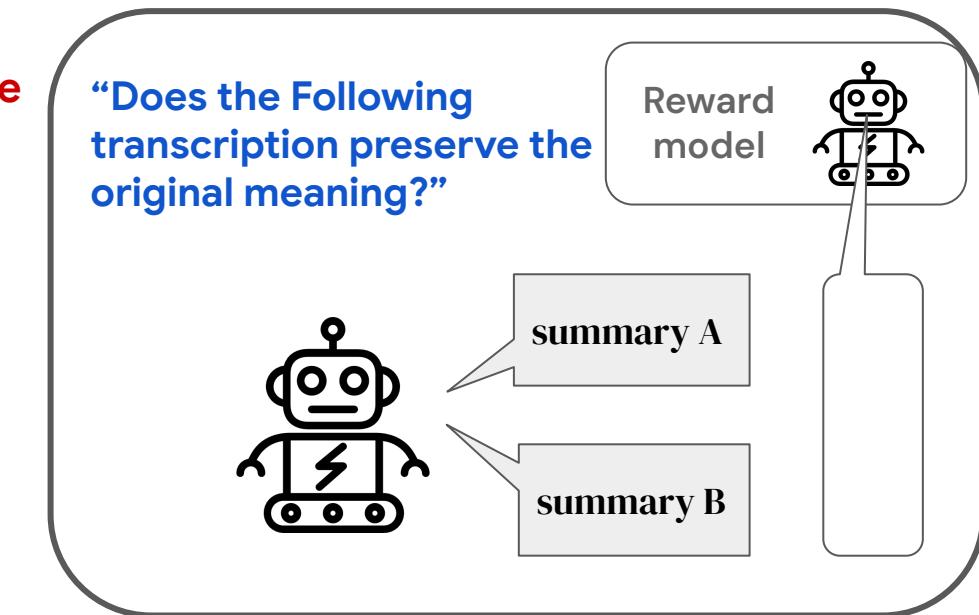
Insight: **High word errors can still preserve meaning !**

Ground Truth: **“Not so good today”**

Output A: **“not so good to the.”**

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Both have same same WER, but B Preserves Meaning.



Reward

Reward Model

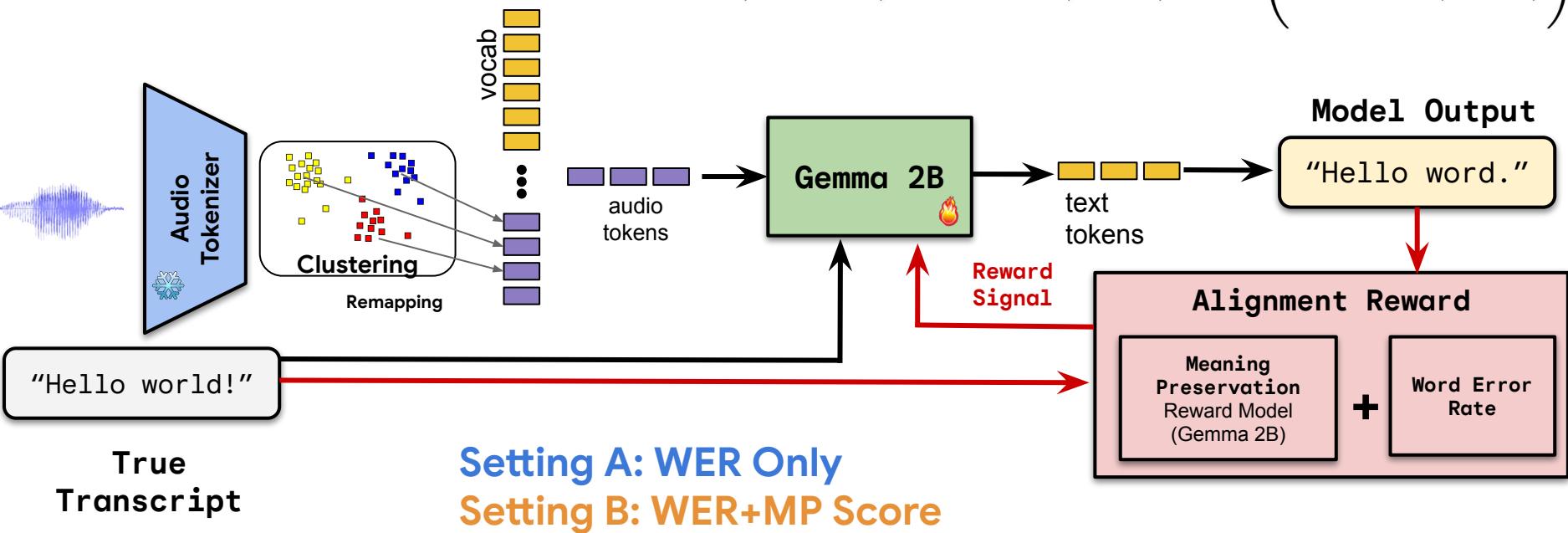
Ground Truth

$$R(\mathbf{x}, \mathbf{y}; \mathbf{y}^*) := \gamma \cdot \text{MP}(\mathbf{y}, \mathbf{y}^*) + \ln \left( 1 - \text{WER}(\mathbf{y}, \mathbf{y}^*) \right)$$

# We use meaning preservation and WER to align the model

## Proximal Policy Optimization

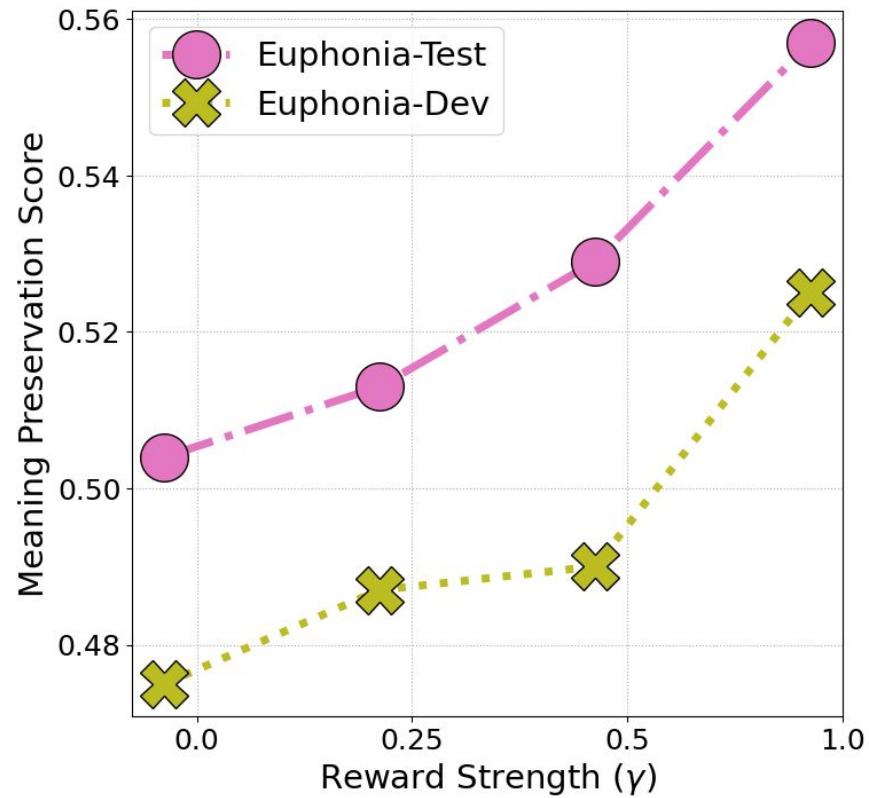
$$R(x, y; y^*) := \gamma \cdot \text{MP}(y, y^*) + \ln \left( 1 - \text{WER}(y, y^*) \right)$$



# Results

## RLHF w/ MP Reward

- Significant improvement in MP.

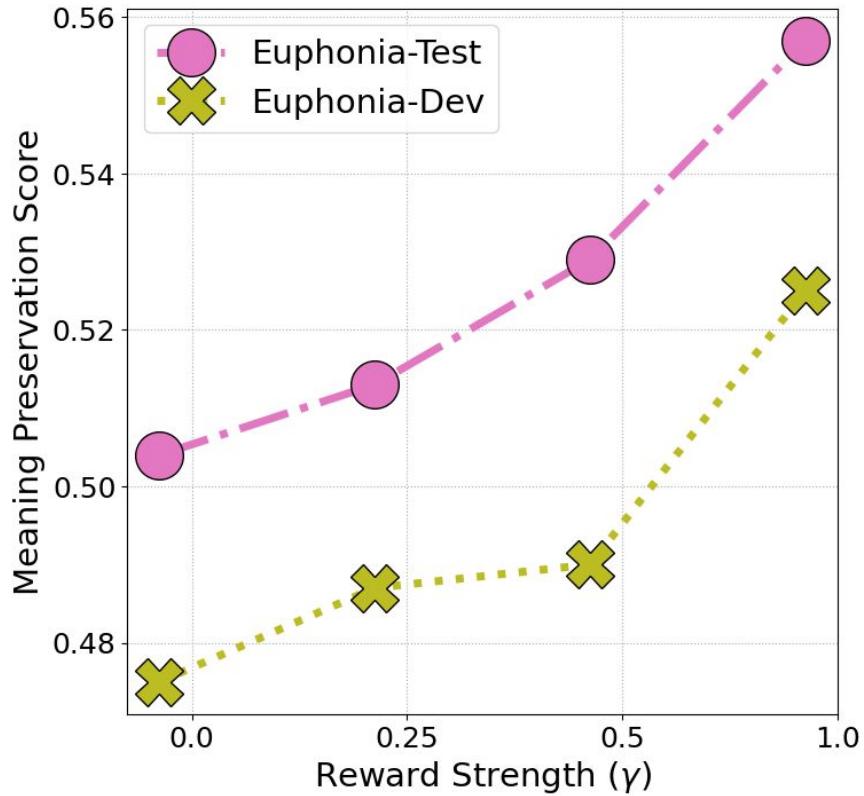


# Results

## RLHF w/ MP Reward

- Significant improvement in MP.
- No significant diff in WER.

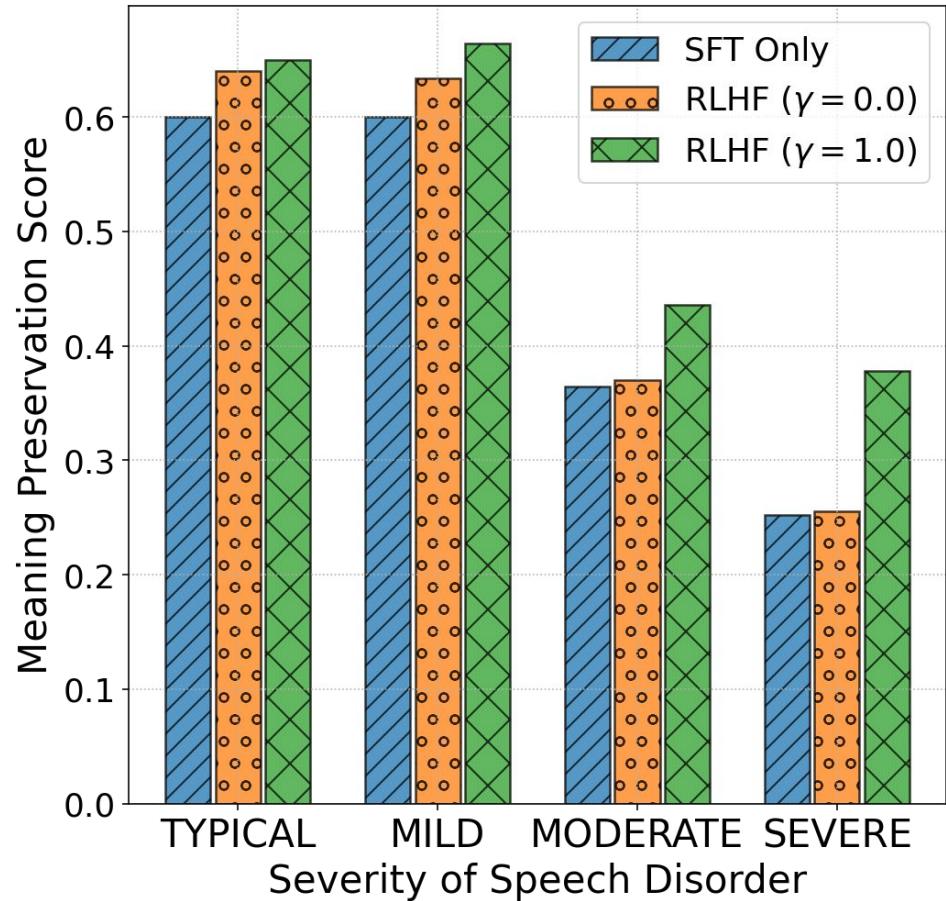
Tuning strategy	Euphonia Test		Euphonia Dev		LibriSpeech Dev	
	WER ↓	MP ↑	WER ↓	MP ↑	WER ↓	MP ↑
Base SFT model	50.4	48.2	47.3	48.1	17.2	85.6
Continued SFT	57.1	42.8	59.2	40.5	22.9	73.2
RLHF WER + MP						
WER ( $\gamma = 0.00$ )	<b>41.0</b>	50.4	<b>40.1</b>	47.5	<b>20.2</b>	75.7
+ MP ( $\gamma = 0.25$ )	41.7	51.3	41.7	48.7	22.4	74.7
+ MP ( $\gamma = 0.50$ )	41.2	52.9	41.1	49.0	23.9	72.2
+ MP ( $\gamma = 1.00$ )	42.6	<b>55.7*</b>	42.9	<b>52.5*</b>	22.0	<b>76.2*</b>



# Results

## RLHF w/ MP Reward

- Significant improvement in MP.
- No significant diff in WER.
- **Gains more pronounced for more severe speech utterances.**

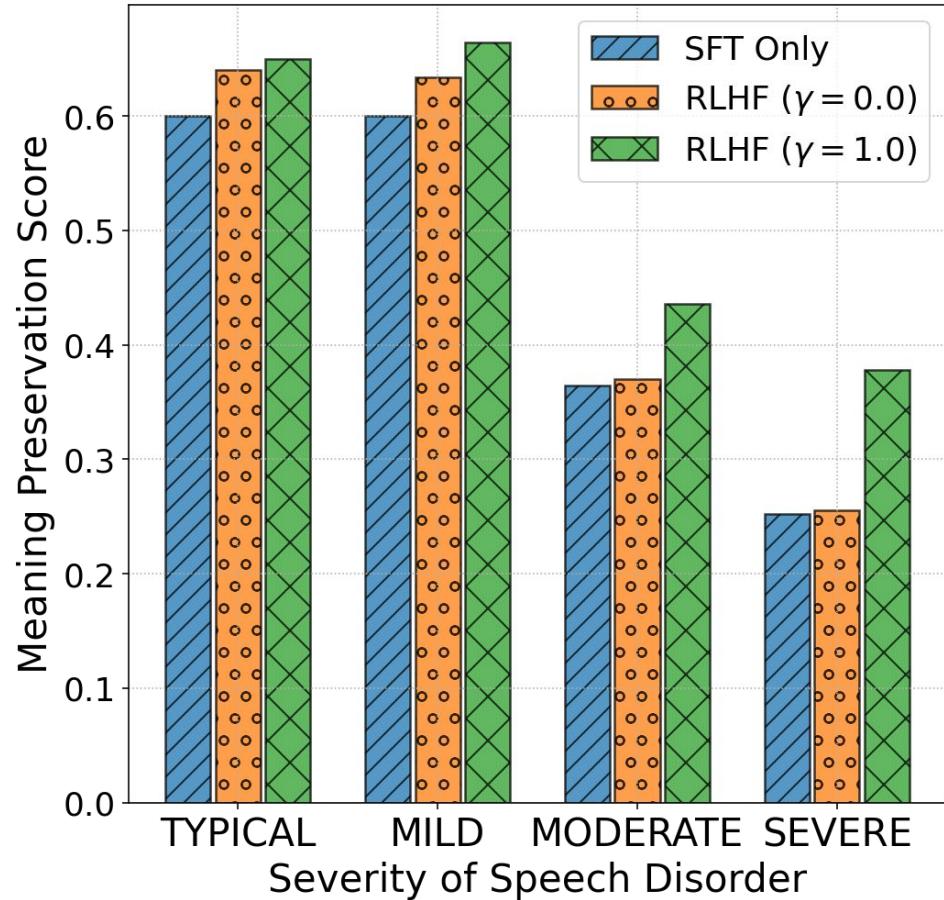


# Results

## Human Eval

- Significant correlation with auto-eval.
- Significant gain in MP.

Statistic (# samples = 220)	$\gamma = 0.0$	$\gamma = 1.0$
Average Primary Assessment (Human MP)	29.10%	40.45%
Accuracy (Human vs. Model MP)	85.90%	81.36%
Spearman ( $\rho$ ) (Human vs. Model MP)	0.684*	0.639*



# Examples

TABLE II: Examples selected based on human evaluation of transcripts on meaning preservation and error type of the RLHF models show that trading-off WER slightly for a significant gain in MP score ( $\gamma = 1.00$ ) leads to better predictions overall.

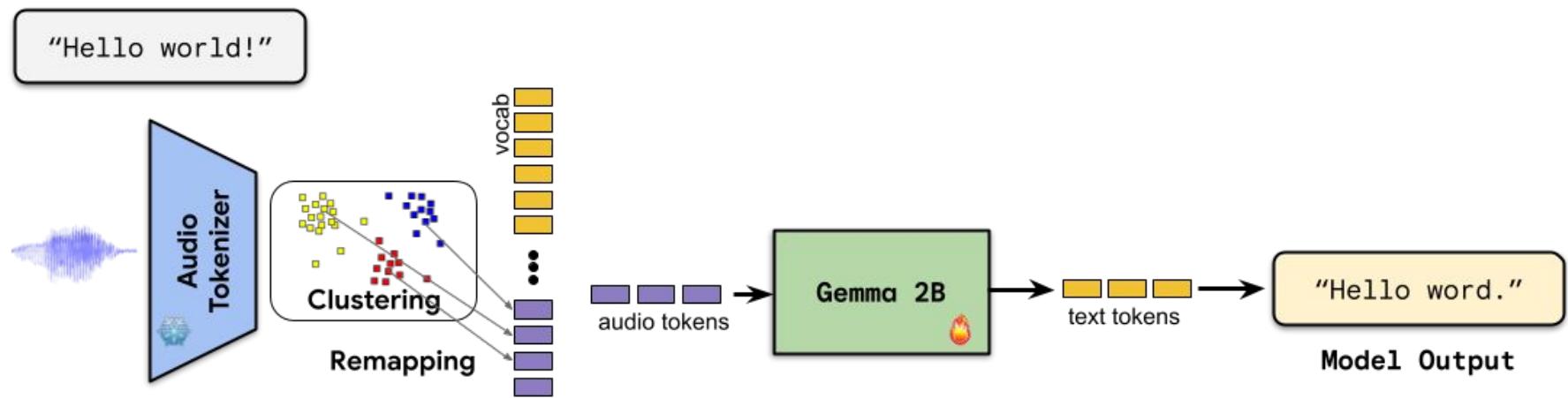
Ground Truth	Severity	RLHF ( $\gamma = 0.0$ )	WER	RLHF ( $\gamma = 1.0$ )	WER
"not so good today"	MILD	"not so good to the."	(0.5)	"not so good to day."	(0.5)
"every one of my family listens to music"	MODERATE	"every once in my frame and listen to music"	(0.62)	"everybody in my family listens to music"	(0.38)
"dancing is so much fun"	MODERATE	"that's so much fun."	(0.40)	"dancing so much fun."	(0.20)
"are you comfortable?"	MODERATE	"are you going to school?"	(1.0)	"are you comfortable with it?"	(0.67)
"happy birthday dear friend."	SEVERE	"absolutely your friend."	(0.75)	"happy birthday to your friend."	(0.50)
"as soon as possible"	SEVERE	"it soon adds pounds him volume"	(1.0)	"a soon as possible."	(0.25)

WER alone as reward.

MP + WER together as  
reward does best.

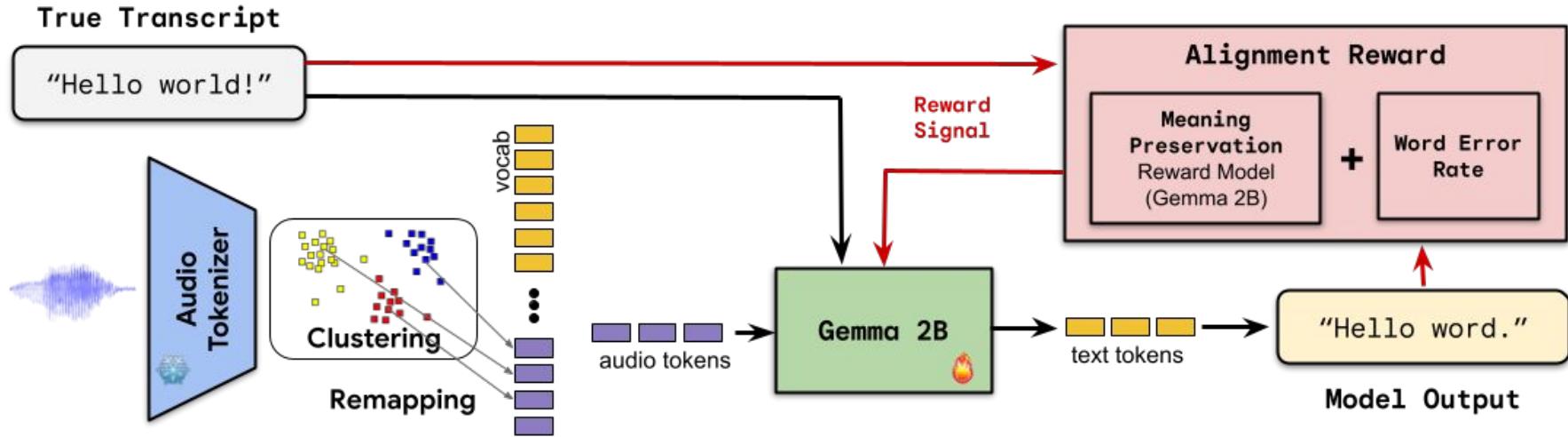
# What we learned

- LLMs can be modified to recognize speech.
- SFT on a mix standard and disordered speech datasets helps.



# What we learned

- LLMs can be modified to recognize speech.
- SFT on a mix standard and disordered speech datasets helps.
- RL can help further generalize the model on disordered speech.
- Combination of Meaning Preservation and WER as reward signal works best.



# Overall key takeaways

- Presented data curation and evals
  - multimodal
  - long-context
  - agentic with tool-use
- In the context of science but very much generalizable
- Lot more potential for multimodal agentic experiences
  - Need smaller performant models
  - Right safeguards
  - Really great experience